YASKAWA Electric Corporation

MP Ethernet/ MECHATROLINK Driver

| 1 | System Configuration | 3 |
|---|------------------------------|----|
| 2 | External Device Selection | 27 |
| 3 | Communication Settings | |
| 4 | Setup Items | |
| 5 | Supported Devices | |
| 6 | Device Code and Address Code | |
| 7 | Error Messages | |

Introduction

This manual describes how to connect the Display and the External Device (target PLC). In this manual, the connection procedure will be described in the sections identified below:

| | | 1 |
|---|--|--|
| 1 | System Configuration This section lists the types of External Devices and SIO that you can connect. | "1 System Configuration" (page 3) |
| | | |
| 2 | External Device Selection Select a model (series) of the External Device and its connection method. | "2 External Device Selection" (page 27) |
| | | |
| 3 | Communication Settings This section shows setting examples for communicating between the Display and the External Device. | েল্লি "3 Communication Settings" (page 28) |
| | | |
| 4 | Setup Items This section describes communication setup items on the Display. Set the Display's communication settings in GP Pro-EX or in offline mode. | ি [©] "4 Setup Items" (page 138) |
| | | |
| | Operation | |

1 System Configuration

The system configuration in the case when the External Device and the Display are connected is shown.

1.1 MP Series

| Series | CPU | Link I/F | SIO Type | Setting Example |
|--------|--------------------------------|--|----------------|--|
| | MP2300 | Ethernet port on 218IF-01 | Ethernet (UDP) | "3.1 Setting Example 1" (page 28) |
| | MP2200 | Ethernet port on 218IF-02 | Ethernet (UDP) | "3.4 Setting Example 4" (page 37) |
| | | Ethernet Connector on CPU unit | Ethernet (UDP) | "3.2 Setting Example 2" (page 31) |
| MP2000 | MP2310 MP2300S | Ethernet port on 218IF-01 | Ethernet (UDP) | "3.3 Setting Example 3" (page 34) |
| | | Ethernet port on 218IF-02 | Ethernet (UDP) | "3.4 Setting Example 4" (page 37) |
| | MP2400 MPU-01 ^{*1} | Ethernet Connector on CPU unit | Ethernet (UDP) | "3.2 Setting Example 2" (page 31) |
| | | Ethernet port on Main CPU ^{*2} or Ethernet port on 218IF-01 | Ethernet (UDP) | "3.12 Setting Example 12" (page 58) |
| | CPU-201 | Ethernet Connector on CPU unit | Ethernet (UDP) | "3.9 Setting Example 9" (page 52) |
| MP3000 | *2 | Ethernet Connector on Main CPU (CPU201) | Ethernet (UDP) | "3.15 Setting Example 15" (page 66) |
| | CPU-201(SUB) ^{*3} | Ethernet Connector on CPU201(SUB) | Ethernet (UDP) | "3.9 Setting Example 9" (page 52) |
| | Σ-7C ^{*4} | Ethernet Port on CPU unit | Ethernet (UDP) | "3.9 Setting Example 9" (page 52) |

*1 The firmware version of the MPU-01 to be supported is Ver. 2.86 or later.

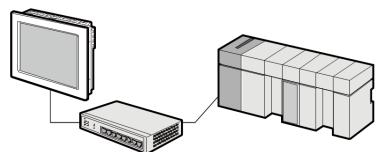
*2 Please refer to the MPU-01 Manual for the supported list of Main CPUs.

*3 The firmware version of the CPU-201 to be supported is Ver. 1.06 or later.

*4 The Display communicates with the Σ -7C controller section.

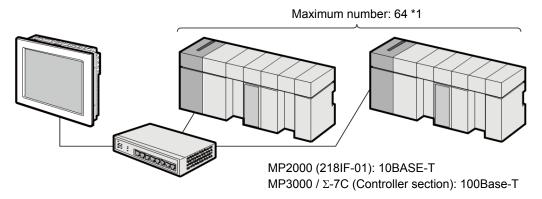
Connection Configuration

- MP Series / Σ -7C (Controller Section)
 - 1:1 Connection



MP2000 (218IF-01): 10BASE-T MP3000 / Σ-7C (Controller section): 100Base-T

1:n Connection

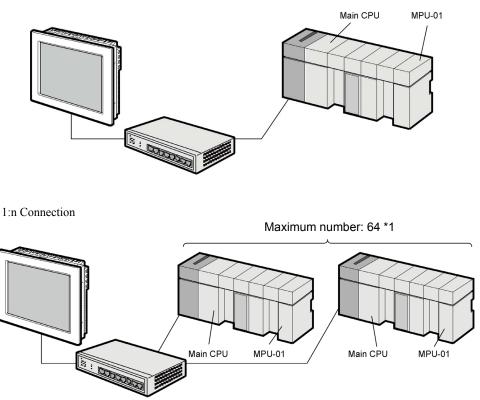


*1 When 33 or more External Devices are connected, it is necessary to check [Increase allowable number of Devices/PLCs].

⁽³⁷⁾ "4.1 Setup Items in GP-Pro EX" (page 138)

• MPU-01

1:1 Connection



*1 When 33 or more External Devices are connected, it is necessary to check [Increase allowable number of Devices/PLCs].

• When connecting to the MPU-01 via the main CPU, do not make communications from two or more devices (e.g. Display and Ladder software) at the same time. If so, the MPU-01 may make no response.

⁽³⁾ "4.1 Setup Items in GP-Pro EX" (page 138)

- Sub CPU
 - 1:1 Connection

| | | | Main CPU | Sub CPU |
|----------------|----------|------------|--------------|------------|
| 1:n Connection | | | | |
| | | Maximum nu | umber: 64 *' | 1 |
| | Main CPU | Sub CPU | Main Cl | PU Sub CPU |
| | | | | |

*1 When 33 or more External Devices are connected, it is necessary to check [Increase allowable number of Devices/PLCs].

^(G) "4.1 Setup Items in GP-Pro EX" (page 138)

| NOTE | • | A Sub CPU can be communicated via a Main CPU or in direct connection. |
|------|---|--|
| | • | When connecting to the Sub CPU via the main CPU, do not make communications from two or |
| | | more devices (e.g. Display and Ladder software) at the same time. If so, the Sub CPU may make no |
| | | response. |
| | | |

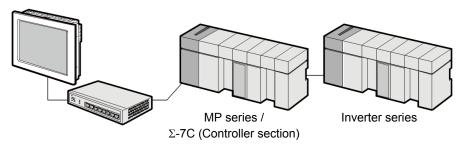
1.2 Inverter Series

| Series | CPU ^{*1} | Link I/F | Communication | Setting Example |
|--------|-------------------|--|---------------------------------------|--|
| V1000 | CIMR-VA A | V1000 Option MECHATROLINK-II (SI-T3/V) | Ethernet (UDP) and MECHATROLINK-II | "3.10 Setting Example 10" (page 54) |
| A1000 | CIMR-ADD ADDDD | A1000 MECHATROLINK-II (SI-T3) | Ethernet (UDP) and MECHATROLINK-II | "3.11 Setting Example 11" (page 56) |

*1 The \Box symbol in the inverter model name represents the maximum applicable motor capacity and other specifications.

Connection Configuration

• 1:1 Connection



Between Display and MP series / Σ -7C (Controller section): Ethernet connection Between MP series / Σ -7C (Controller section) and Inverter series: MECHATROLINK connection

• 1:n Connection

Maximum number: 64 *1

Between Display and MP series / Σ -7C (Controller section): Ethernet connection Between MP series / Σ -7C (Controller section) and Inverter series: MECHATROLINK connection Between Inverter series and Inverter series: MECHATROLINK connection

*1 When 33 or more External Devices are connected, it is necessary to check [Increase allowable number of Devices/PLCs].

⁽³⁾"4.1 Setup Items in GP-Pro EX" (page 138)

7

1.3 Servo

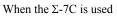
| Series | CPU | Link I/F | SIO Type | Setting Example |
|---|--------------------------------|--|--|--|
| Σ-V Series Rotary Motors (M-II) | SGDV- 000111 0000000 | MECHATROLINK Communications Connectors (CN6A/CN6B) | Ethernet (UDP) and MECHATROLINK-II | "3.5 Setting Example 5" (page 40) |
| Σ-V Series Linear Motors (M-II) | SGDV- 00015 000000 | MECHATROLINK Communications Connectors (CN6A/CN6B) | Ethernet (UDP) and MECHATROLINK-II | "3.6 Setting Example 6" (page 43) |
| | | MECHATROLINK Communications Connectors (CN6A/CN6B) | Ethernet (UDP) and MECHATROLINK-III | "3.7 Setting Example 7" (page 46) |
| Σ-V Series Rotary Motors (M-III) | SGDV- | MECHATROLINK Communications Connectors on MPU-01 | Ethernet (UDP) and MECHATROLINK-III | "3.13 Setting Example 13" (page 60) |
| | | MECHATROLINK Communications Connectors on Sub CPU | Ethernet (UDP) and MECHATROLINK-III | "3.16 Setting Example 16" (page 68) |
| | | MECHATROLINK Communications Connectors (CN6A/CN6B) | Ethernet (UDP) and MECHATROLINK-III | "3.8 Setting Example 8" (page 49) |
| Σ-V Series Linear Motors (M-III) | SGDV- 00025 000000 | MECHATROLINK Communications Connectors on MPU-01 | Ethernet (UDP) and MECHATROLINK-III | "3.14 Setting Example 14" (page 63) |
| | | MECHATROLINK Communications Connectors on Sub CPU | Ethernet (UDP) and MECHATROLINK-III | "3.17 Setting Example 17" (page 71) |
| Σ-7 Series Single-axis SERVOPACKs (M-II) | SGD7S- | MECHATROLINK Communications Connectors (CN6A/CN6B) | Ethernet (UDP) and MECHATROLINK-II | "3.18 Setting Example 18" (page 74) |
| Σ-7 Series | | MECHATROLINK Communications Connectors (CN6A/CN6B) | Ethernet (UDP) and MECHATROLINK-III | "3.19 Setting Example 19" (page 77) |
| Single-axis SERVOPACKs (M-III) | SGD7S- | MECHATROLINK Communications Connectors on MPU-01 | Ethernet (UDP) and MECHATROLINK-III | "3.20 Setting Example 20" (page 80) |
| | | MECHATROLINK Communications Connectors on Sub CPU | Ethernet (UDP) and MECHATROLINK-III | "3.21 Setting Example 21" (page 83) |
| N 7 Corice | | MECHATROLINK Communications Connectors (CN6A/CN6B) | Ethernet (UDP) and MECHATROLINK-III | "3.22 Setting Example 22" (page 86) |
| Σ-7 Series 2-axis SERVO- PACKs (M-III) | /O- SGD7W- □□□□20 □□□□□0 | MECHATROLINK Communications Connectors on MPU-01 | Ethernet (UDP) and MECHATROLINK-III | "3.23 Setting Example 23" (page 89) |
| . , | | MECHATROLINK Communications Connectors on Sub CPU | Ethernet (UDP) and MECHATROLINK-III | "3.24 Setting Example 24" (page 92) |

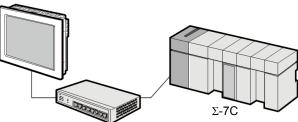
| Series | CPU | Link I/F | SIO Type | Setting Example |
|--|--|---------------------------|--|---|
| Σ-7 Series 2-axis SERVO- PACKs with built- in controller (M-III) | SGD7C- □□□AMAA □□□ ^{*1} | Ethernet Connector (CN12) | Ethernet (UDP) and MECHATROLINK-III | "3.40 Setting Example 40" (page 136) |

*1 The Display communicates with the Σ -7C servo section.

Connection Configuration

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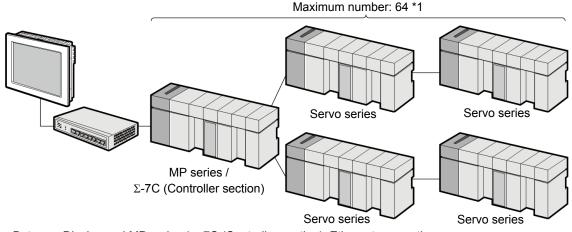




Between Display and Σ -7C: Ethernet connection

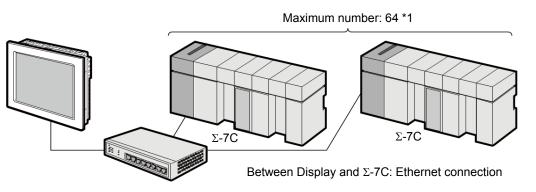
• 1:n Connection

When the MP series / Σ -7C (Controller section) is relayed



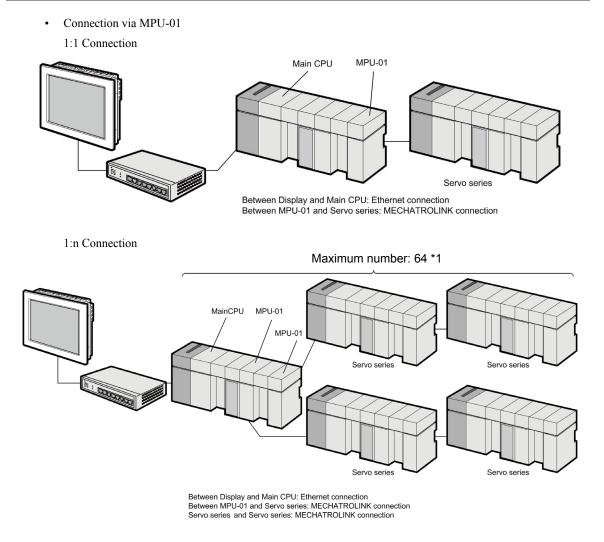
Between Display and MP series / Σ -7C (Controller section): Ethernet connection Between MP series / Σ -7C (Controller section) and Servo series: MECHATROLINK connection Between Servo series and Servo series: MECHATROLINK connection

When the Σ -7C is used



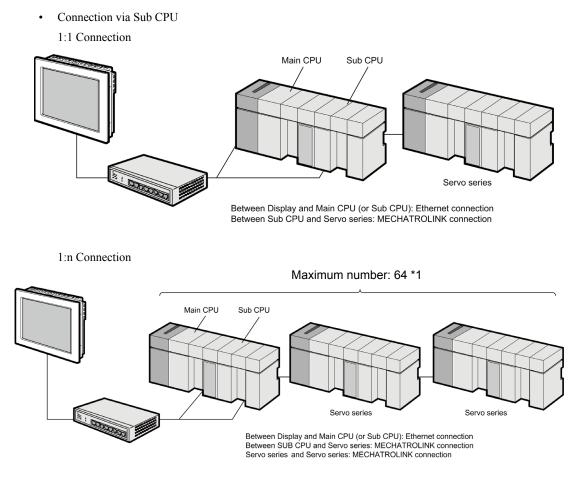
*1 When 33 or more External Devices are connected, it is necessary to check [Increase allowable number of Devices/PLCs].

⁽³⁷⁾ "4.1 Setup Items in GP-Pro EX" (page 138)



*1 When 33 or more External Devices are connected, it is necessary to check [Increase allowable number of Devices/PLCs].

⁽³⁾ "4.1 Setup Items in GP-Pro EX" (page 138)



- *1 When 33 or more External Devices are connected, it is necessary to check [Increase allowable number of Devices/PLCs].
 - "4.1 Setup Items in GP-Pro EX" (page 138)

<complex-block>

Between Display and Main CPU: Ethernet connection Between MPU-01 and Servo series: MECHATROLINK connection Servo series and Servo series: MECHATROLINK connection

*1 When 33 or more External Devices are connected, it is necessary to check [Increase allowable number of Devices/PLCs].

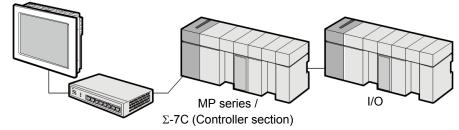
⁽³⁷⁾ "4.1 Setup Items in GP-Pro EX" (page 138)

1.4 I/O(M-System)

| Series | CPU | Link I/F | SIO Type | Setting Example |
|-------------------------------------|-----------------------|--|-------------------------------------|---|
| | | MECHATROLINK Communications Connectors (CN6A/CN6B) | Ethernet (UDP) and MECHATROLINK-III | "3.25 Setting Example 25" (page 95) |
| | R7G4HML3-6- LC2 | MECHATROLINK Communications Connectors on MPU-01 | Ethernet (UDP) and MECHATROLINK-III | "3.26 Setting Example 26" (page 97) |
| | | MECHATROLINK Communications Connectors on Sub CPU | Ethernet (UDP) and MECHATROLINK-III | "3.27 Setting Example 27" (page 100) |
| | R7G4HML3-6- STYVS1 | MECHATROLINK Communications Connectors (CN6A/CN6B) | Ethernet (UDP) and MECHATROLINK-III | "3.34 Setting Example 34" (page 120) |
| M-System Co., Ltd. Remote I/O | | MECHATROLINK Communications Connectors on MPU-01 | Ethernet (UDP) and MECHATROLINK-III | "3.35 Setting Example 35" (page 122) |
| | | MECHATROLINK Communications Connectors on Sub CPU | Ethernet (UDP) and MECHATROLINK-III | "3.36 Setting Example 36" (page 125) |
| | R7G4HML3-6- LC2A | MECHATROLINK Communications Connectors (CN6A/CN6B) | Ethernet (UDP) and MECHATROLINK-III | "3.37 Setting Example 37" (page 128) |
| | | MECHATROLINK Communications Connectors on MPU-01 | Ethernet (UDP) and MECHATROLINK-III | "3.38 Setting Example 38" (page 130) |
| | | MECHATROLINK Communications Connectors on Sub CPU | Ethernet (UDP) and MECHATROLINK-III | "3.39 Setting Example 39" (page 133) |

Connection Configuration

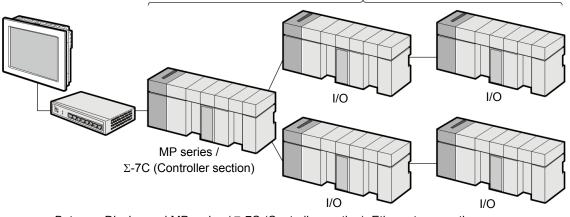
1:1 Connection



Between Display and MP series / Σ -7C (Controller section): Ethernet connection Between MP series / Σ -7C (Controller section) and I/O: MECHATROLINK connection

• 1:n Connection

Maximum number: 64 *1



Between Display and MP series / Σ -7C (Controller section): Ethernet connection Between MP series / Σ -7C (Controller section) and I/O: MECHATROLINK connection Between I/O and I/O: MECHATROLINK connection

*1 When 33 or more External Devices are connected, it is necessary to check [Increase allowable number of Devices/PLCs].

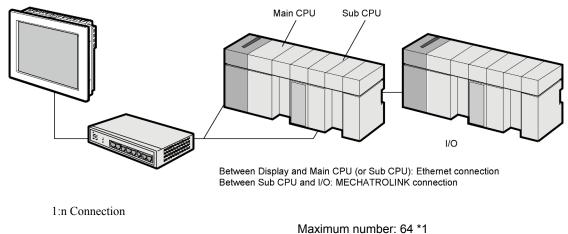
"4.1 Setup Items in GP-Pro EX" (page 138)

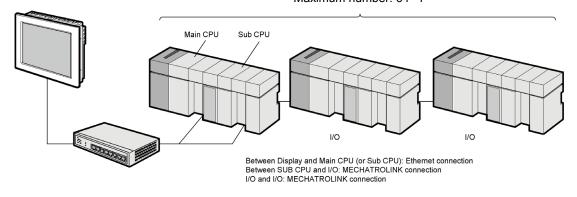
- Connection via MPU-01 1:1 Connection MPU-01 Main CPU I/O Between Display and Main CPU: Ethernet connection Between MPU-01 and I/O: MECHATROLINK connection 1:n Connection Maximum number: 64 *1 MainCPU MPU-01 MPU-01 I/O I/O STOCK STOCK I/O I/O Between Display and Main CPU: Ethernet connection Between MPU-01 and I/O: MECHATROLINK connection I/O and I/O: MECHATROLINK connection
 - *1 When 33 or more External Devices are connected, it is necessary to check [Increase allowable number of Devices/PLCs].

^(GP) "4.1 Setup Items in GP-Pro EX" (page 138)

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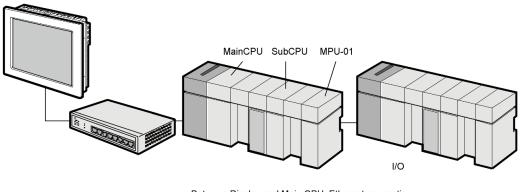
- Connection via Sub CPU
 - 1:1 Connection



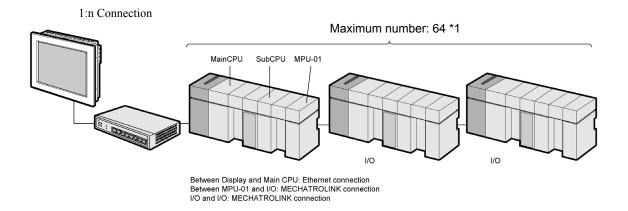


- *1 When 33 or more External Devices are connected, it is necessary to check [Increase allowable number of Devices/PLCs].
 - ⁽³⁷⁾ "4.1 Setup Items in GP-Pro EX" (page 138)

- Connection via Sub CPU and MPU-01
 - 1:1 Connection



Between Display and Main CPU: Ethernet connection Between MPU-01 and I/O: MECHATROLINK connection



*1 When 33 or more External Devices are connected, it is necessary to check [Increase allowable number of Devices/PLCs].

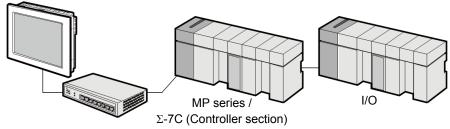
⁽³⁾ "4.1 Setup Items in GP-Pro EX" (page 138)

1.5 I/O(Azbil)

| Series | CPU | Link I/F | SIO Type | Setting Example |
|------------------------------------|---|--|-------------------------------------|---|
| | ion K1G-C04M Communi on MECHAT ies MECHAT Ommuni on MPU-C | MECHATROLINK Communications Connectors (CN6A/CN6B) | Ethernet (UDP) and MECHATROLINK-III | "3.28 Setting Example 28" (page 103) |
| Azbil Corporation K1G Series | | MECHATROLINK Communications Connectors on MPU-01 | Ethernet (UDP) and MECHATROLINK-III | "3.29 Setting Example 29" (page 106) |
| | | MECHATROLINK Communications Connectors on Sub CPU | Ethernet (UDP) and MECHATROLINK-III | "3.30 Setting Example 30" (page 109) |

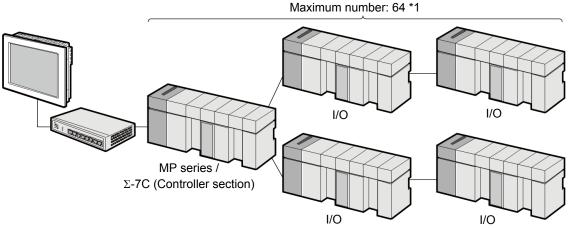
Connection Configuration





Between Display and MP series / Σ -7C (Controller section): Ethernet connection Between MP series / Σ -7C (Controller section) and I/O: MECHATROLINK connection

• 1:n Connection



Between Display and MP series / Σ -7C (Controller section): Ethernet connection Between MP series / Σ -7C (Controller section) and I/O: MECHATROLINK connection Between I/O and I/O: MECHATROLINK connection

*1 When 33 or more External Devices are connected, it is necessary to check [Increase allowable number of Devices/PLCs].

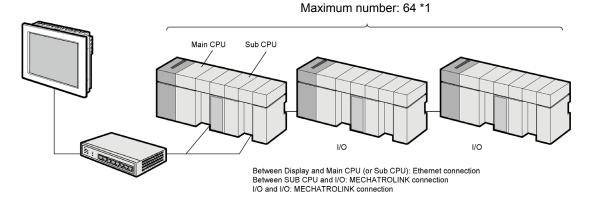
⁽³⁾"4.1 Setup Items in GP-Pro EX" (page 138)

- Connection via MPU-01 1:1 Connection MPU-01 Main CPU I/O Between Display and Main CPU: Ethernet connection Between MPU-01 and I/O: MECHATROLINK connection 1:n Connection Maximum number: 64 *1 MainCPU MPU-01 MPU-01 I/O I/O STOCK STOCK I/O I/O Between Display and Main CPU: Ethernet connection Between MPU-01 and I/O: MECHATROLINK connection I/O and I/O: MECHATROLINK connection
 - *1 When 33 or more External Devices are connected, it is necessary to check [Increase allowable number of Devices/PLCs].

^(GP) "4.1 Setup Items in GP-Pro EX" (page 138)

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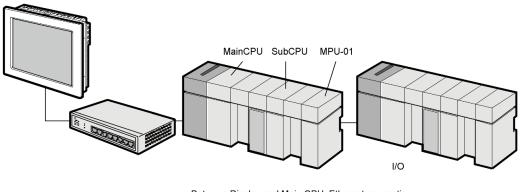
Connection via Sub CPU
 1:1 Connection
 Main CPU Sub CPU
 Generation
 Main CPU Sub CPU
 Generation
 Etween Display and Main CPU (or Sub CPU): Ethernet connection
 Etween Sub CPU and I/O: MECHATROLINK connection



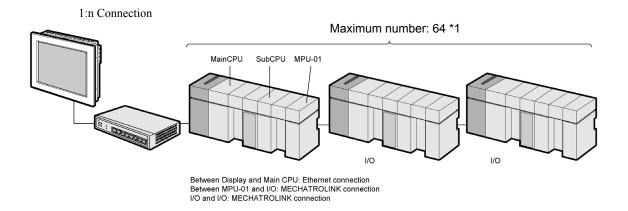
*1 When 33 or more External Devices are connected, it is necessary to check [Increase allowable number of Devices/PLCs].

⁽³⁷⁾ "4.1 Setup Items in GP-Pro EX" (page 138)

- Connection via Sub CPU and MPU-01
 - 1:1 Connection



Between Display and Main CPU: Ethernet connection Between MPU-01 and I/O: MECHATROLINK connection



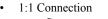
*1 When 33 or more External Devices are connected, it is necessary to check [Increase allowable number of Devices/PLCs].

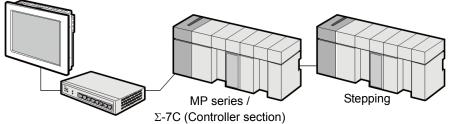
⁽³⁾ "4.1 Setup Items in GP-Pro EX" (page 138)

| Series | CPU | Link I/F | SIO Type | Setting Example |
|---|------------------------|--|--|---|
| | | MECHATROLINK Communications Connectors (CN6A/CN6B) | Ethernet (UDP) and MECHATROLINK-III | "3.31 Setting Example 31" (page 112) |
| ORIENTAL MOTOR Co., Ltd. AZ Series | AZD3A-KM3 AZD4A-KM3 | MECHATROLINK Communications Connectors on MPU-01 | Ethernet (UDP) and MECHATROLINK-III | "3.32 Setting Example 32" (page 114) |
| | | MECHATROLINK Communications Connectors on Sub CPU | Ethernet (UDP) and MECHATROLINK-III | "3.33 Setting Example 33" (page 117) |

1.6 Stepping(Orientalmotor)

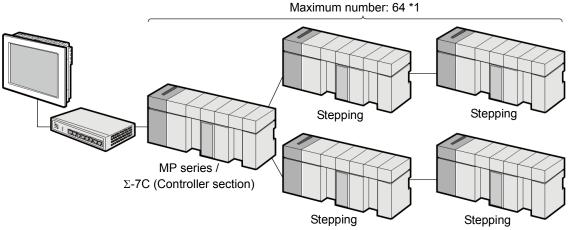
Connection Configuration





Between Display and MP series / Σ -7C (Controller section): Ethernet connection Between MP series / Σ -7C (Controller section) and Stepping: MECHATROLINK connection

• 1:n Connection

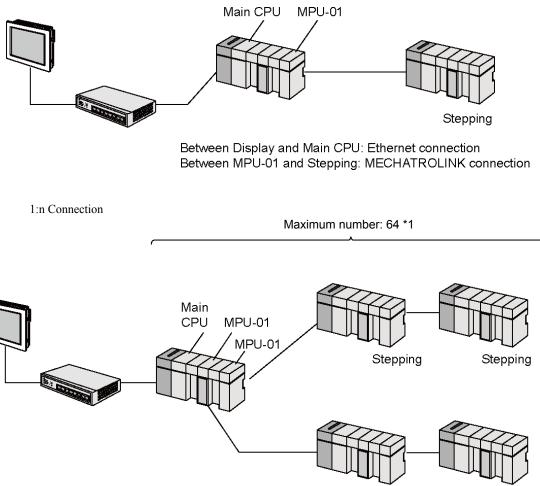


Between Display and MP series / Σ -7C (Controller section): Ethernet connection Between MP series / Σ -7C (Controller section) and Stepping: MECHATROLINK connection Between Stepping and Stepping: MECHATROLINK connection

*1 When 33 or more External Devices are connected, it is necessary to check [Increase allowable number of Devices/PLCs].

"4.1 Setup Items in GP-Pro EX" (page 138)

- Connection via MPU-01
 - 1:1 Connection



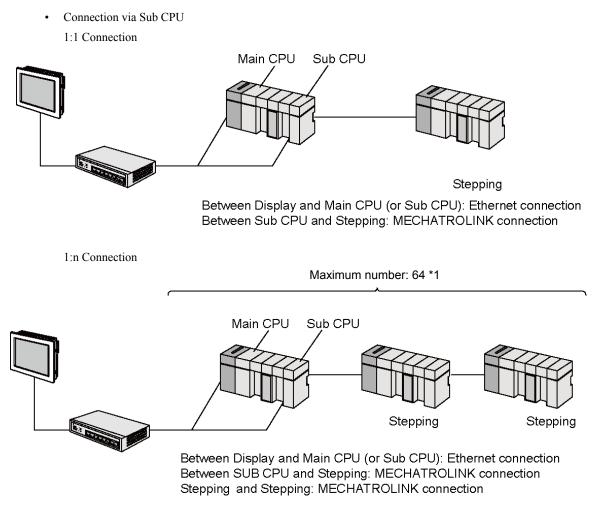
Stepping

Stepping

Between Display and Main CPU: Ethernet connection Between MPU-01 and Stepping: MECHATROLINK connection Stepping and Stepping: MECHATROLINK connection

*1 When 33 or more External Devices are connected, it is necessary to check [Increase allowable number of Devices/PLCs].

"4.1 Setup Items in GP-Pro EX" (page 138)



- *1 When 33 or more External Devices are connected, it is necessary to check [Increase allowable number of Devices/PLCs].
 - "4.1 Setup Items in GP-Pro EX" (page 138)

Connection via Sub CPU and MPU-01 1:1 Connection Main Sub CPU MPU-01 CPU Stepping Between Display and Main CPU: Ethernet connection Between MPU-01 and Stepping: MECHATROLINK connection 1:n Connection Maximum number: 64 *1 Main CPU Sub CPU MPU-01 Stepping Stepping Between Display and Main CPU: Ethernet connection Between MPU-01 and Stepping: MECHATROLINK connection

Stepping and Stepping: MECHATROLINK connection

*1 When 33 or more External Devices are connected, it is necessary to check [Increase allowable number of Devices/PLCs].

⁽²⁷⁾ "4.1 Setup Items in GP-Pro EX" (page 138)

2 External Device Selection

Select the External Device to be connected to the Display.

| ₩elcome to GP-Pro EX | | × |
|----------------------|--------------|--|
| GP-Pro | Device/PLC - | vices/PLCs 1 |
| | | Device/PLC 1 |
| | Manufacturer | YASKAWA Electric Corporation |
| | Series | MP Ethernet/MECHATROLINK |
| | Port | Ethernet (UDP) |
| | | Refer to the manual of this Device/PLC |
| | | Recent Device/PLC |
| | | <u> </u> |
| | Use Syster | n Area <u>Device Information</u> |
| | Back (I | Communication Settings New Logic New Screen Cancel |

| Setup Items | Setup Description |
|----------------------------|--|
| Number of Devices/ PLCs | Use an integer from 1 to 4 to enter the number of Devices/PLCs to connect to the display. |
| Manufacturer | Select the manufacturer of the External Device to be connected. Select "YASKAWA Electric Corporation". |
| Series | Select a model (series) of the External Device to be connected and connection method. Select "MP Ethernet/MECHATROLINK". Check the External Device which can be connected in "MP Ethernet/MECHATROLINK" in system configuration. |
| Port | Select the Display port to be connected to the External Device. |
| Use System Area | Check this option to synchronize the system data area of the Display and the device (memory) of the External Device. When synchronized, you can use the External Device's ladder program to switch the display or display the window on the Display. Cf. GP-Pro EX Reference Manual "LS Area (Direct Access Method Area)" This feature can also be set in GP-Pro EX or in the Display's offline mode. Cf. GP-Pro EX Reference Manual "System Settings [Display Unit] - [System Area] Settings Guide" Cf. Maintenance/Troubleshooting Guide "Main Unit - System Area Settings" |

3 Communication Settings

Examples of communication settings of the Display and the External Device, recommended by Pro-face, are shown.

3.1 Setting Example 1

Settings of GP-Pro EX

Communication Settings

To display the setup screen, from the [Project] menu, point to [System Settings] and select [Device/PLC].

| Device/PLC 1 | | | |
|-------------------------------------|--------------------------|--|------------------------|
| Summary | | | Change Device/PLC |
| Manufacturer YASK | AWA Electric Corporation | Series MP Ethemet/MECHATROL | INK Port Ethemet (UDP) |
| Text Data Mode | 1 Change | | |
| Communication Settings | 3 | | |
| Port No. | 1024 🚊 🗹 Auto | | |
| Timeout | 3 🕂 (sec) | | |
| Retry | 2 + | | |
| Wait To Send | 0 🕂 (ms) | Default | |
| Device-Specific Setting | s | | |
| Allowable Number of Devices/PLCs | Add Device 32 | Increase Allowable Number of Devices/PLCs | Add Indirect |
| No. Device Name | Settings | | Device |
| 👗 1 🛛 PLC1 | Series=MP2000 | Series, Access to MPU-01=OFF, IP Add | F . |

Device Setting

To display the [Individual Device Settings] dialog box, from [Device-Specific Settings] in the [Device/PLC] window, select the External Device and click [Settings] III. To connect multiple External Devices, from [Device-Specific Settings] in the [Device/PLC] window, click [Add Device] to add another External Device.

| <i>拳</i> Individual De | evice Settings | 1 |
|--|---|---|
| PLC1 | | |
| Product | MP2000 Series | |
| | Access to MPU-01 | |
| If you change the p address settings. | product or series, please reconfirm all | |
| IP Address | 192. 168. 0. 1 | |
| | | |
| | | |
| | | |
| | | |
| | | |
| | | |
| | Default | |
| | OK (0) Cancel | |

Notes

- Check with a network administrator about IP address. Do not set the duplicate IP address.
- Set IP address on the External Device address in the [Individual Device Settings] dialog box.
- You need to set IP address on the Display in the offline mode of the Display.

Settings of External Device

Use the ladder software (MPE720) to set up communication settings for the communication module 218IF-01. For details on communication settings, please refer to the manual of the External Device. The setup procedure differs depending on the version of your ladder software.

- Ladder Software Setting (for MPE720 Ver.5)
- 1 Start the ladder software, and in the root folder make the order and PLC folders.
- **2** Right-click the generated External Device, and from the shortcut menu select Logon.

• In the shortcut menu, please confirm there is no check mark beside the [Online] command before logging on.

- For methods on logging on, refer to the User's Manual of the External Device.
- **3** From the PLC folder, double-click the [Definition folder]'s [Module Configuration] to display the [Engineering Manager].
- **4** In the [Engineering Manager]'s [Controller], use the pull-down menu to select the rack classification and communication module.

Set the number associated with the slot number used by the communication module.

When you select the communication module, its setting information is displayed in the [Engineering Manager]'s [Module details].

5 In the [Module details], double-click the No. field's numeric portion.

Double-click the number associated with the slot number connected to the Ethernet unit.

| Setup Items | | Setup Description |
|------------------------|-------------------------|-------------------|
| Transmission parameter | This Station IP address | PLC IP address |

IMPORTANT • Please make the connection parameter blank. Communication is not possible when a connection parameter is set.

6 Double-click "No.1" and set up serial communication.

Serial communication is used to transfer communication settings to the PLC.

- 7 Save the settings and exit [Engineering Manager].
- 8 After turning ON the communication module's "INIT" DIP Switch, turn ON the power supply.
- **9** Transfer the settings to the communication module.
- 10 While online, logon to the External Device. Write the transferred data to FLASH memory.
- 11 Turn OFF the External Device's power supply, turn OFF the "INIT" DIP Switch, and turn the External Device's power back ON.

- Ladder Software Setting (for MPE720 Ver.6)
- 1 Start the ladder software.
- 2 Make a project file.
- **3** From the tree view, double-click [Module Configuration].

[Engineering Manager] starts.

4 In the [Engineering Manager]'s [Controller], use the pull-down menu to select the rack classification and communication module.

Set the number associated with the slot number used by the communication module.

When you select the communication module, its setting information is displayed in the [Engineering Manager]'s [Module details].

5 In the [Module details], double-click the No. field's numeric portion.

Double-click the number associated with the slot number connected to the Ethernet unit.

| Setup Items | | Setup Description |
|------------------------|-------------------------|-------------------|
| Transmission parameter | This Station IP address | PLC IP address |

IMPORTANT

Please make the connection parameter blank.
 Communication is not possible when a connection parameter is set.

6 Double-click "No.1" and set up serial communication.

Serial communication is used to transfer communication settings to the PLC.

- 7 Save the settings and exit [Engineering Manager].
- 8 After turning ON the communication module's "INIT" DIP Switch, turn ON the power supply.
- **9** Write the settings to the communication module.

IMPORTANT
 To write the settings, select the [Save to flash after transferring to the controller] check box.
 If the data is transferred without selecting the check box, the transferred data is deleted when restarting the External Device.

10 Turn OFF the External Device's power supply, turn OFF the "INIT" DIP Switch, and turn the External Device's power back ON.

Notes

• Check with a network administrator about IP address. Do not set the duplicate IP address.

3.2 Setting Example 2

Settings of GP-Pro EX

Communication Settings

To display the setup screen, from the [Project] menu, point to [System Settings] and select [Device/PLC].

| Device/PLC 1 | | |
|-------------------------------------|--|--------------------|
| Summary | | Change Device/PLC |
| Manufacturer YASK | AWA Electric Corporation Series MP Ethemet/MECHATROLINK | Port Ethemet (UDP) |
| Text Data Mode | 1 Change | |
| Communication Settings | 5 | |
| Port No. | 1024 🗾 🔽 Auto | |
| Timeout | 3 (sec) | |
| Retry | 2 🕂 | |
| Wait To Send | 0 (ms) Default | |
| Device-Specific Setting | S | |
| Allowable Number of Devices/PLCs | 32 Add Device Increase Allowable Number of Devices/PLCs | Add Indirect |
| No. Device Name | Settings | Device |
| 👗 1 PLC1 | Series=MP2000 Series,Access to MPU-01=OFF,IP Add | F |

Device Setting

To display the [Individual Device Settings] dialog box, from [Device-Specific Settings] in the [Device/PLC] window, select the External Device and click [Settings] III. To connect multiple External Devices, from [Device-Specific Settings] in the [Device/PLC] window, click [Add Device] to add another External Device.

| 🎒 Individual D | evice Settings | × |
|--|---|---|
| PLC1 | | |
| Product | MP2000 Series 💌 | |
| | Access to MPU-01 | |
| If you change the address settings. | product or series, please reconfirm all | |
| IP Address | 192. 168. 0. 1 | |
| | | |
| | | |
| | | |
| | | |
| | | |
| | Default | _ |
| | | |
| | OK (O) Cancel | |

Notes

- Check with a network administrator about IP address. Do not set the duplicate IP address.
- Set IP address on the External Device address in the [Individual Device Settings] dialog box.
- You need to set IP address on the Display in the offline mode of the Display.

Settings of External Device

Use the ladder software (MPE720) to set up communication settings for the communication module CPU unit. For details on communication settings, please refer to the manual of the External Device. The setup procedure differs depending on the version of your ladder software.

- Ladder Software Setting (for MPE720 Ver.5)
- 1 Start the ladder software, and in the root folder make the order and PLC folders.
- **2** Right-click the generated External Device, and from the shortcut menu select Logon.

• In the shortcut menu, please confirm there is no check mark beside the [Online] command before logging on.

- For methods on logging on, refer to the User's Manual of the External Device.
- **3** From the PLC folder, double-click the [Definition folder]'s [Module Configuration] to display the [Engineering Manager].
- **4** In the [Engineering Manager]'s [Controller], use the pull-down menu to select the rack classification and communication module.

Set the number associated with the slot number used by the communication module.

When you select the communication module, its setting information is displayed in the [Engineering Manager]'s [Module details].

5 In the [Module details], double-click the No. field's numeric portion.

Double-click the number associated with the slot number connected to the Ethernet unit.

| Setup Items | | Setup Description |
|------------------------|-------------------------|-------------------|
| Transmission parameter | This Station IP address | PLC IP address |

IMPORTANT • Please make the connection parameter blank. Communication is not possible when a connection parameter is set.

- **6** Save the settings and exit [Engineering Manager].
- 7 After turning ON the communication module's "INIT" DIP Switch, turn ON the power supply.
- **8** Transfer the settings to the communication module.
- **9** While online, logon to the External Device. Write the transferred data to FLASH memory.
- 10 Turn OFF the External Device's power supply, turn OFF the "INIT" DIP Switch, and turn the External Device's power back ON.

- Ladder Software Setting (for MPE720 Ver.6)
- 1 Start the ladder software.
- **2** Make a project file.
- **3** From the tree view, double-click [Module Configuration].

[Engineering Manager] starts.

4 In the [Engineering Manager]'s [Controller], use the pull-down menu to select the rack classification and communication module.

Set the number associated with the slot number used by the communication module.

When you select the communication module, its setting information is displayed in the [Engineering Manager]'s [Module details].

5 In the [Module details], double-click the No. field's numeric portion.

Double-click the number associated with the slot number connected to the Ethernet unit.

| Setup Items | | Setup Description |
|------------------------|-------------------------|-------------------|
| Transmission parameter | This Station IP address | PLC IP address |

IMPORTANT

Please make the connection parameter blank.
 Communication is not possible when a connection parameter is set.

- 6 Save the settings and exit [Engineering Manager].
- 7 After turning ON the communication module's "INIT" DIP Switch, turn ON the power supply.
- **8** Write the settings to the communication module.

IMPORTANT • To write the settings, select the [Save to flash after transferring to the controller] check box.

If the data is transferred without selecting the check box, the transferred data is deleted when restarting the External Device.

9 Turn OFF the External Device's power supply, turn OFF the "INIT" DIP Switch, and turn the External Device's power back ON.

Notes

· Check with a network administrator about IP address. Do not set the duplicate IP address.

3.3 Setting Example 3

Settings of GP-Pro EX

Communication Settings

To display the setup screen, from the [Project] menu, point to [System Settings] and select [Device/PLC].

| Device/PLC 1 | | |
|-------------------------------------|---|--------------------|
| Summary | | Change Device/PLC |
| Manufacturer YA | SKAWA Electric Corporation Series MP Ethemet/MECHATROLINK | Port Ethemet (UDP) |
| Text Data Mode | 1 Change | |
| Communication Settin | ngs | |
| Port No. | 1024 🗾 🔽 Auto | |
| Timeout | 3 (sec) | |
| Retry | 2 | |
| Wait To Send | 0 (ms) Default | |
| Device-Specific Setti | ngs | |
| Allowable Number of Devices/PLCs | Add Device Increase Allowable 32 Number of Devices/PLCs | Add Indirect |
| No. Device Nan | ne Settings | Device |
| 👗 1 PLC1 | Series=MP2000 Series,Access to MPU-01=OFF,IP Add | F . |

Device Setting

To display the [Individual Device Settings] dialog box, from [Device-Specific Settings] in the [Device/PLC] window, select the External Device and click [Settings] III. To connect multiple External Devices, from [Device-Specific Settings] in the [Device/PLC] window, click [Add Device] to add another External Device.

| 🎒 Individual D | evice Settings | × |
|--|---|---|
| PLC1 | | |
| Product | MP2000 Series 💌 | |
| | Access to MPU-01 | |
| If you change the address settings. | product or series, please reconfirm all | |
| IP Address | 192. 168. 0. 1 | |
| | | |
| | | |
| | | |
| | | |
| | | |
| | Default | _ |
| | | |
| | OK (O) Cancel | |

Notes

- Check with a network administrator about IP address. Do not set the duplicate IP address.
- Set IP address on the External Device address in the [Individual Device Settings] dialog box.
- You need to set IP address on the Display in the offline mode of the Display.

Settings of External Device

Use the ladder software (MPE720) to set up communication settings for the communication module 218IF-01. For details on communication settings, please refer to the manual of the External Device. The setup procedure differs depending on the version of your ladder software.

- Ladder Software Setting (for MPE720 Ver.5)
- 1 Start the ladder software, and in the root folder make the order and PLC folders.
- **2** Right-click the generated External Device, and from the shortcut menu select Logon.

• In the shortcut menu, please confirm there is no check mark beside the [Online] command before logging on.

- For methods on logging on, refer to the User's Manual of the External Device.
- **3** From the PLC folder, double-click the [Definition folder]'s [Module Configuration] to display the [Engineering Manager].
- **4** In the [Engineering Manager]'s [Controller], use the pull-down menu to select the rack classification and communication module.

Set the number associated with the slot number used by the communication module.

When you select the communication module, its setting information is displayed in the [Engineering Manager]'s [Module details].

5 In the [Module details], double-click the No. field's numeric portion.

Double-click the number associated with the slot number connected to the Ethernet unit.

| Setup Items | | Setup Description |
|------------------------|-------------------------|-------------------|
| Transmission parameter | This Station IP address | PLC IP address |

IMPORTANT • Please make the connection parameter blank. Communication is not possible when a connection parameter is set.

- **6** Save the settings and exit [Engineering Manager].
- 7 After turning ON the communication module's "INIT" DIP Switch, turn ON the power supply.
- **8** Transfer the settings to the communication module.
- **9** While online, logon to the External Device. Write the transferred data to FLASH memory.
- 10 Turn OFF the External Device's power supply, turn OFF the "INIT" DIP Switch, and turn the External Device's power back ON.

- Ladder Software Setting (for MPE720 Ver.6)
- 1 Start the ladder software.
- **2** Make a project file.
- **3** From the tree view, double-click [Module Configuration].

[Engineering Manager] starts.

4 In the [Engineering Manager]'s [Controller], use the pull-down menu to select the rack classification and communication module.

Set the number associated with the slot number used by the communication module.

When you select the communication module, its setting information is displayed in the [Engineering Manager]'s [Module details].

5 In the [Module details], double-click the No. field's numeric portion.

Double-click the number associated with the slot number connected to the Ethernet unit.

| Setup Items | | Setup Description |
|------------------------|-------------------------|-------------------|
| Transmission parameter | This Station IP address | PLC IP address |

IMPORTANT

Please make the connection parameter blank.
 Communication is not possible when a connection parameter is set.

- 6 Save the settings and exit [Engineering Manager].
- 7 After turning ON the communication module's "INIT" DIP Switch, turn ON the power supply.
- **8** Write the settings to the communication module.

IMPORTANT • To write the settings, select the [Save to flash after transferring to the controller] check box.

If the data is transferred without selecting the check box, the transferred data is deleted when restarting the External Device.

9 Turn OFF the External Device's power supply, turn OFF the "INIT" DIP Switch, and turn the External Device's power back ON.

Notes

· Check with a network administrator about IP address. Do not set the duplicate IP address.

3.4 Setting Example 4

Settings of GP-Pro EX

Communication Settings

To display the setup screen, from the [Project] menu, point to [System Settings] and select [Device/PLC].

| Device/PLC 1 | | |
|-------------------------------------|---|--------------------|
| Summary | | Change Device/PLC |
| Manufacturer YA | SKAWA Electric Corporation Series MP Ethemet/MECHATROLINK | Port Ethemet (UDP) |
| Text Data Mode | 1 Change | |
| Communication Settin | ngs | |
| Port No. | 1024 🗾 🔽 Auto | |
| Timeout | 3 (sec) | |
| Retry | 2 | |
| Wait To Send | 0 (ms) Default | |
| Device-Specific Setti | ngs | |
| Allowable Number of Devices/PLCs | Add Device Increase Allowable 32 Number of Devices/PLCs | Add Indirect |
| No. Device Nan | ne Settings | Device |
| 👗 1 PLC1 | Series=MP2000 Series,Access to MPU-01=OFF,IP Add | F . |

Device Setting

To display the [Individual Device Settings] dialog box, from [Device-Specific Settings] in the [Device/PLC] window, select the External Device and click [Settings] III. To connect multiple External Devices, from [Device-Specific Settings] in the [Device/PLC] window, click [Add Device] to add another External Device.

| 🎒 Individual D | evice Settings | × |
|--|---|---|
| PLC1 | | |
| Product | MP2000 Series 💌 | |
| | Access to MPU-01 | |
| If you change the address settings. | product or series, please reconfirm all | |
| IP Address | 192. 168. 0. 1 | |
| | | |
| | | |
| | | |
| | | |
| | | |
| | Default | _ |
| | | |
| | OK (O) Cancel | |

- Check with a network administrator about IP address. Do not set the duplicate IP address.
- Set IP address on the External Device address in the [Individual Device Settings] dialog box.
- You need to set IP address on the Display in the offline mode of the Display.

Use the ladder software (MPE720) to set up communication settings for the communication module 218IF-01. For details on communication settings, please refer to the manual of the External Device. The setup procedure differs depending on the version of your ladder software.

- Ladder Software Setting (for MPE720 Ver.5)
- 1 Start the ladder software, and in the root folder make the order and PLC folders.
- **2** Right-click the generated External Device, and from the shortcut menu select Logon.

• In the shortcut menu, please confirm there is no check mark beside the [Online] command before logging on.

- For methods on logging on, refer to the User's Manual of the External Device.
- **3** From the PLC folder, double-click the [Definition folder]'s [Module Configuration] to display the [Engineering Manager].
- **4** In the [Engineering Manager]'s [Controller], use the pull-down menu to select the rack classification and communication module.

Set the number associated with the slot number used by the communication module.

When you select the communication module, its setting information is displayed in the [Engineering Manager]'s [Module details].

5 In the [Module details], double-click the No. field's numeric portion.

Double-click the number associated with the slot number connected to the Ethernet unit.

| Setup Items | | Setup Description |
|------------------------|-------------------------|-------------------|
| Transmission parameter | This Station IP address | PLC IP address |

IMPORTANT • Please make the connection parameter blank. Communication is not possible when a connection parameter is set.

- **6** Save the settings and exit [Engineering Manager].
- 7 After turning ON the communication module's "INIT" DIP Switch, turn ON the power supply.
- **8** Transfer the settings to the communication module.
- **9** While online, logon to the External Device. Write the transferred data to FLASH memory.
- 10 Turn OFF the External Device's power supply, turn OFF the "INIT" DIP Switch, and turn the External Device's power back ON.

- Ladder Software Setting (for MPE720 Ver.6)
- 1 Start the ladder software.
- **2** Make a project file.
- **3** From the tree view, double-click [Module Configuration].

[Engineering Manager] starts.

4 In the [Engineering Manager]'s [Controller], use the pull-down menu to select the rack classification and communication module.

Set the number associated with the slot number used by the communication module.

When you select the communication module, its setting information is displayed in the [Engineering Manager]'s [Module details].

5 In the in [Module details], double-click the No. field's numeric portion.

Double-click the number associated with the slot number connected to the Ethernet unit.

| Setup Items | | Setup Description |
|------------------------|-------------------------|-------------------|
| Transmission parameter | This Station IP address | PLC IP address |

IMPORTANT

Please make the connection parameter blank.
 Communication is not possible when a connection parameter is set.

- 6 Save the settings and exit [Engineering Manager].
- 7 After turning ON the communication module's "INIT" DIP Switch, turn ON the power supply.
- **8** Write the settings to the communication module.

IMPORTANT • To write the settings, select the [Save to flash after transferring to the controller] check box.

If the data is transferred without selecting the check box, the transferred data is deleted when restarting the External Device.

9 Turn OFF the External Device's power supply, turn OFF the "INIT" DIP Switch, and turn the External Device's power back ON.

Notes

3.5 Setting Example 5

Settings of GP-Pro EX

Communication Settings

To display the setup screen, from the [Project] menu, point to [System Settings] and select [Device/PLC].

| Device/PLC 1 | |
|--|-------|
| Summary Change Device/PLC | |
| Manufacturer YASKAWA Electric Corporation Series MP Ethemet/MECHATROLINK Port Ethemet (UDP) | |
| Text Data Mode 1 Change | |
| Communication Settings | |
| Port No. 1024 🖃 🗸 Auto | |
| Timeout 3 🙀 (sec) | |
| Retry 2 | |
| Wait To Send 0 📑 (ms) Default | |
| Device-Specific Settings | |
| Allowable Number <u>Add Device</u> Increase Allowable of Devices/PLCs 32 Number of Devices/PLCs | |
| No. Device Name Settings Device | |
| 1 PLC1 Series=Sigma-V Series Rotational Motor(M-II),IP Addres | |
| | |
| MPORTANT • To connect Σ -V Series using a 1:n connection, [Wait To Send] must be | 100ms |

Device Setting

more.

To display the [Individual Device Settings] dialog box, from [Device-Specific Settings] in the [Device/PLC] window, select the External Device and click [Settings] I. To connect multiple External Devices, from [Device-Specific Settings] in the [Device/PLC] window, click [Add Device] to add another External Device.

| 🎒 Individual De | vice Settings X |
|--|---|
| PLC1 | |
| Product | Servo |
| Series | Sigma-V Series Rotational Motor(M-II) 💌 |
| If you change the p address settings. | product or series, please reconfirm all |
| Station Address(S | ervo) 65 🗄 |
| Relay Controle | r Setting |
| IP Address | s 192. 168. 0. 1 |
| De | vice Type Circuit No. |
| 1 MECHATI | ROLINK 🔽 1 🚍 |
| | |
| | |
| | Default |
| | OK (O) Cancel |

- Check with a network administrator about IP address. Do not set the duplicate IP address.
- Set IP address on the External Device address in the [Individual Device Settings] dialog box.
- You need to set IP address on the Display in the offline mode of the Display.

Set communication settings for both MP and Σ -V Series.

MP Series Setting

Use the ladder software (MPE720) to set up communication settings.

For details on communication settings, please refer to the manual of the External Device.

- 1 Start the ladder software.
- **2** Make a project file.
- **3** From the tree view, double-click [Module Configuration].

[Engineering Manager] starts.

- 4 In the [Create new file] dialog box, click [OK].
- **5** In the [Engineering Manager]'s [Controller], use the pull-down menu to select MECHATROLINK connection module.

Select the number associated with the slot number used by the module.

When you select the MECHATROLINK connection module, its setting information is displayed in the

[Engineering Manger]'s [Module details].

6 In the [module Details]'s [Circuit Number] field, enter "01".

Set up the same value as the Display's circuit number.

- 7 In [Details], double-click [MECHATROLINK].
- **8** Click the [Link Assignments] tab, and then set [ST#]'s [01] field as follows.

| Setup Items | Setup Description |
|-------------|--|
| ТҮРЕ | Select the type of Σ -V Series you are using. |

NOTE

[ST#] is defined based on the Σ-V Series station address.
 When the station address is 41H, define "ST#01".

- 9 In the [Engineering Manager]'s [Controller], select CPU.
- **10** In the [Module details], double-click the communication module's No. field.
- **11** Set [Transmission Parameters] as follows.

| Setup Items | Setup Description |
|-------------|-------------------|
| IP Address | 192.168.0.1 |
| Subnet Mask | 255.255.255.0 |

- 12 From the [File] menu select [Save] to save your settings, and exit [Engineering Manager].
- **13** Write the settings to the MP Series.

IMPORTANT • To write the settings, select the [Save to flash after transferring to the controller] check box.

If the data is transferred without selecting the check box, the transferred data is deleted when restarting the External Device.

Σ-V Series Setting

Set up communication settings with the DIP Switch (SW2) and the rotary switch (SW1). For example, when the SW2-3 is OFF and SW1 is 1, the station address is 41H.

For details on communication settings, please refer to the manual for the External Device.

• DIP Switch (SW2) Setting

| DIP Switch | Settings | Setup Description |
|------------|----------|--|
| 1 | ON | Communication speed: 10Mbps (MECHATROLINK-II) |
| 2 | Optional | Data transfer size. ON: 32-byte data transfer OFF: 17-byte data transfer |
| 3 | OFF | Define the station address in combination with the rotary switch (SW1). ON: Tenth's position of station address is 0x5 OFF: Tenth's position of station address is 0x4 |
| 4 | OFF | Always OFF |

• Rotary Switch (SW1) Setting

Set the station address in combination with the DIP Switch (SW2), number 3.

| Rotary Switch | Settings | Setup Description |
|---------------|----------|-----------------------------------|
| SW1 | 1 | Ones place of the station address |

Notes

3.6 Setting Example 6

Settings of GP-Pro EX

Communication Settings

To display the setup screen, from the [Project] menu, point to [System Settings] and select [Device/PLC].

| Device/PLC 1 | |
|--|--------|
| Summary Change Device/PLC | |
| Manufacturer YASKAWA Electric Corporation Series MP Ethemet/MECHATROLINK Port Ethemet (UDP) | |
| Text Data Mode 1 Change | |
| Communication Settings | |
| Port No. 1024 Z Auto | |
| Timeout 3 (sec) | |
| Retry 2 | |
| Wait To Send 0 (ms) Default | |
| Device-Specific Settings | |
| Allowable Number <u>Add Device</u> Increase Allowable of Devices/PLCs 32 Number of Devices/PLCs | |
| No. Device Name Settings Add Indirect | |
| 1 PLC1 Series=Sigma-V Series Linear Motor(M-II).IP Address=1 | |
| | |
| MPORTANT • To connect Σ -V Series using a 1:n connection, [Wait To Send] must be 1 | 00ms (|

Device Setting

more.

To display the [Individual Device Settings] dialog box, from [Device-Specific Settings] in the [Device/PLC] window, select the External Device and click [Settings] I. To connect multiple External Devices, from [Device-Specific Settings] in the [Device/PLC] window, click [Add Device] to add another External Device.

| 🎒 Individual D | evice Settings |
|--|---|
| PLC1 | |
| Product | Servo |
| Series | Sigma-V Series Linear Motor(M-II) |
| If you change the address settings. | product or series, please reconfirm all |
| Station Address(| Servo) 65 芸 |
| Relay Control | er Setting |
| IP Addres | ss 192. 168. 0. 1 |
| D | levice Type Circuit No. |
| 1 MECHAT | ROLINK 🔽 1 🗮 |
| | |
| | |
| | Default |
| | OK (0) Cancel |

- Check with a network administrator about IP address. Do not set the duplicate IP address.
- Set IP address on the External Device address in the [Individual Device Settings] dialog box.
- You need to set IP address on the Display in the offline mode of the Display.

Set communication settings for both MP and Σ -V Series.

MP Series Setting

Use the ladder software (MPE720) to set up communication settings.

For details on communication settings, please refer to the manual of the External Device.

- 1 Start the ladder software.
- 2 Make a project file.

NOTE

3 From the tree view, double-click [Module Configuration].

[Engineering Manager] starts.

- 4 In the [Create new file] dialog box, click [OK].
- **5** In the [Engineering Manager]'s [Controller], use the pull-down menu to select MECHATROLINK connection module.

Select the number associated with the slot number used by the module.

When you select the MECHATROLINK connection module, its setting information is displayed in the

[Engineering Manger]'s [Module details].

6 In the [module Details]'s [Circuit Number] field, enter "01".

Set up the same value as the Display's circuit number.

- 7 In [Details], double-click [MECHATROLINK].
- 8 Click the [Link Assignments] tab, and then set [ST#]'s [01] field as follows.

| Setup Items | Setup Description |
|-------------|--|
| ТҮРЕ | Select the type of Σ -V Series you are using. |

[ST#] is defined based on the Σ-V Series station address.
 When the station address is 41H, define "ST#01".

- 9 In the [Engineering Manager]'s [Controller], select CPU.
- **10** In the [Module details], double-click the communication module's No. field.
- **11** Set [Transmission Parameters] as follows.

| Setup Items | Setup Description |
|-------------|-------------------|
| IP Address | 192.168.0.1 |
| Subnet Mask | 255.255.255.0 |

- 12 From the [File] menu select [Save] to save your settings, and exit [Engineering Manager].
- **13** Write the settings to the MP Series.

IMPORTANT • To write the settings, select the [Save to flash after transferring to the controller] check box.

If the data is transferred without selecting the check box, the transferred data is deleted when restarting the External Device.

Σ-V Series Setting

Set up communication settings with the DIP Switch (SW2) and the rotary switch (SW1). For example, when the SW2-3 is OFF and SW1 is 1, the station address is 41H.

For details on communication settings, please refer to the manual for the External Device.

• DIP Switch (SW2) Setting

| DIP Switch | Settings | Setup Description |
|------------|----------|--|
| 1 | ON | Communication speed: 10Mbps (MECHATROLINK-II) |
| 2 | Optional | Data transfer size. ON: 32-byte data transfer OFF: 17-byte data transfer |
| 3 | OFF | Define the station address in combination with the rotary switch (SW1). ON: Tenth's position of station address is 0x5 OFF: Tenth's position of station address is 0x4 |
| 4 | OFF | Always OFF |

• Rotary Switch (SW1) Setting

Set the station address in combination with the DIP Switch (SW2), number 3.

| Rotary Switch | Settings | Setup Description | |
|---------------|----------|-----------------------------------|--|
| SW1 | 1 | Ones place of the station address | |

Notes

3.7 Setting Example 7

Settings of GP-Pro EX

Communication Settings

To display the setup screen, from the [Project] menu, point to [System Settings] and select [Device/PLC].

| Device/PLC 1 | |
|------------------------|---|
| Summary | Change Device/PLC |
| Manufactu | er VASKAWA Electric Corporation Series MP Ethemet/MECHATROLINK Port Ethemet (UDP) |
| Text Data | Mode 1 Change |
| Communica | ion Settings |
| Port No | . 1024 🗾 🔽 Auto |
| Timeou | t 3 🔄 (sec) |
| Retry | 2 * |
| Wait To | Send 0 (ms) Default |
| Device-Spe | sific Settings |
| Allowable of Device | |
| | vice Name Settings Add Indirect |
| 👗 1 P | C1 In Series = Sigma-V Series Rotational Motor(M-III),IP Addre |
| | |
| | |
| IMPORTANT | To connect Σ -V Series using a 1:n connection, [Wait To Send] must be 1 |

Device Setting

more.

To display the [Individual Device Settings] dialog box, from [Device-Specific Settings] in the [Device/PLC] window, select the External Device and click [Settings] I. To connect multiple External Devices, from [Device-Specific Settings] in the [Device/PLC] window, click [Add Device] to add another External Device.

| 🎒 Individual De | evice Settings X |
|--|--|
| PLC1 | |
| Product | Servo |
| Series | Sigma-V Series Rotational Motor(M-III) 💌 |
| If you change the p address settings. | product or series, please reconfirm all |
| Station Address(S | Servo) 3 🗄 |
| Relay Controle | er Setting |
| IP Addres | s 192. 168. 0. 1 |
| D | evice Type Circuit No. |
| 1 MECHAT | ROLINK 🔽 1 🚍 |
| | |
| | |
| | Default |
| | OK (0) Cancel |

- Check with a network administrator about IP address. Do not set the duplicate IP address.
- Set IP address on the External Device address in the [Individual Device Settings] dialog box.
- You need to set IP address on the Display in the offline mode of the Display.

Set communication settings for both MP and Σ -V Series.

MP Series Setting

Use the ladder software (MPE720) to set up communication settings.

For details on communication settings, please refer to the manual of the External Device.

- 1 Start the ladder software.
- **2** Make a project file.
- **3** From the tree view, double-click [Module Configuration].

[Engineering Manager] starts.

- **4** In the [Create new file] dialog box, click [OK].
- **5** In the [Engineering Manager]'s [Controller], use the pull-down menu to select MECHATROLINK connection module.

Select the number associated with the slot number used by the module.

When you select the MECHATROLINK connection module, its setting information is displayed in the

[Engineering Manger]'s [Module details].

6 In the [module Details]'s [Circuit Number] field, enter "01".

Set up the same value as the Display's circuit number.

- 7 In [Details], double-click [MECHATROLINK].
- **8** Click the [Link Assignments] tab, and then [ST#]'s [01] as follows.

| Setup Items | Setup Description |
|-------------|-------------------------|
| ADR | 03H |
| ExADR | 00 |
| VENDOR | Yaskawa Electric co. |
| DEVICE | Σ -V Series type |

NOTE

• [PROFILE], [BYTE] and [SCAN] are defined automatically.

- **9** In the [Engineering Manager]'s [Controller], select CPU.
- 10 In the [Module details], double-click the communication module's No. field.
- **11** Set [Transmission Parameters] as follows.

| Setup Items | Setup Description |
|-------------|-------------------|
| IP Address | 192.168.0.1 |
| Subnet Mask | 255.255.255.0 |

- 12 From the [File] menu select [Save] to save your settings, and exit [Engineering Manager].
- **13** Write the settings to MP Series.

IMPORTANT

• To write the settings, select the [Save to flash after transferring to the controller] check box.

If the data is transferred without selecting the check box, the transferred data is deleted when restarting the External Device.

$\blacktriangleright \Sigma$ -V Series Setting

Set up communication settings with rotary switches (S1 and S2). For details on communication settings, please refer to the manual of the External Device.

| Rotary Switch | Settings | Setup Description |
|---------------|----------|-------------------|
| S1 (x16) | 0 | Station address |
| S2 (x1) | 3 | Station address |

Notes

3.8 Setting Example 8

Settings of GP-Pro EX

Communication Settings

To display the setup screen, from the [Project] menu, point to [System Settings] and select [Device/PLC].

| Device/PLC 1 | |
|--|----------------------------|
| Summary | Change Device/PLC |
| Manufacturer YASKAWA Electric Corporation Series MP Ethemet/MECHATROLINK | Port Ethemet (UDP) |
| Text Data Mode 1 Change | |
| Communication Settings | |
| Port No. 1024 📑 🔽 Auto | |
| Timeout 3 (sec) | |
| Retry 2 | |
| Wait To Send 0 (ms) Default | |
| Device-Specific Settings | |
| Allowable Number <u>Add Device</u> <u>Increase Allowable</u> of Devices/PLCs 32 <u>Number of Devices/PLCs</u> | |
| No. Device Name Settings | Add Indirect Device |
| 1 PLC1 Series=Sigma-V Series Linear Motor(M-III), IP Address= | . |
| | |
| | |
| IMPORTANT • To connect Σ-V Series using a 1:n connection, [\ | /Vait To Send] must be 100 |

Device Setting

more.

To display the [Individual Device Settings] dialog box, from [Device-Specific Settings] in the [Device/PLC] window, select the External Device and click [Settings] I. To connect multiple External Devices, from [Device-Specific Settings] in the [Device/PLC] window, click [Add Device] to add another External Device.

| 🚰 Individual Device Settings |
|--|
| PLC1 |
| Product Servo |
| Series Sigma-V Series Linear Motor(M-III) |
| If you change the product or series, please reconfirm all address settings. |
| Station Address(Servo) 3 |
| Relay Controler Setting |
| IP Address 192. 168. 0. 1 |
| Device Type Circuit No. |
| 1 MECHATROLINK 🔽 1 🗮 |
| |
| |
| Default |
| OK (0) Cancel |
| |

- Check with a network administrator about IP address. Do not set the duplicate IP address.
- Set IP address on the External Device address in the [Individual Device Settings] dialog box.
- You need to set IP address on the Display in the offline mode of the Display.

Set communication settings for both MP and Σ -V Series.

MP Series Setting

Use the ladder software (MPE720) to set up communication settings.

For details on communication settings, please refer to the manual of the External Device.

- 1 Start the ladder software.
- **2** Make a project file.
- **3** From the tree view, double-click [Module Configuration].

[Engineering Manager] starts.

- **4** In the [Create new file] dialog box, click [OK].
- **5** In the [Engineering Manager]'s [Controller], use the pull-down menu to select MECHATROLINK connection module.

Select the number associated with the slot number used by the module.

When you select the MECHATROLINK connection module, its setting information is displayed in the

[Engineering Manger]'s [Module details].

6 In the [module Details]'s [Circuit Number] field, enter "01".

Set up the same value as the Display's circuit number.

- 7 In [Details], double-click [MECHATROLINK].
- **8** Click the [Link Assignments] tab, and then [ST#]'s [01] as follows.

| Setup Items | Setup Description |
|-------------|-------------------------|
| ADR | 03H |
| ExADR | 00 |
| VENDOR | Yaskawa Electric co. |
| DEVICE | Σ -V Series type |

NOTE

• [PROFILE], [BYTE] and [SCAN] are defined automatically.

- **9** In the [Engineering Manager]'s [Controller], select CPU.
- 10 In the [Module details], double-click the communication module's No. field.
- **11** Set [Transmission Parameters] as follows.

| Setup Items | Setup Description |
|-------------|-------------------|
| IP Address | 192.168.0.1 |
| Subnet Mask | 255.255.255.0 |

- 12 From the [File] menu select [Save] to save your settings, and exit [Engineering Manager].
- **13** Write the settings to MP Series.

IMPORTANT

• To write the settings, select the [Save to flash after transferring to the controller] check box.

If the data is transferred without selecting the check box, the transferred data is deleted when restarting the External Device.

$\blacktriangleright \Sigma$ -V Series Setting

Set up communication settings with rotary switches (S1 and S2). For details on communication settings, please refer to the manual of the External Device.

| Rotary Switch | Settings | Setup Description |
|---------------|----------|-------------------|
| S1 (x16) | 0 | Station address |
| S2 (x1) | 3 | |

Notes

3.9 Setting Example 9

Settings of GP-Pro EX

Communication Settings

To display the setup screen, from the [Project] menu, point to [System Settings] and select [Device/PLC].

| Device/PLC 1 | | |
|-------------------------------------|--|--------------------|
| Summary | | Change Device/PLC |
| Manufacturer YASK | AWA Electric Corporation Series MP Ethemet/MECHATROLINK | Port Ethemet (UDP) |
| Text Data Mode | 1 Change | |
| Communication Settings | 5 | |
| Port No. | 1024 🛃 🔽 Auto | |
| Timeout | 3 * (sec) | |
| Retry | 2 | |
| Wait To Send | 0 (ms) Default | |
| Device-Specific Setting | s | |
| Allowable Number of Devices/PLCs | 32 Add Device Increase Allowable Number of Devices/PLCs | Add Indirect |
| No. Device Name | Settings | Device |
| 👗 1 PLC1 | Series=MP3000 Series,Access to Sub CPU=OFF,IP Ac | F . |

Device Setting

To display the [Individual Device Settings] dialog box, from [Device-Specific Settings] in the [Device/PLC] window, select the External Device and click [Settings] III. To connect multiple External Devices, from [Device-Specific Settings] in the [Device/PLC] window, click [Add Device] to add another External Device.

| <i>ã</i> Individual D | evice Settings | × |
|---------------------------------------|---|----|
| PLC1 | | |
| Product | MP3000 Series 💌 | |
| | Access to Sub CPU | |
| If you change the address settings | product or series, please reconfirm all | |
| IP Address | 192. 168. 0. 1 | |
| | | |
| | | |
| | | |
| | | |
| | | |
| | Default | -1 |
| | | |
| | OK (O) Cancel | |

- Check with a network administrator about IP address. Do not set the duplicate IP address.
- Set IP address on the External Device address in the [Individual Device Settings] dialog box.
- You need to set the Display's IP address in its offline mode.

Use the ladder software (MP720 Ver.7) to set up communication settings. For details on communication settings, please refer to the manual of the External Device.

- 1 Start the ladder software.
- 2 Make a project file.
- **3** Click [Module Configuration] to start [MC-Configurator].
- 4 Double-click [218IFD] on the CPU you want to use.
- **5** Click the [Transmission Parameters] tab.
- 6 In the [Transmission Parameters], set the [IP Address] and [Subnet Mask].

| Setup Items | Setup Description | |
|-------------|-------------------|--|
| IP Address | 192.168.0.1 | |
| Subnet Mask | 255.255.255.0 | |

- **7** Write the settings to the External Device.
- ${\bf 8}\,$ Turn ON the External Device again.

Notes

3.10 Setting Example 10

- Settings of GP-Pro EX
- Communication Settings

To display the setup screen, from the [Project] menu, point to [System Settings] and select [Device/PLC].

| Device/PLC 1 | | |
|-------------------------------------|---|--------------------|
| Summary | | Change Device/PLC |
| Manufacturer YASKA | WA Electric Corporation Series MP Ethemet/MECHATROLINK | Port Ethemet (UDP) |
| Text Data Mode | 1 Change | |
| Communication Settings | | |
| Port No. | 1024 🛃 Auto | |
| Timeout | 3 (sec) | |
| Retry | 2 | |
| Wait To Send | 0 (ms) Default | |
| Device-Specific Settings | | |
| Allowable Number of Devices/PLCs | Add Device Increase Allowable 32 Number of Devices/PLCs | Add Indirect |
| No. Device Name | Settings | Device |
| 👗 1 PLC1 | Series=V1000,IP Address=192.168.000.001,Station Ac | F . |

Device Setting

To display the [Individual Device Settings] dialog box, from [Device-Specific Settings] in the [Device/PLC] window, select the External Device and click [Settings] III. To connect multiple External Devices, from [Device-Specific Settings] in the [Device/PLC] window, click [Add Device] to add another External Device.

| <i>拳</i> Individual De | vice Settings |
|--|---|
| PLC1 | |
| Product | Inverter |
| Series | V1000 |
| If you change the p address settings. | product or series, please reconfirm all |
| Station Address(I | nverter) 33 🗄 |
| -Relay Controle | r Setting |
| IP Addres | s 192. 168. 0. 1 |
| De | evice Type Circuit No. |
| 1 MECHAT | ROLINK 🔽 1 🗮 |
| | |
| | |
| | Default |
| | |
| | OK (O) Cancel |

- Check with a network administrator about IP address. Do not set the duplicate IP address.
- Set IP address on the External Device address in the [Individual Device Settings] dialog box.
- You need to set the Display's IP address in offline mode.

For details on communication settings, please refer to the manual of the External Device.

Setup Procedure

- 1 Press UP to display the Parameter Setting Mode screen. Press ENTER to change to Set Up Mode.
- 2 Press UP to display setup items. Press ENTER key to change to setup screen.
- ${\bf 3}\,$ Press UP or RESET to select the setup value. Press ENTER to set up a description.

Setup Description

| Setup Items | Setup value | Description |
|---------------------|-------------|-------------------------------------|
| b1-02 ^{*1} | 3 | Run Command Selection (Option Card) |
| F6-20 | 21 | MECHATROLINK station address |
| F6-22 | 0 | MECHATROLINK link rate (10Mbps) |

*1 Set b1-01 to 3 when you set the frequency via MECHATROLINK.

3.11 Setting Example 11

- Settings of GP-Pro EX
- Communication Settings

To display the setup screen, from the [Project] menu, point to [System Settings] and select [Device/PLC].

| Device/PLC 1 | | | |
|-------------------------------------|--------------------------|--|-------------------------|
| Summary | | | Change Device/PLC |
| Manufacturer YASK | AWA Electric Corporation | Series MP Ethemet/MECHATRO | LINK Port Ethemet (UDP) |
| Text Data Mode | 1 Change | | |
| Communication Settings | | | |
| Port No. | 1024 📑 🔽 Auto | | |
| Timeout | 3 🔹 (sec) | | |
| Retry | 2 📫 | | |
| Wait To Send | 0 🕂 (ms) | Default | |
| Device-Specific Settings | 5 | | |
| Allowable Number of Devices/PLCs | Add Device 32 | Increase Allowable Number of Devices/PLCs | |
| No. Device Name | Settings | | Add Indirect Device |
| 👗 1 PLC1 | Series=A1000,IP | Address=192.168.000.001,Station Ac | - |
| | | | |

Device Setting

To display the [Individual Device Settings] dialog box, from [Device-Specific Settings] in the [Device/PLC] window, select the External Device and click [Settings] III. To connect multiple External Devices, from [Device-Specific Settings] in the [Device/PLC] window, click [Add Device] to add another External Device.

| <i>拳</i> Individual De | vice Settings 🛛 🗙 | | |
|--|---|--|--|
| PLC1 | | | |
| Product Inverter | | | |
| Series | A1000 | | |
| If you change the p address settings. | product or series, please reconfirm all | | |
| Station Address() | nverter) 33 🔆 | | |
| Relay Controle | r Setting | | |
| IP Addres | IP Address 192, 168, 0, 1 | | |
| De | evice Type Circuit No. | | |
| 1 MECHAT | ROLINK 🔽 1 🗮 | | |
| | | | |
| | | | |
| | Default | | |
| | OK (O) Cancel | | |

- Check with a network administrator about IP address. Do not set the duplicate IP address.
- Set IP address on the External Device address in the [Individual Device Settings] dialog box.
- You need to set the Display's IP address in offline mode.

For details on communication settings, please refer to the manual of the External Device.

Setup Procedure

- 1 Press UP to display the Parameter Setting Mode screen. Press ENTER to change to Set Up Mode.
- 2 Press UP to display setup items. Press ENTER key to change to setup screen.
- ${\bf 3}\,$ Press UP or RESET to select the setup value. Press ENTER to set up a description.

Setup Description

| Setup Items | Setup value | Description |
|---------------------|-------------|-------------------------------------|
| b1-02 ^{*1} | 3 | Run Command Selection (Option Card) |
| F6-20 | 21 | MECHATROLINK station address |
| F6-22 | 0 | MECHATROLINK link rate (10Mbps) |

*1 Set b1-01 to 3 when you set the frequency via MECHATROLINK.

3.12 Setting Example 12

- Settings of GP-Pro EX
- Communication Settings

To display the setup screen, from the [Project] menu, point to [System Settings] and select [Device/PLC].

| Device/PLC 1 | | |
|-------------------------------------|--|--------------------|
| Summary | | Change Device/PLC |
| Manufacturer YASK | AWA Electric Corporation Series MP Ethemet/MECHATROLINK | Port Ethemet (UDP) |
| Text Data Mode | 1 Change | |
| Communication Settings | | |
| Port No. | 1024 Auto | |
| Timeout | 3 (sec) | |
| Retry | 2 . | |
| Wait To Send | 0 (ms) Default | |
| Device-Specific Setting | 3 | |
| Allowable Number of Devices/PLCs | 32 Add Device Increase Allowable Number of Devices/PLCs | Add Indirect |
| No. Device Name | Settings | Device |
| 👗 1 PLC1 | Series=MP2000 Series,Access to MPU-01=ON,IP Add | 5 |

Device Setting

To display the [Individual Device Settings] dialog box, from [Device-Specific Settings] in the [Device/PLC] window, select the External Device and click [Settings] III. To connect multiple External Devices, from [Device-Specific Settings] in the [Device/PLC] window, click [Add Device] to add another External Device.

| <i>拳</i> Individual D | evice Settings |
|---------------------------------------|---|
| PLC1 | |
| Product | MP2000 Series |
| | Access to MPU-01 |
| If you change the address settings | product or series, please reconfirm all |
| Relay Contro | ler Setting |
| IP Addre | ss 192. 168. 0. 1 |
| | Device Type Circuit No. |
| 1 MPU-01 | 3 |
| | |
| | |
| | Default |
| | OK (O) Cancel |

- Check with a network administrator about IP address. Do not set the duplicate IP address.
- Set IP address on the External Device address in the [Individual Device Settings] dialog box.
- You need to set IP address on the Display in the offline mode of the Display.

Use the ladder software (MP720 Ver.7) to set up communication settings. For details on communication settings, please refer to the manual of the External Device.

- 1 Start the ladder software.
- **2** Make a project file. Select the main CPU models from [Model].
- **3** From the tree view, double-click [Module Configuration].

[MC-Configurator] starts.

- **4** Double-click [218IFD] on the CPU to use.
- 5 Click [Parameters] tab.
- 6 Set "IP Address" and "Subnet Mask" of "Transmission Parameters".

| Setup Items | Setup Description |
|-------------|-------------------|
| IP Address | 192.168.0.1 |
| Subnet Mask | 255.255.255.0 |

- 7 Double-click the module number corresponding to the option slot which attaches MPU-01 in the [MC-Configurator]
- **8** Select [MPU-01] in the [Module] dialog box, and click [OK].
- 9 Set "3" to the circuit number of MPU-01 that displayed in the [MC-Configurator].

Set up the same value as the Display's circuit number.

10 Write the settings to the External Device.

| To write the settings, select the [Save to flash after transferring to the controller] check |
|--|
| box. |
| If the data is transferred without selecting the check box, the transferred data is |
| deleted when restarting the External Device. |

Notes

3.13 Setting Example 13

- Settings of GP-Pro EX
- Communication Settings

To display the setup screen, from the [Project] menu, point to [System Settings] and select [Device/PLC].

| Device/PLC 1 | | |
|-------------------------------------|--|--------------------|
| Summary | | Change Device/PLC |
| Manufacturer YASK | AWA Electric Corporation Series MP Ethemet/MECHATROLINK | Port Ethemet (UDP) |
| Text Data Mode | 1 Change | |
| Communication Settings | 3 | |
| Port No. | 1024 🗾 🖌 Auto | |
| Timeout | 3 (sec) | |
| Retry | 2 * | |
| Wait To Send | 0 (ms) Default | |
| Device-Specific Settings | S | |
| Allowable Number of Devices/PLCs | 32 Add Device Increase Allowable Number of Devices/PLCs | Add Indirect |
| No. Device Name | Settings | Device |
| 👗 1 PLC1 | Series=Sigma-V Series Rotational Motor(M-III),IP Addre | F . |

Device Setting

To display the [Individual Device Settings] dialog box, from [Device-Specific Settings] in the [Device/PLC] window, select the External Device and click [Settings] III. To connect multiple External Devices, from [Device-Specific Settings] in the [Device/PLC] window, click [Add Device] to add another External Device.

| 🎒 Individual D | evice Settings X |
|-------------------------------------|--|
| PLC1 | |
| Product | Servo |
| Series | Sigma-V Series Rotational Motor(M-III) 💌 |
| If you change the address settings. | product or series, please reconfirm all |
| Station Address(| Servo) 3 🗄 |
| Relay Control | er Setting |
| IP Addres | s 192. 168. 0. 1 |
| D | evice Type Circuit No. |
| 1 MPU-01 | 3 |
| 2 MECHAT | ROLINK 🗾 1 🗮 |
| | |
| | Default |
| | OK (O) Cancel |

- · Check with a network administrator about IP address. Do not set the duplicate IP address.
- Set IP address on the External Device address in the [Individual Device Settings] dialog box.
- You need to set IP address on the Display in the offline mode of the Display.

Use the ladder software (MP720 Ver.7) to set up communication settings. Set the next contents. (1) Main CPU settings

- (2) MPU-01 settings
- (3) Σ -Vseries settings

For details on communication settings, please refer to the manual of the External Device.

Main CPU Settings

- 1 Start the ladder software.
- **2** Make a project file. Select the main CPU models from [Model].
- **3** From the tree view, double-click [Module Configuration].

[MC-Configurator] starts.

- **4** Double-click [218IFD] on the CPU to use.
- 5 Click [Parameters] tab.
- 6 Set "IP Address" and "Subnet Mask" of "Transmission Parameters".

| Setup Items | Setup Description |
|-------------|-------------------|
| IP Address | 192.168.0.1 |
| Subnet Mask | 255.255.255.0 |

- 7 Double-click the module number corresponding to the option slot which attaches MPU-01 in the [MC-Configurator]
- 8 Select [MPU-01] in the [Module] dialog box, and click [OK].
- 9 Set "3" to the circuit number of MPU-01 that displayed in the [MC-Configurator].

Set up the same value as the Display's circuit number.

10 Write the settings to the External Device.

• To write the settings, select the [Save to flash after transferring to the controller] check box. If the data is transferred without selecting the check box, the transferred data is deleted when restarting the External Device.

♦ MPU-01 Settings

- 1 Start the ladder software.
- 2 Make a project file. Select "MPU-01" from [Model].
- **3** From the tree view, double-click [Module Configuration]. [MC-Configurator] starts.
- 4 Expand [SVC] of [MPU-01] module, and double-click [01 UNDEFINED].
- 5 Select the using Σ -V series of [Slave] dialog box, and click [OK].
- 6 Set "1" to the circuit number of [SVC].
- 7 Set "3" to the station address of the added V-series.

8 Write the settings to the MPU-01 series.

IMPORTANT • To write the settings, select the [Save to flash after transferring to the controller] check box.

If the data is transferred without selecting the check box, the transferred data is deleted when restarting the External Device.

Σ-V Series Setting

Set up communication settings with rotary switches (S1 and S2). For details on communication settings, please refer to the manual of the External Device.

| Rotary Switch | Settings | Setup Description |
|---------------|----------|-------------------|
| S1 (x16) | 0 | Station address |
| S2 (x1) | 3 | |

Notes

3.14 Setting Example 14

- Settings of GP-Pro EX
- Communication Settings

To display the setup screen, from the [Project] menu, point to [System Settings] and select [Device/PLC].

| Device/PLC 1 | | |
|-------------------------------------|---|--------------------|
| Summary | | Change Device/PLC |
| Manufacturer YASKA | AWA Electric Corporation Series MP Ethemet/MECHATROLINK | Port Ethemet (UDP) |
| Text Data Mode | 1 Change | |
| Communication Settings | | |
| Port No. | 1024 🔄 🖌 Auto | |
| Timeout | 3 (sec) | |
| Retry | 2 * | |
| Wait To Send | 0 (ms) Default | |
| Device-Specific Settings | 3 | |
| Allowable Number of Devices/PLCs | Add Device Increase Allowable 32 Number of Devices/PLCs | Add Indirect |
| No. Device Name | Settings | Device |
| 👗 1 PLC1 | Series=Sigma-V Series Linear Motor(M-III),IP Address= | F |

Device Setting

To display the [Individual Device Settings] dialog box, from [Device-Specific Settings] in the [Device/PLC] window, select the External Device and click [Settings] III. To connect multiple External Devices, from [Device-Specific Settings] in the [Device/PLC] window, click [Add Device] to add another External Device.

| 🎒 Individual D | evice Settings X |
|--|---|
| PLC1 | |
| Product | Servo |
| Series | Sigma-V Series Linear Motor(M-III) |
| If you change the address settings. | product or series, please reconfirm all |
| Station Address(| Servo) 3 🗄 |
| Relay Control | er Setting |
| IP Addre: | ss 192. 168. 0. 1 |
| C | levice Type Circuit No. |
| 1 MPU-01 | 3 |
| 2 MECHAT | ROLINK 🔽 1 🚍 |
| | |
| | Default |
| | OK (O) Cancel |

- Check with a network administrator about IP address. Do not set the duplicate IP address.
- Set IP address on the External Device address in the [Individual Device Settings] dialog box.
- You need to set IP address on the Display in the offline mode of the Display.

Use the ladder software (MP720 Ver.7) to set up communication settings. Set the next contents. (1) Main CPU settings

- (2) MPU-01 settings
- (3) Σ -Vseries settings

For details on communication settings, please refer to the manual of the External Device.

Main CPU Settings

- 1 Start the ladder software.
- **2** Make a project file. Select the main CPU models from [Model].
- **3** From the tree view, double-click [Module Configuration].

[MC-Configurator] starts.

- **4** Double-click [218IFD] on the CPU to use.
- 5 Click [Parameters] tab.
- 6 Set "IP Address" and "Subnet Mask" of "Transmission Parameters".

| Setup Items | Setup Description |
|-------------|-------------------|
| IP Address | 192.168.0.1 |
| Subnet Mask | 255.255.255.0 |

- 7 Double-click the module number corresponding to the option slot which attaches MPU-01 in the [MC-Configurator]
- 8 Select [MPU-01] in the [Module] dialog box, and click [OK].
- 9 Set "3" to the circuit number of MPU-01 that displayed in the [MC-Configurator].

Set up the same value as the Display's circuit number.

10 Write the settings to the External Device.

• To write the settings, select the [Save to flash after transferring to the controller] check box. If the data is transferred without selecting the check box, the transferred data is deleted when restarting the External Device.

♦ MPU-01 Settings

- 1 Start the ladder software.
- 2 Make a project file. Select "MPU-01" from [Model].
- **3** From the tree view, double-click [Module Configuration]. [MC-Configurator] starts.
- 4 Expand [SVC] of [MPU-01] module, and double-click [01 UNDEFINED].
- 5 Select the using Σ -V series of [Slave] dialog box, and click [OK].
- 6 Set "1" to the circuit number of [SVC].
- 7 Set "3" to the station address of the added V-series.

8 Write the settings to the MPU-01 series.

IMPORTANT • To write the settings, select the [Save to flash after transferring to the controller] check box.

If the data is transferred without selecting the check box, the transferred data is deleted when restarting the External Device.

Σ-V Series Setting

Set up communication settings with rotary switches (S1 and S2). For details on communication settings, please refer to the manual of the External Device.

| Rotary Switch | Settings | Setup Description |
|---------------|----------|-------------------|
| S1 (x16) | 0 | Station address |
| S2 (x1) | 3 | |

Notes

3.15 Setting Example 15

- Settings of GP-Pro EX
- Communication Settings

To display the setup screen, from the [Project] menu, point to [System Settings] and select [Device/PLC].

| Device/PLC 1 | | |
|-------------------------------------|---|--------------------|
| Summary | | Change Device/PLC |
| Manufacturer YA | SKAWA Electric Corporation Series MP Ethemet/MECHATROLINK | Port Ethemet (UDP) |
| Text Data Mode | 1 Change | |
| Communication Setti | ngs | |
| Port No. | 1024 - Auto | |
| Timeout | 3 (sec) | |
| Retry | 2 - | |
| Wait To Send | 0 (ms) Default | |
| Device-Specific Setti | ings | |
| Allowable Number of Devices/PLCs | Add Device Increase Allowable 32 Number of Devices/PLCs | Add Indirect |
| No. Device Nan | ne Settings | Device |
| 👗 1 🛛 PLC1 | Series=MP3000 Series,Access to Sub CPU=ON,IP Ad | F |

Device Setting

To display the [Individual Device Settings] dialog box, from [Device-Specific Settings] in the [Device/PLC] window, select the External Device and click [Settings] III. To connect multiple External Devices, from [Device-Specific Settings] in the [Device/PLC] window, click [Add Device] to add another External Device.

| 🎒 Individual 🛛 | Device Settings | × |
|--|-------------------------|---|
| PLC1 | | |
| Product | MP3000 Series 💌 | |
| | Access to Sub CPU | |
| If you change the product or series, please reconfirm all address settings. | | |
| Relay Contro | oler Setting | 1 |
| IP Addr | ess 192. 168. 0. 1 | |
| | Device Type Circuit No. | |
| 1 Sub CP | °U 🔽 5 🚍 | |
| | | |
| | | |
| | Default | |
| | OK (O) Cancel | 1 |

- Check with a network administrator about IP address. Do not set the duplicate IP address.
- Set IP address on the External Device address in the [Individual Device Settings] dialog box.
- You need to set IP address on the Display in the offline mode of the Display.

Use the ladder software (MP720 Ver.7) to set up communication settings. For details on communication settings, please refer to the manual of the External Device.

- 1 Start the ladder software.
- **2** Make a project file. Select the main CPU models from [Model].
- **3** From the tree view, double-click [Module Configuration].

[MC-Configurator] starts.

- **4** Double-click [218IFD] on the CPU to use.
- 5 Click [Parameters] tab.
- 6 Set "IP Address" and "Subnet Mask" of "Transmission Parameters".

| Setup Items | Setup Description |
|-------------|-------------------|
| IP Address | 192.168.0.1 |
| Subnet Mask | 255.255.255.0 |

- 7 Double-click the number of module which attaches a sub CPU in [MC-Configurator].
- 8 Select a sub CPU to be used in the [Module] dialog box, and click [OK].
- 9 Set "5" to the circuit number of Sub CPU that displayed in the [MC-Configurator].

Set up the same value as the Display's circuit number.

10 Write the settings to the External Device.

| IMPORTANT • | To write the settings, select the [Save to flash after transferring to the controller] check |
|-------------|--|
| | box. |
| | If the data is transferred without selecting the check box, the transferred data is |
| | deleted when restarting the External Device. |

Notes

3.16 Setting Example 16

- Settings of GP-Pro EX
- Communication Settings

To display the setup screen, from the [Project] menu, point to [System Settings] and select [Device/PLC].

| Device/PLC 1 | | |
|-------------------------------------|--|--------------------|
| Summary | | Change Device/PLC |
| Manufacturer YASK | AWA Electric Corporation Series MP Ethemet/MECHATROLINK | Port Ethemet (UDP) |
| Text Data Mode | 1 Change | |
| Communication Settings | 3 | |
| Port No. | 1024 🗾 🖌 Auto | |
| Timeout | 3 (sec) | |
| Retry | 2 * | |
| Wait To Send | 0 (ms) Default | |
| Device-Specific Settings | S | |
| Allowable Number of Devices/PLCs | 32 Add Device Increase Allowable Number of Devices/PLCs | Add Indirect |
| No. Device Name | Settings | Device |
| 👗 1 PLC1 | Series=Sigma-V Series Rotational Motor(M-III),IP Addre | F . |

Device Setting

To display the [Individual Device Settings] dialog box, from [Device-Specific Settings] in the [Device/PLC] window, select the External Device and click [Settings] III. To connect multiple External Devices, from [Device-Specific Settings] in the [Device/PLC] window, click [Add Device] to add another External Device.

| FIndividual Device Settings | | |
|--|--|--|
| PLC1 | | |
| Product | Servo | |
| Series | Sigma-V Series Rotational Motor(M-III) 💌 | |
| If you change the product or series, please reconfirm all address settings. | | |
| Station Address(S | Servo) 3 💼 | |
| Relay Controle | er Setting | |
| IP Address 192, 168, 0, 1 | | |
| D | evice Type Circuit No. | |
| 1 Sub CPU | 5 📰 | |
| 2 MECHAT | ROLINK 🔽 1 🚍 | |
| | | |
| | Default | |
| | OK (O) Cancel | |

- Check with a network administrator about IP address. Do not set the duplicate IP address.
- Set IP address on the External Device address in the [Individual Device Settings] dialog box.
- You need to set IP address on the Display in the offline mode of the Display.

Use the ladder software (MP720 Ver.7) to set up communication settings. Set the next contents. (1) Main CPU settings

- (2) Sub CPU settings
- (3) Σ -Vseries settings

For details on communication settings, please refer to the manual of the External Device.

Main CPU Settings

- 1 Start the ladder software.
- **2** Make a project file. Select the main CPU models from [Model].
- **3** From the tree view, double-click [Module Configuration].

[MC-Configurator] starts.

- **4** Double-click [218IFD] on the CPU to use.
- 5 Click [Parameters] tab.
- 6 Set "IP Address" and "Subnet Mask" of "Transmission Parameters".

| Setup Items | Setup Description |
|-------------|-------------------|
| IP Address | 192.168.0.1 |
| Subnet Mask | 255.255.255.0 |

- 7 Double-click the number of module which attaches a sub CPU in [MC-Configurator].
- **8** Select a sub CPU to be used in the [Module] dialog box, and click [OK].
- 9 Set "5" to the circuit number of Sub CPU that displayed in the [MC-Configurator].

Set up the same value as the Display's circuit number.

10 Write the settings to the External Device.

IMPORTANT
 To write the settings, select the [Save to flash after transferring to the controller] check box.
 If the data is transferred without selecting the check box, the transferred data is deleted when restarting the External Device.

- ♦ Sub CPU Settings
- 1 Start the ladder software.
- **2** Make a project file. Select a Sub CPU to be used from [Model].
- **3** From the tree view, double-click [Module Configuration]. [MC-Configurator] starts.
- 4 Expand [SVC] of Sub CPU, and double-click [01 UNDEFINED].
- 5 Select the using Σ -V series of [Slave] dialog box, and click [OK].
- 6 Set "1" to the circuit number of [SVC].
- 7 Set "3" to the station address of the added V-series.

8 Write the settings to the Sub CPU.

IMPORTANT • To write the settings, select the [Save to flash after transferring to the controller] check box.

If the data is transferred without selecting the check box, the transferred data is deleted when restarting the External Device.

Σ-V Series Setting

Set up communication settings with rotary switches (S1 and S2). For details on communication settings, please refer to the manual of the External Device.

| Rotary Switch | Settings | Setup Description |
|---------------|----------|-------------------|
| S1 (x16) | 0 | Station address |
| S2 (x1) | 3 | |

Notes

3.17 Setting Example 17

- Settings of GP-Pro EX
- Communication Settings

To display the setup screen, from the [Project] menu, point to [System Settings] and select [Device/PLC].

| Device/PLC 1 | | |
|-------------------------------------|--|--------------------|
| Summary | | Change Device/PLC |
| Manufacturer YASK | AWA Electric Corporation Series MP Ethemet/MECHATROLINK | Port Ethemet (UDP) |
| Text Data Mode | 1 Change | |
| Communication Settings | | |
| Port No. | 1024 Auto | |
| Timeout | 3 (sec) | |
| Retry | 2 . | |
| Wait To Send | 0 (ms) Default | |
| Device-Specific Settings | 3 | |
| Allowable Number of Devices/PLCs | 32 Add Device Increase Allowable Number of Devices/PLCs | Add Indirect |
| No. Device Name | Settings | Device |
| 👗 1 PLC1 | Series=Sigma-V Series Linear Motor(M-III),IP Address= | F |

Device Setting

To display the [Individual Device Settings] dialog box, from [Device-Specific Settings] in the [Device/PLC] window, select the External Device and click [Settings] I. To connect multiple External Devices, from [Device-Specific Settings] in the [Device/PLC] window, click [Add Device] to add another External Device.

| 🎒 Individual D | evice Settings X | |
|--|--------------------------------------|--|
| PLC1 | | |
| Product | Servo | |
| Series | Sigma-V Series Linear Motor(M-III) 💽 | |
| If you change the product or series, please reconfirm all address settings. | | |
| Station Address(| Servo) <u>3</u> | |
| Relay Control | er Setting | |
| IP Address 192. 168. 0. 1 | | |
| C | Device Type Circuit No. | |
| 1 Sub CPL | 5 📰 | |
| 2 MECHAT | | |
| | | |
| | Default | |
| | OK (O) Cancel | |

- Check with a network administrator about IP address. Do not set the duplicate IP address.
- Set IP address on the External Device address in the [Individual Device Settings] dialog box.
- You need to set IP address on the Display in the offline mode of the Display.

Use the ladder software (MP720 Ver.7) to set up communication settings. Set the next contents. (1) Main CPU settings

- (2) Sub CPU settings
- (3) Σ -Vseries settings

For details on communication settings, please refer to the manual of the External Device.

Main CPU Settings

- 1 Start the ladder software.
- **2** Make a project file. Select the main CPU models from [Model].
- **3** From the tree view, double-click [Module Configuration].

[MC-Configurator] starts.

- **4** Double-click [218IFD] on the CPU to use.
- 5 Click [Parameters] tab.
- 6 Set "IP Address" and "Subnet Mask" of "Transmission Parameters".

| Setup Items | Setup Description |
|-------------|-------------------|
| IP Address | 192.168.0.1 |
| Subnet Mask | 255.255.255.0 |

- 7 Double-click the number of module which attaches a sub CPU in [MC-Configurator].
- **8** Select a sub CPU to be used in the [Module] dialog box, and click [OK].
- 9 Set "5" to the circuit number of Sub CPU that displayed in the [MC-Configurator].

Set up the same value as the Display's circuit number.

10 Write the settings to the External Device.

IMPORTANT
 To write the settings, select the [Save to flash after transferring to the controller] check box.
 If the data is transferred without selecting the check box, the transferred data is deleted when restarting the External Device.

- Sub CPU Settings
- 1 Start the ladder software.
- **2** Make a project file. Select a sub CPU to be used from [Model].
- **3** From the tree view, double-click [Module Configuration]. [MC-Configurator] starts.
- 4 Expand [SVC] of Sub CPU, and double-click [01 UNDEFINED].
- 5 Select the using Σ -V series of [Slave] dialog box, and click [OK].
- 6 Set "1" to the circuit number of [SVC].
- 7 Set "3" to the station address of the added V-series.

8 Write the settings to the Sub CPU.

IMPORTANT • To write the settings, select the [Save to flash after transferring to the controller] check box.

If the data is transferred without selecting the check box, the transferred data is deleted when restarting the External Device.

Σ-V Series Setting

Set up communication settings with rotary switches (S1 and S2). For details on communication settings, please refer to the manual of the External Device.

| Rotary Switch | Settings | Setup Description |
|---------------|----------|-------------------|
| S1 (x16) | 0 | Station address |
| S2 (x1) | 3 | |

Notes

3.18 Setting Example 18

- Settings of GP-Pro EX
- Communication Settings

To display the setup screen, from the [Project] menu, point to [System Settings] and select [Device/PLC].

| Summary Change Device/PLC Manufacturer YASKAWA Electric Corporation Series MP Ethemet/MECHATROLINK Port Ethemet (UDP) Text Data Mode 1 Change Communication Settings Port No. 1024 Image Image Communication Settings Port No. 1024 Image Image Image Communication Settings Image Image Image Image Image Value 3 Image Image Image Image Image Device-Specific Settings Image Image Image Image Image Image No. Device Name Settings Image Image Image Add Indirect Device I PLC1 Image Series=Sigma-7S series Servo pack(M-II), IP Address=1 Image Image | Device/PLC 1 | | | |
|---|-------------------------|---------------------------------|-------------------------------|------------------------|
| Text Data Mode 1 Change Communication Settings Port No. 1024 IV Auto Timeout 3 IV Auto Timeout 3 Timeout 3 IV Auto Timeout Sec) Retry 2 IV Auto Default Device-Specific Settings Add Device Increase Allowable Allowable Number Add Device Number of Devices/PLCs No. Device Name Settings Add Indirect | Summary | | | Change Device/PLC |
| Communication Settings Port No. 1024 Timeout 3 3 | Manufacturer YASK | AWA Electric Corporation Series | MP Ethemet/MECHATROLIN | VK Port Ethemet (UDP) |
| Port No. 1024 Image: Auto Timeout 3 Image: (sec) Retry 2 Image: Auto Wait To Send 0 Image: (mas) Device-Specific Settings Add Device Allowable Number of Devices/PLCs 32 Increase Allowable Number of Devices/PLCs No. Device Name Settings Add Indirect Device | Text Data Mode | 1 Change | | |
| Timeout 3 and (sec) Retry 2 and Wait To Send 0 and (ms) Device-Specific Settings Add Device Allowable Number of Devices/PLCs 32 No. Device Name Settings | Communication Setting | 3 | | |
| Retry 2 Wait To Send 0 Device-Specific Settings Allowable Number of Devices/PLCs 32 No. Device Name Settings | Port No. | 1024 🗧 🗹 Auto | | |
| Wait To Send O Image: Constraint of the second sec | Timeout | 3 📫 (sec) | | |
| Device-Specific Settings Allowable Number <u>Add Device</u> <u>Increase Allowable</u> of Devices/PLCs 32 <u>Number of Devices/PLCs</u> No. Device Name Settings <u>Add Indirect</u> Device | Retry | 2 * | | |
| Allowable Number Add Device Increase Allowable Of Devices/PLCs 32 Add Indirect Device Name Settings Device | Wait To Send | 0 📑 (ms) De | efault | |
| of Devices/PLCs 32 Number of Devices/PLCs Add Indirect No. Device Name Settings Device | Device-Specific Setting | s | | |
| No. Device Name Settings Add Indirect Device | | | | |
| | | | Humber of Devicean Les | |
| | | | Servo pack(M-II),IP Address=1 | |
| | <u> </u> | | | <u></u> |
| | TANT | nnect Σ -7 Series usin | a a 1:n connection. | [Wait To Send] must be |

Device Setting

more.

To display the [Individual Device Settings] dialog box, from [Device-Specific Settings] in the [Device/PLC] window, select the External Device and click [Settings] I. To connect multiple External Devices, from [Device-Specific Settings] in the [Device/PLC] window, click [Add Device] to add another External Device.

| 🎒 Individual D | evice Settings X |
|--|---|
| PLC1 | |
| Product | Servo |
| Series | Sigma-7S series Servo pack(M-II) |
| If you change the address settings. | product or series, please reconfirm all |
| Station Address(| Servo) 65 芸 |
| Relay Control | er Setting |
| IP Addres | ss 192. 168. 0. 1 |
| D | levice Type Circuit No. |
| 1 MECHAT | ROLINK 🔽 1 🚍 |
| | |
| | |
| | Default |
| | OK (O) Cancel |

- Check with a network administrator about IP address. Do not set the duplicate IP address.
- Set IP address on the External Device address in the [Individual Device Settings] dialog box.
- You need to set IP address on the Display in the offline mode of the Display.

Set communication settings for both MP and Σ -7 Series.

MP Series Setting

Use the ladder software (MPE720) to set up communication settings.

For details on communication settings, please refer to the manual of the External Device.

- 1 Start the ladder software.
- **2** Make a project file.
- **3** From the tree view, double-click [Module Configuration].

[Engineering Manager] starts.

- **4** In the [Create new file] dialog box, click [OK].
- **5** In the [Engineering Manager]'s [Controller], use the pull-down menu to select MECHATROLINK connection module.

Select the number associated with the slot number used by the module.

When you select the MECHATROLINK connection module, its setting information is displayed in the

[Engineering Manger]'s [Module details].

6 In the [module Details]'s [Circuit Number] field, enter "01".

Set up the same value as the Display's circuit number.

- 7 In [Details], double-click [MECHATROLINK].
- 8 Click the [Link Assignments] tab, and then set [ST#]'s [01] field as follows.

| Setup Items | Setup Description |
|-------------|--|
| ТҮРЕ | Select the type of Σ -7 Series you are using. |

NOTE

[ST#] is defined based on the Σ-7 Series station address.
 When the station address is 41H, define "ST#01".

- 9 In the [Engineering Manager]'s [Controller], select CPU.
- **10** In the [Module details], double-click the communication module's No. field.
- **11** Set [Transmission Parameters] as follows.

| Setup Items | Setup Description |
|-------------|-------------------|
| IP Address | 192.168.0.1 |
| Subnet Mask | 255.255.255.0 |

- 12 From the [File] menu select [Save] to save your settings, and exit [Engineering Manager].
- **13** Write the settings to the MP Series.

IMPORTANT • To write the settings, select the [Save to flash after transferring to the controller] check box.

If the data is transferred without selecting the check box, the transferred data is deleted when restarting the External Device.

Σ-7 Series Setting

Set up communication settings with the DIP Switch (SW2) and the rotary switch (SW1). For example, when the SW2-3 is OFF and SW1 is 1, the station address is 41H.

For details on communication settings, please refer to the manual for the External Device.

• DIP Switch (SW2) Setting

| DIP Switch | Settings | Setup Description |
|------------|----------|--|
| 1 | ON | Communication speed: 10Mbps (MECHATROLINK-II) |
| 2 | Optional | Data transfer size. ON: 32-byte data transfer OFF: 17-byte data transfer |
| 3 | OFF | Define the station address in combination with the rotary switch (SW1). ON: Tenth's position of station address is 0x5 OFF: Tenth's position of station address is 0x4 |
| 4 | OFF | Always OFF |

• Rotary Switch (SW1) Setting

Set the station address in combination with the DIP Switch (SW2), number 3.

| Rotary Switch | Settings | Setup Description | |
|---------------|----------|-----------------------------------|--|
| SW1 | 1 | Ones place of the station address | |

Notes

3.19 Setting Example 19

- Settings of GP-Pro EX
- Communication Settings

To display the setup screen, from the [Project] menu, point to [System Settings] and select [Device/PLC].

| Summary Manufacturer YASKAWA Electric Corporation Series MP Ethemet/MECHATROLINK Text Data Mode 1 Change Communication Settings Port No. 1024 - Value Auto | Change Device/PLC Port Ethemet (UDP) |
|--|---|
| Text Data Mode 1 Change | Port Ethemet (UDP) |
| Communication Settings | |
| | |
| Port No. 1024 😴 🔽 Auto | |
| · | |
| Timeout 3 (sec) | |
| Retry 2 | |
| Wait To Send 0 (ms) Default | |
| Device-Specific Settings | |
| Allowable Number Ald Device Increase Allowable of Devices/PLCs 32 Number of Devices/PLCs | |
| No. Device Name Settings | Add Indirect Device |
| 1 PLC1 Series=Sigma-7S series Servo pack(M-III),IP Address= | |
| | L=11 |
| | |

Device Setting

more.

To display the [Individual Device Settings] dialog box, from [Device-Specific Settings] in the [Device/PLC] window, select the External Device and click [Settings] III. To connect multiple External Devices, from [Device-Specific Settings] in the [Device/PLC] window, click [Add Device] to add another External Device.

| <i>拳</i> Individual D | evice Settings X |
|--|---|
| PLC1 | |
| Product | Servo |
| Series | Sigma-7S series Servo pack(M-III) |
| If you change the address settings. | product or series, please reconfirm all |
| Station Address(| Servo) 3 芸 |
| -Relay Control | er Setting |
| IP Addre | ss 192. 168. 0. 1 |
| [| Device Type Circuit No. |
| 1 MECHA | TROLINK 🔽 1 🚍 |
| | |
| | |
| | Default |
| | OK (0) Cancel |

- Check with a network administrator about IP address. Do not set the duplicate IP address.
- Set IP address on the External Device address in the [Individual Device Settings] dialog box.
- You need to set IP address on the Display in the offline mode of the Display.

Set communication settings for both MP and Σ -7 Series.

MP Series Setting

Use the ladder software (MPE720) to set up communication settings.

For details on communication settings, please refer to the manual of the External Device.

- 1 Start the ladder software.
- **2** Make a project file.
- **3** From the tree view, double-click [Module Configuration].

[Engineering Manager] starts.

- **4** In the [Create new file] dialog box, click [OK].
- **5** In the [Engineering Manager]'s [Controller], use the pull-down menu to select MECHATROLINK connection module.

Select the number associated with the slot number used by the module.

When you select the MECHATROLINK connection module, its setting information is displayed in the

[Engineering Manger]'s [Module details].

6 In the [module Details]'s [Circuit Number] field, enter "01".

Set up the same value as the Display's circuit number.

- 7 In [Details], double-click [MECHATROLINK].
- **8** Click the [Link Assignments] tab, and then [ST#]'s [01] as follows.

| Setup Items | Setup Description |
|-------------|-------------------------|
| ADR | 03H |
| ExADR | 00 |
| VENDOR | Yaskawa Electric co. |
| DEVICE | Σ -7 Series type |

NOTE

• [PROFILE], [BYTE] and [SCAN] are defined automatically.

- **9** In the [Engineering Manager]'s [Controller], select CPU.
- 10 In the [Module details], double-click the communication module's No. field.
- **11** Set [Transmission Parameters] as follows.

| Setup Items | Setup Description |
|-------------|-------------------|
| IP Address | 192.168.0.1 |
| Subnet Mask | 255.255.255.0 |

- 12 From the [File] menu select [Save] to save your settings, and exit [Engineering Manager].
- **13** Write the settings to MP Series.

IMPORTANT

• To write the settings, select the [Save to flash after transferring to the controller] check box.

If the data is transferred without selecting the check box, the transferred data is deleted when restarting the External Device.

◆ Σ-7 Series Setting

Set up communication settings with rotary switches (S1 and S2). For details on communication settings, please refer to the manual of the External Device.

| Rotary Switch | Settings | Setup Description |
|---------------|----------|-------------------|
| S1 (x16) | 0 | Station address |
| S2 (x1) | 3 | |

Notes

3.20 Setting Example 20

- Settings of GP-Pro EX
- Communication Settings

To display the setup screen, from the [Project] menu, point to [System Settings] and select [Device/PLC].

| Device/PLC 1 | | |
|-------------------------------------|---|--------------------|
| Summary | | Change Device/PLC |
| Manufacturer YASKA | AWA Electric Corporation Series MP Ethemet/MECHATROLINK | Port Ethemet (UDP) |
| Text Data Mode | 1 Change | |
| Communication Settings | | |
| Port No. | 1024 🚅 🖌 Auto | |
| Timeout | 3 (sec) | |
| Retry | 2 | |
| Wait To Send | 0 (ms) Default | |
| Device-Specific Settings | 3 | |
| Allowable Number of Devices/PLCs | Add Device Increase Allowable 32 Number of Devices/PLCs | Add Indirect |
| No. Device Name | Settings | Device |
| 👗 1 PLC1 | Series=Sigma-7S series Servo pack(M-III),IP Address= | 5 |

Device Setting

To display the [Individual Device Settings] dialog box, from [Device-Specific Settings] in the [Device/PLC] window, select the External Device and click [Settings] I. To connect multiple External Devices, from [Device-Specific Settings] in the [Device/PLC] window, click [Add Device] to add another External Device.

| 🖆 Individual Device Settings 🛛 🔀 | | |
|--|---|--|
| PLC1 | | |
| Product | Servo | |
| Series | Sigma-7S series Servo pack(M-III) | |
| If you change the address settings. | product or series, please reconfirm all | |
| Station Address(| Servo) 3 🔆 | |
| Relay Control | er Setting | |
| IP Addre: | ss 192. 168. 0. 1 | |
| C | levice Type Circuit No. | |
| 1 MPU-01 | 3 | |
| 2 MECHAT | ROLINK 🔽 1 🗮 | |
| | | |
| | Default | |
| | OK (O) Cancel | |

- Check with a network administrator about IP address. Do not set the duplicate IP address.
- Set IP address on the External Device address in the [Individual Device Settings] dialog box.
- You need to set IP address on the Display in the offline mode of the Display.

Use the ladder software (MP720 Ver.7) to set up communication settings. Set the next contents. (1) Main CPU settings

- (2) MPU-01 settings
- (3) Σ -7 series settings

For details on communication settings, please refer to the manual of the External Device.

Main CPU Settings

- 1 Start the ladder software.
- **2** Make a project file. Select the main CPU models from [Model].
- **3** From the tree view, double-click [Module Configuration].

[MC-Configurator] starts.

- **4** Double-click [218IFD] on the CPU to use.
- 5 Click [Parameters] tab.
- 6 Set "IP Address" and "Subnet Mask" of "Transmission Parameters".

| Setup Items | Setup Description |
|-------------|-------------------|
| IP Address | 192.168.0.1 |
| Subnet Mask | 255.255.255.0 |

- 7 Double-click the module number corresponding to the option slot which attaches MPU-01 in the [MC-Configurator]
- 8 Select [MPU-01] in the [Module] dialog box, and click [OK].
- 9 Set "3" to the circuit number of MPU-01 that displayed in the [MC-Configurator].

Set up the same value as the Display's circuit number.

10 Write the settings to the External Device.

• To write the settings, select the [Save to flash after transferring to the controller] check box. If the data is transferred without selecting the check box, the transferred data is deleted when restarting the External Device.

♦ MPU-01 Settings

- 1 Start the ladder software.
- 2 Make a project file. Select "MPU-01" from [Model].
- **3** From the tree view, double-click [Module Configuration]. [MC-Configurator] starts.
- 4 Expand [SVC] of [MPU-01] module, and double-click [01 UNDEFINED].
- 5 Select the using Σ -7 series of [Slave] dialog box, and click [OK].
- 6 Set "1" to the circuit number of [SVC].
- 7 Set "3" to the station address of the added Σ -7 series.

8 Write the settings to the MPU-01 series.

IMPORTANT • To write the settings, select the [Save to flash after transferring to the controller] check box.

If the data is transferred without selecting the check box, the transferred data is deleted when restarting the External Device.

Σ-7 Series Setting

Set up communication settings with rotary switches (S1 and S2). For details on communication settings, please refer to the manual of the External Device.

| Rotary Switch | Settings | Setup Description |
|---------------|----------|-------------------|
| S1 (x16) | 0 | Station address |
| S2 (x1) | 3 | |

Notes

3.21 Setting Example 21

- Settings of GP-Pro EX
- Communication Settings

To display the setup screen, from the [Project] menu, point to [System Settings] and select [Device/PLC].

| Device/PLC 1 | | |
|-------------------------------------|---|--------------------|
| Summary | | Change Device/PLC |
| Manufacturer YAS | KAWA Electric Corporation Series MP Ethemet/MECHATROLINK | Port Ethemet (UDP) |
| Text Data Mode | 1 Change | |
| Communication Setting | gs | |
| Port No. | 1024 🗾 🔽 Auto | |
| Timeout | 3 (sec) | |
| Retry | 2 * | |
| Wait To Send | 0 (ms) Default | |
| Device-Specific Settin | Igs | |
| Allowable Number of Devices/PLCs | Add Device Increase Allowable 32 Number of Devices/PLCs | Add Indirect |
| No. Device Name | e Settings | Device |
| 👗 1 PLC1 | Series=Sigma-7S series Servo pack(M-III),IP Address= | F . |

Device Setting

To display the [Individual Device Settings] dialog box, from [Device-Specific Settings] in the [Device/PLC] window, select the External Device and click [Settings] III. To connect multiple External Devices, from [Device-Specific Settings] in the [Device/PLC] window, click [Add Device] to add another External Device.

| 🚰 Individual Device Settings 🛛 🛛 🔀 | | |
|--|---|--|
| PLC1 | | |
| Product | Servo 💌 | |
| Series | Sigma-7S series Servo pack(M-III) | |
| If you change the address settings. | product or series, please reconfirm all | |
| Station Address(| Servo) 3 芸 | |
| Relay Control | er Setting | |
| IP Addre: | ss 192. 168. 0. 1 | |
| C | levice Type Circuit No. | |
| 1 Sub CPL | 5 | |
| 2 MECHAT | ROLINK 🔽 1 🚍 | |
| | | |
| | Default | |
| | OK (0) Cancel | |

- Check with a network administrator about IP address. Do not set the duplicate IP address.
- Set IP address on the External Device address in the [Individual Device Settings] dialog box.
- You need to set IP address on the Display in the offline mode of the Display.

Use the ladder software (MP720 Ver.7) to set up communication settings. Set the next contents. (1) Main CPU settings

- (2) Sub CPU settings
- (3) Σ -7 series settings

For details on communication settings, please refer to the manual of the External Device.

Main CPU Settings

- 1 Start the ladder software.
- **2** Make a project file. Select the main CPU models from [Model].
- **3** From the tree view, double-click [Module Configuration].

[MC-Configurator] starts.

- **4** Double-click [218IFD] on the CPU to use.
- 5 Click [Parameters] tab.
- 6 Set "IP Address" and "Subnet Mask" of "Transmission Parameters".

| Setup Items | Setup Description |
|-------------|-------------------|
| IP Address | 192.168.0.1 |
| Subnet Mask | 255.255.255.0 |

- 7 Double-click the number of module which attaches a sub CPU in [MC-Configurator].
- 8 Select a sub CPU to be used in the [Module] dialog box, and click [OK].
- 9 Set "5" to the circuit number of Sub CPU that displayed in the [MC-Configurator].

Set up the same value as the Display's circuit number.

10 Write the settings to the External Device.

IMPORTANT
 To write the settings, select the [Save to flash after transferring to the controller] check box.
 If the data is transferred without selecting the check box, the transferred data is deleted when restarting the External Device.

- ♦ Sub CPU Settings
- 1 Start the ladder software.
- **2** Make a project file. Select a Sub CPU to be used from [Model].
- **3** From the tree view, double-click [Module Configuration]. [MC-Configurator] starts.
- 4 Expand [SVC] of Sub CPU, and double-click [01 UNDEFINED].
- 5 Select the using Σ -7 series of [Slave] dialog box, and click [OK].
- 6 Set "1" to the circuit number of [SVC].
- 7 Set "3" to the station address of the added Σ -7 series.

8 Write the settings to the Sub CPU.

IMPORTANT • To write the settings, select the [Save to flash after transferring to the controller] check box.

If the data is transferred without selecting the check box, the transferred data is deleted when restarting the External Device.

Σ-7 Series Setting

Set up communication settings with rotary switches (S1 and S2). For details on communication settings, please refer to the manual of the External Device.

| Rotary Switch | Settings | Setup Description |
|---------------|----------|-------------------|
| S1 (x16) | 0 | Station address |
| S2 (x1) | 3 | |

Notes

3.22 Setting Example 22

Settings of GP-Pro EX

Communication Settings

To display the setup screen, from the [Project] menu, point to [System Settings] and select [Device/PLC].

| Device/PLC 1 | |
|---|--------------------------------|
| Summary | Change Device/PLC |
| Manufacturer YASKAWA Electric Corporation Series MP Ethemet/M | ECHATROLINK Port Ethemet (UDP) |
| Text Data Mode 1 Change | |
| Communication Settings | |
| Port No. 1024 🗾 Auto | |
| Timeout 3 (sec) | |
| Retry 2 | |
| Wait To Send 0 (ms) Default | |
| Device-Specific Settings | |
| Allowable Number Add Device Increase Allowable of Devices/PLCs 32 Number of Device | |
| No. Device Name Settings | Add Indirect Device |
| | |
| I PLC1 Series=Sigma-7W series Servo pack(M-III),IF | P Address= |
| | |

Device Setting

more.

To display the [Individual Device Settings] dialog box, from [Device-Specific Settings] in the [Device/PLC] window, select the External Device and click [Settings] I. To connect multiple External Devices, from [Device-Specific Settings] in the [Device/PLC] window, click [Add Device] to add another External Device.

| <i>拳</i> Individual De | vice Settings |
|--|--|
| PLC1 | |
| Product | Servo |
| Series | Sigma-7W series Servo pack(M-III) 💌 |
| If you change the p address settings. | roduct or series, please reconfirm all |
| Station Address(S | iervo) 3 ই Axis No. 1 芸 |
| -Relay Controle | r Setting |
| IP Addres | s 192. 168. 0. 1 |
| De | evice Type Circuit No. |
| 1 MECHAT | ROLINK 🔽 1 🚍 |
| | |
| | |
| | Default |
| | |
| | OK (O) Cancel |

- Check with a network administrator about IP address. Do not set the duplicate IP address.
- Set IP address on the External Device address in the [Individual Device Settings] dialog box.
- You need to set IP address on the Display in the offline mode of the Display.

Set communication settings for both MP and Σ -7 Series.

MP Series Setting

Use the ladder software (MPE720) to set up communication settings.

For details on communication settings, please refer to the manual of the External Device.

- 1 Start the ladder software.
- **2** Make a project file.
- **3** From the tree view, double-click [Module Configuration].

[Engineering Manager] starts.

- **4** In the [Create new file] dialog box, click [OK].
- **5** In the [Engineering Manager]'s [Controller], use the pull-down menu to select MECHATROLINK connection module.

Select the number associated with the slot number used by the module.

When you select the MECHATROLINK connection module, its setting information is displayed in the

[Engineering Manger]'s [Module details].

6 In the [module Details]'s [Circuit Number] field, enter "01".

Set up the same value as the Display's circuit number.

- 7 In [Details], double-click [MECHATROLINK].
- **8** Click the [Link Assignments] tab, and then [ST#]'s [01] as follows.

| Setup Items | Setup Description |
|-------------|-------------------------|
| ADR | 03H |
| ExADR | 00 |
| VENDOR | Yaskawa Electric co. |
| DEVICE | Σ -7 Series type |

NOTE

• [PROFILE], [BYTE] and [SCAN] are defined automatically.

- **9** In the [Engineering Manager]'s [Controller], select CPU.
- 10 In the [Module details], double-click the communication module's No. field.
- **11** Set [Transmission Parameters] as follows.

| Setup Items | Setup Description |
|-------------|-------------------|
| IP Address | 192.168.0.1 |
| Subnet Mask | 255.255.255.0 |

- 12 From the [File] menu select [Save] to save your settings, and exit [Engineering Manager].
- **13** Write the settings to MP Series.

IMPORTANT

• To write the settings, select the [Save to flash after transferring to the controller] check box.

If the data is transferred without selecting the check box, the transferred data is deleted when restarting the External Device.

◆ Σ-7 Series Setting

Set up communication settings with rotary switches (S1 and S2). For details on communication settings, please refer to the manual of the External Device.

| Rotary Switch | Settings | Setup Description |
|---------------|----------|-------------------|
| S1 (x16) | 0 | Station address |
| S2 (x1) | 3 | |

Notes

3.23 Setting Example 23

- Settings of GP-Pro EX
- Communication Settings

To display the setup screen, from the [Project] menu, point to [System Settings] and select [Device/PLC].

| Device/PLC 1 | | |
|-------------------------------------|--|--------------------|
| Summary | | Change Device/PLC |
| Manufacturer YASK | AWA Electric Corporation Series MP Ethemet/MECHATROLINK | Port Ethemet (UDP) |
| Text Data Mode | 1 Change | |
| Communication Settings | 1 | |
| Port No. | 1024 🔄 🖌 Auto | |
| Timeout | 3 (sec) | |
| Retry | 2 * | |
| Wait To Send | 0 (ms) Default | |
| Device-Specific Settings | 3 | |
| Allowable Number of Devices/PLCs | 32 Add Device Increase Allowable Number of Devices/PLCs | Add Indirect |
| No. Device Name | Settings | Device |
| 👗 1 PLC1 | Series=Sigma-7W series Servo pack(M-III),IP Address= | F . |

Device Setting

To display the [Individual Device Settings] dialog box, from [Device-Specific Settings] in the [Device/PLC] window, select the External Device and click [Settings] III. To connect multiple External Devices, from [Device-Specific Settings] in the [Device/PLC] window, click [Add Device] to add another External Device.

| <i>拳</i> Individual D | evice Settings | | | |
|-----------------------|--|--|--|--|
| PLC1 | | | | |
| Product | Servo 💌 | | | |
| Series | Sigma-7W series Servo pack(M-III) 💽 | | | |
| | If you change the product or series, please reconfirm all address settings. | | | |
| Station Address | (Servo) 3 🔆 Axis No. 1 🔆 | | | |
| -Relay Contro | ler Setting | | | |
| IP Addre | ss 192. 168. 0. 1 | | | |
| [| Device Type Circuit No. | | | |
| 1 MPU-01 | 3 芸 | | | |
| 2 MECHA | TROLINK 🔽 1 🗮 | | | |
| | | | | |
| | Default | | | |
| | OK (O) Cancel | | | |

- Check with a network administrator about IP address. Do not set the duplicate IP address.
- Set IP address on the External Device address in the [Individual Device Settings] dialog box.
- You need to set IP address on the Display in the offline mode of the Display.

Use the ladder software (MP720 Ver.7) to set up communication settings. Set the next contents. (1) Main CPU settings

- (2) MPU-01 settings
- (3) Σ -7 series settings

For details on communication settings, please refer to the manual of the External Device.

Main CPU Settings

- 1 Start the ladder software.
- **2** Make a project file. Select the main CPU models from [Model].
- **3** From the tree view, double-click [Module Configuration].

[MC-Configurator] starts.

- **4** Double-click [218IFD] on the CPU to use.
- 5 Click [Parameters] tab.
- 6 Set "IP Address" and "Subnet Mask" of "Transmission Parameters".

| Setup Items | Setup Description |
|-------------|-------------------|
| IP Address | 192.168.0.1 |
| Subnet Mask | 255.255.255.0 |

- 7 Double-click the module number corresponding to the option slot which attaches MPU-01 in the [MC-Configurator]
- 8 Select [MPU-01] in the [Module] dialog box, and click [OK].
- 9 Set "3" to the circuit number of MPU-01 that displayed in the [MC-Configurator].

Set up the same value as the Display's circuit number.

10 Write the settings to the External Device.

• To write the settings, select the [Save to flash after transferring to the controller] check box. If the data is transferred without selecting the check box, the transferred data is deleted when restarting the External Device.

♦ MPU-01 Settings

- 1 Start the ladder software.
- 2 Make a project file. Select "MPU-01" from [Model].
- **3** From the tree view, double-click [Module Configuration]. [MC-Configurator] starts.
- 4 Expand [SVC] of [MPU-01] module, and double-click [01 UNDEFINED].
- 5 Select the using Σ -7 series of [Slave] dialog box, and click [OK].
- 6 Set "1" to the circuit number of [SVC].
- 7 Set "3" to the station address of the added Σ -7 series.

8 Write the settings to the MPU-01 series.

IMPORTANT • To write the settings, select the [Save to flash after transferring to the controller] check box.

If the data is transferred without selecting the check box, the transferred data is deleted when restarting the External Device.

Σ-7 Series Setting

Set up communication settings with rotary switches (S1 and S2). For details on communication settings, please refer to the manual of the External Device.

| Rotary Switch | Settings | Setup Description |
|---------------|----------|-------------------|
| S1 (x16) | 0 | Station address |
| S2 (x1) | 3 | |

Notes

3.24 Setting Example 24

Settings of GP-Pro EX

Communication Settings

To display the setup screen, from the [Project] menu, point to [System Settings] and select [Device/PLC].

| Device/PLC 1 | | |
|--|---|--------------------------------|
| Summary | | Change Device/PLC |
| Manufacturer YASKAW | A Electric Corporation Series MP Ethemet/M | ECHATROLINK Port Ethemet (UDP) |
| Text Data Mode | 1 Change | |
| Communication Settings | | |
| Port No. | 1024 🗾 🗹 Auto | |
| Timeout | 3 • (sec) | |
| Retry | 2 : | |
| Wait To Send | 0 (ms) Default | |
| Device-Specific Settings | | |
| Allowable Number of Devices/PLCs 32 | Add Device Increase Allowab Number of Device | |
| No. Device Name | Settings | Device |
| 👗 1 PLC1 | Series=Sigma-7W series Servo pack(M-III),II | P Address= |

Device Setting

To display the [Individual Device Settings] dialog box, from [Device-Specific Settings] in the [Device/PLC] window, select the External Device and click [Settings] III. To connect multiple External Devices, from [Device-Specific Settings] in the [Device/PLC] window, click [Add Device] to add another External Device.

| 🎒 Individual D | evice Settings |
|--|---|
| PLC1 | |
| Product | Servo 💌 |
| Series | Sigma-7W series Servo pack(M-III) |
| If you change the address settings. | product or series, please reconfirm all |
| Station Address(| Servo) 3 🔆 Axis No. 1 🔆 |
| Relay Control | er Setting |
| IP Addre | ss 192. 168. 0. 1 |
| [| Device Type Circuit No. |
| 1 Sub CPL | J 💌 5 📰 |
| 2 MECHAT | TROLINK 💌 1 🗮 |
| | |
| | Default |
| | OK (0) Cancel |

- Check with a network administrator about IP address. Do not set the duplicate IP address.
- Set IP address on the External Device address in the [Individual Device Settings] dialog box.
- You need to set IP address on the Display in the offline mode of the Display.

Use the ladder software (MP720 Ver.7) to set up communication settings. Set the next contents. (1) Main CPU settings

- (2) Sub CPU settings
- (3) Σ -7 series settings

For details on communication settings, please refer to the manual of the External Device.

Main CPU Settings

- 1 Start the ladder software.
- **2** Make a project file. Select the main CPU models from [Model].
- **3** From the tree view, double-click [Module Configuration].

[MC-Configurator] starts.

- **4** Double-click [218IFD] on the CPU to use.
- 5 Click [Parameters] tab.
- 6 Set "IP Address" and "Subnet Mask" of "Transmission Parameters".

| Setup Items | Setup Description |
|-------------|-------------------|
| IP Address | 192.168.0.1 |
| Subnet Mask | 255.255.255.0 |

- 7 Double-click the number of module which attaches a sub CPU in [MC-Configurator].
- 8 Select a sub CPU to be used in the [Module] dialog box, and click [OK].
- 9 Set "5" to the circuit number of Sub CPU that displayed in the [MC-Configurator].

Set up the same value as the Display's circuit number.

10 Write the settings to the External Device.

IMPORTANT
 To write the settings, select the [Save to flash after transferring to the controller] check box.
 If the data is transferred without selecting the check box, the transferred data is deleted when restarting the External Device.

- Sub CPU Settings
- 1 Start the ladder software.
- **2** Make a project file. Select a Sub CPU to be used from [Model].
- **3** From the tree view, double-click [Module Configuration]. [MC-Configurator] starts.
- 4 Expand [SVC] of Sub CPU, and double-click [01 UNDEFINED].
- 5 Select the using Σ -7 series of [Slave] dialog box, and click [OK].
- 6 Set "1" to the circuit number of [SVC].
- 7 Set "3" to the station address of the added Σ -7 series.

8 Write the settings to the Sub CPU.

IMPORTANT • To write the settings, select the [Save to flash after transferring to the controller] check box.

If the data is transferred without selecting the check box, the transferred data is deleted when restarting the External Device.

Σ-7 Series Setting

Set up communication settings with rotary switches (S1 and S2). For details on communication settings, please refer to the manual of the External Device.

| Rotary Switch | Settings | Setup Description |
|---------------|----------|-------------------|
| S1 (x16) | 0 | Station address |
| S2 (x1) | 3 | |

Notes

3.25 Setting Example 25

Settings of GP-Pro EX

Communication Settings

To display the setup screen, from the [Project] menu, point to [System Settings] and select [Device/PLC].

| Device/PLC 1 | |
|--|------------------------|
| Summary | Change Device/PLC |
| Manufacturer YASKAWA Electric Corporation Series MP Ethemet/MECHATROLINK | Port Ethemet (UDP) |
| Text Data Mode 1 Change | |
| Communication Settings | |
| Port No. 1024 💆 Auto | |
| Timeout 3 (sec) | |
| Retry 2 | |
| Wait To Send 0 💼 (ms) Default | |
| Device-Specific Settings | |
| Allowable Number <u>Add Device</u> <u>Increase Allowable</u> of Devices/PLCs 32 <u>Number of Devices/PLCs</u> | |
| No. Device Name Settings | Add Indirect Device |
| 1 PLC1 Iseries=R7G4HML3-LC2(M-III),IP Address=192.168.00 | . |
| | |
| | |
| PORTANT • To connect Remote I/O Series using a 1:n connect | tion, [Wait To Send] r |
| 100ms or more | |

Device Setting

To display the [Individual Device Settings] dialog box, from [Device-Specific Settings] in the [Device/PLC] window, select the External Device and click [Settings] III. To connect multiple External Devices, from [Device-Specific Settings] in the [Device/PLC] window, click [Add Device] to add another External Device.

| 🎒 Individual De | vice Settings | × | |
|--|--|---|--|
| PLC1 | | | |
| Product | I/O(M-System) | | |
| Series | R7G4HML3-LC2(M-III) | | |
| If you change the p address settings. | roduct or series, please reconfirm all | | |
| Station Address(L | (O) 3 🗮 | | |
| -Relay Controle | r Setting | 1 | |
| IP Address | s 192. 168. 0. 1 | | |
| De | vice Type Circuit No. | | |
| 1 MECHAT | ROLINK 🔽 1 🗮 | | |
| | | | |
| | | | |
| | Default | 1 | |
| | | | |
| | OK (O) Cancel | | |

- · Check with a network administrator about IP address. Do not set the duplicate IP address.
- Set IP address on the External Device address in the [Individual Device Settings] dialog box.
- You need to set IP address on the Display in the offline mode of the Display.

Use the ladder software (MP720 Ver.7) to set up communication settings. Set the next contents. (1) Main CPU settings

(2) Remote I/O settings

For details on communication settings, please refer to the manual of the External Device.

Main CPU Settings

- 1 Start the ladder software.
- **2** Make a project file. From the [Model] list, select the main CPU.
- **3** From the [Start] tab, click [Module Configuration].

[MC-Configurator] starts up.

- 4 On the CPU you want to use, double-click [218IFD].
- **5** Click the [Parameters] tab.
- 6 In the [Transmission Parameters] group define the [IP Address] and [Subnet Mask] as follows.

| Setup Items | Setup Description |
|-------------|-------------------|
| IP Address | 192.168.0.1 |
| Subnet Mask | 255.255.255.0 |

7 On the CPU you want to use, set the [SVC32] circuit number to "1".

Set up the same value as the Display's circuit number.

- **8** On the CPU you want to use, open [SVC32], and double-click [01 UNDEFINED].
- 9 In the tree view, from [I/O]-[Other], select [WILDCARD I/O], and click [OK].
- 10 For the [WILDCARD I/O] station number, set "3".
- **11** Write the settings to the External Device.

To write the settings, select the [Save to flash after transferring to the controller] check box.
 If the data is transferred without selecting the check box, the transferred data is deleted when restarting the External Device.

Remote I/O Settings

Set up communication settings with rotary switches (S1 and S2). For details on communication settings, please refer to the manual of the External Device.

| Rotary Switch | Settings | Setup Description |
|---------------|----------|-------------------|
| S1 (x16) | 0 | Station address |
| S2 (x1) | 3 | |

Notes

3.26 Setting Example 26

- Settings of GP-Pro EX
- Communication Settings

To display the setup screen, from the [Project] menu, point to [System Settings] and select [Device/PLC].

| Device/PLC 1 | | |
|-------------------------------------|---|--------------------|
| Summary | | Change Device/PLC |
| Manufacturer YASK | AWA Electric Corporation Series MP Ethemet/MECHATROLINK | Port Ethemet (UDP) |
| Text Data Mode | 1 Change | |
| Communication Setting | s | |
| Port No. | 1024 🖉 Auto | |
| Timeout | 3 | |
| Retry | 2 🔅 | |
| Wait To Send | 0 (ms) Default | |
| Device-Specific Setting | js | |
| Allowable Number of Devices/PLCs | Add Device Increase Allowable 32 Number of Devices/PLCs | Add Indirect |
| No. Device Name | Settings | Device |
| 👗 1 PLC1 | Series=R7G4HML3-LC2(M-III),IP Address=192.168.00 | F . |

Device Setting

To display the [Individual Device Settings] dialog box, from [Device-Specific Settings] in the [Device/PLC] window, select the External Device and click [Settings] III. To connect multiple External Devices, from [Device-Specific Settings] in the [Device/PLC] window, click [Add Device] to add another External Device.

| 🎒 Individual De | evice Settings X |
|--|---|
| PLC1 | |
| Product | I/O(M-System) |
| Series | R7G4HML3-LC2(M-III) |
| If you change the address settings. | product or series, please reconfirm all |
| Station Address(| I/O) <u>3</u> |
| Relay Control | er Setting |
| IP Addres | s 192. 168. 0. 1 |
| D | evice Type Circuit No. |
| 1 MPU-01 | 3 |
| 2 MECHAT | ROLINK 🗾 1 🚍 |
| | |
| | Default |
| | OK (O) Cancel |

- Check with a network administrator about IP address. Do not set the duplicate IP address.
- Set IP address on the External Device address in the [Individual Device Settings] dialog box.
- You need to set IP address on the Display in the offline mode of the Display.

Use the ladder software (MP720 Ver.7) to set up communication settings. Set the next contents. (1) Main CPU settings

- (2) MPU-01 settings
- (3) Remote I/O settings

For details on communication settings, please refer to the manual of the External Device.

Main CPU Settings

- 1 Start the ladder software.
- **2** Make a project file. From the [Model] list, select the main CPU.
- **3** From the [Start] tab, click [Module Configuration].

[MC-Configurator] starts up.

- 4 On the CPU you want to use, double-click [218IFD].
- **5** Click the [Parameters] tab.
- **6** In the [Transmission Parameters] group define the [IP Address] and [Subnet Mask] as follows.

| Setup Items | Setup Description |
|-------------|-------------------|
| IP Address | 192.168.0.1 |
| Subnet Mask | 255.255.255.0 |

- 7 Double-click the module number associated with the option slot attached to MPU-01 in the [MC-Configurator].
- 8 In the [Module] dialog box, select [MPU-01] and click [OK].
- **9** In the [MC-Configurator], set [MPU-01]'s circuit number to "3".

Set up the same value as the Display's circuit number.

10 Write the settings to the External Device.

IMPORTANT
 To write the settings, select the [Save to flash after transferring to the controller] check box.
 If the data is transferred without selecting the check box, the transferred data is deleted when restarting the External Device.

♦ MPU-01 Settings

- 1 Start the ladder software.
- 2 Make a project file. Select "MPU-01" from [Model].
- **3** From the tree view, click [Module Configuration]. [MC-Configurator] starts.
- 4 Expand [SVC] of [MPU-01] module, and double-click [01 UNDEFINED].
- 5 Select the using Remote I/O of [Slave] dialog box, and click [OK].
- 6 Set "1" to the circuit number of [SVC].
- 7 Set "3" to the station address of the added Remote I/O.

8 Write the settings to the MPU-01 series.

IMPORTANT • To write the settings, select the [Save to flash after transferring to the controller] check box.

If the data is transferred without selecting the check box, the transferred data is deleted when restarting the External Device.

Remote I/O Settings

Set up communication settings with rotary switches (S1 and S2). For details on communication settings, please refer to the manual of the External Device.

| Rotary Switch | Settings | Setup Description |
|---------------|----------|-------------------|
| S1 (x16) | 0 | Station address |
| S2 (x1) | 3 | |

Notes

3.27 Setting Example 27

Settings of GP-Pro EX

Communication Settings

To display the setup screen, from the [Project] menu, point to [System Settings] and select [Device/PLC].

| Device/PLC 1 | | |
|--|---|--------------------|
| Summary | | Change Device/PLC |
| Manufacturer YASKAW | A Electric Corporation Series MP Ethemet/MECHATROLINK | Port Ethemet (UDP) |
| Text Data Mode | 1 Change | |
| Communication Settings | | |
| Port No. | 1024 🖉 Auto | |
| Timeout | 3 (sec) | |
| Retry | 2 * | |
| Wait To Send | 0 (ms) Default | |
| Device-Specific Settings | | |
| Allowable Number of Devices/PLCs 32 | 2 Add Device Increase Allowable Number of Devices/PLCs | Add Indirect |
| No. Device Name | Settings | Device |
| 👗 1 PLC1 | Series=R7G4HML3-LC2(M-III),IP Address=192.168.00 | - |

Device Setting

To display the [Individual Device Settings] dialog box, from [Device-Specific Settings] in the [Device/PLC] window, select the External Device and click [Settings] III. To connect multiple External Devices, from [Device-Specific Settings] in the [Device/PLC] window, click [Add Device] to add another External Device.

| <i>拳</i> Individual De | vice Settings X | | |
|--|---|--|--|
| PLC1 | | | |
| Product | I/O(M-System) | | |
| Series | R7G4HML3-LC2(M-Ⅲ) ▼ | | |
| If you change the p address settings. | product or series, please reconfirm all | | |
| Station Address(I | /0) 3 🗄 | | |
| Relay Controle | r Setting | | |
| IP Addres | s 192. 168. 0. 1 | | |
| De | evice Type Circuit No. | | |
| 1 Sub CPU | 5 芸 | | |
| 2 MECHAT | ROLINK 🔽 1 🗮 | | |
| | | | |
| | Default | | |
| | OK (0) Cancel | | |

- Check with a network administrator about IP address. Do not set the duplicate IP address.
- Set IP address on the External Device address in the [Individual Device Settings] dialog box.
- You need to set IP address on the Display in the offline mode of the Display.

Use the ladder software (MP720 Ver.7) to set up communication settings. Set the next contents. (1) Main CPU settings

- (2) MPU-01 settings
- (3) Remote I/O settings

For details on communication settings, please refer to the manual of the External Device.

Main CPU Settings

- 1 Start the ladder software.
- **2** Make a project file. From the [Model] list, select the main CPU.
- **3** From the [Start] tab, click [Module Configuration].

[MC-Configurator] starts up.

- 4 On the CPU you want to use, double-click [218IFD].
- **5** Click the [Parameters] tab.
- 6 In the [Transmission Parameters] group define the [IP Address] and [Subnet Mask] as follows.

| Setup Items | Setup Description |
|-------------|-------------------|
| IP Address | 192.168.0.1 |
| Subnet Mask | 255.255.255.0 |

- 7 Double-click the module number attached to the sub CPU in the [MC-Configurator].
- 8 In the [Module] dialog box, select the sub CPU in use and click [OK].
- **9** In the [MC-Configurator], set the sub CPU circuit number to "5".

Set up the same value as the Display's circuit number.

10 Write the settings to the External Device.

IMPORTANT
 To write the settings, select the [Save to flash after transferring to the controller] check box.
 If the data is transferred without selecting the check box, the transferred data is deleted when restarting the External Device.

- ♦ Sub CPU Settings
- 1 Start the ladder software.
- **2** Make a project file. Select a Sub CPU to be used from [Model].
- **3** From the tree view, click [Module Configuration]. [MC-Configurator] starts.
- **4** Expand [SVC] of Sub CPU, and double-click [01 UNDEFINED].
- 5 Select the using Remote I/O of [Slave] dialog box, and click [OK].
- 6 Set "1" to the circuit number of [SVC].
- 7 Set "3" to the station address of the added Remote I/O.

8 Write the settings to the Sub CPU.

IMPORTANT • To write the settings, select the [Save to flash after transferring to the controller] check box.

If the data is transferred without selecting the check box, the transferred data is deleted when restarting the External Device.

Remote I/O Settings

Set up communication settings with rotary switches (S1 and S2). For details on communication settings, please refer to the manual of the External Device.

| Rotary Switch | Settings | Setup Description |
|---------------|----------|-------------------|
| S1 (x16) | 0 | Station address |
| S2 (x1) | 3 | |

Notes

3.28 Setting Example 28

- Settings of GP-Pro EX
- Communication Settings

To display the setup screen, from the [Project] menu, point to [System Settings] and select [Device/PLC].

| Device/PLC 1 |
|--|
| Summary Change Device/PLC |
| Manufacturer YASKAWA Electric Corporation Series MP Ethemet/MECHATROLINK Port Ethemet (UDP) |
| Text Data Mode 1 Change |
| Communication Settings |
| Port No. 1024 😴 🗹 Auto |
| Timeout 3 😴 (sec) |
| Retry 2 |
| Wait To Send 0 🔆 (ms) Default |
| Device-Specific Settings |
| Allowable Number Add Device Increase Allowable of Devices/PLCs 32 Number of Devices/PLCs |
| No. Device Name Settings Add Indirect |
| 1 PLC1 Image: Series=K1G(M-III).IP Address=192.168.000.001,Station Image: Series=K1G(M-III).IP Address=192.168.000.001,Station |
| |
| |
| MPORTANT • To connect Remote I/O Series using a 1:n connection, [Wait To Send] mus |
| 100ms or more. |

Device Setting

To display the [Individual Device Settings] dialog box, from [Device-Specific Settings] in the [Device/PLC] window, select the External Device and click [Settings] III. To connect multiple External Devices, from [Device-Specific Settings] in the [Device/PLC] window, click [Add Device] to add another External Device.

| 🎒 Individual De | vice Settings X |
|-------------------------------------|---|
| PLC1 | |
| Product | I/O(Azbil) |
| Series | К1G(M-Ш) |
| If you change the address settings. | product or series, please reconfirm all |
| Station Address(L/ | (O) 3 🗮 |
| Relay Controle | r Setting |
| IP Address | s <u>192. 168. 0. 1</u> |
| De | vice Type Circuit No. |
| 1 MECHATE | ROLINK 🔽 1 🗮 |
| | |
| | |
| | Default |
| | OK (O) Cancel |

- · Check with a network administrator about IP address. Do not set the duplicate IP address.
- Set IP address on the External Device address in the [Individual Device Settings] dialog box.
- You need to set IP address on the Display in the offline mode of the Display.

Use the ladder software (MP720 Ver.7) to set up communication settings. Set the next contents. (1) Main CPU settings

(2) Controller settings

For details on communication settings, please refer to the manual of the External Device.

Main CPU Settings

- 1 Start the ladder software.
- **2** Make a project file. From the [Model] list, select the main CPU.
- **3** From the [Start] tab, click [Module Configuration].

[MC-Configurator] starts up.

- 4 On the CPU you want to use, double-click [218IFD].
- **5** Click the [Parameters] tab.
- 6 In the [Transmission Parameters] group define the [IP Address] and [Subnet Mask] as follows.

| Setup Items | Setup Description |
|-------------|-------------------|
| IP Address | 192.168.0.1 |
| Subnet Mask | 255.255.255.0 |

7 On the CPU you want to use, set the [SVC32] circuit number to "1".

Set up the same value as the Display's circuit number.

- **8** On the CPU you want to use, open [SVC32], and double-click [01 UNDEFINED].
- 9 In the tree view, from [I/O]-[Other], select [WILDCARD I/O], and click [OK].
- 10 For the [WILDCARD I/O] station number, set "3".
- **11** Write the settings to the External Device.

IMPORTANT • To write the settings, select the [Save to flash after transferring to the controller] check box.

If the data is transferred without selecting the check box, the transferred data is deleted when restarting the External Device.

Controller Settings

To configure communication settings for the External Device, use the CPU unit's Run, para, enter and cursor keys. Refer to your External Device manual for details.

Procedure

- 1 When [Run] is lit, press and hold the Run key for 3 seconds.
- **2** Press the para key to display parameters.
- $\mathbf{3}$ Use the up/down cursor keys to display the setup items. (Setup items will blink.)
- **4** Press the enter key to select a setup item.
- 5 Select the settings with the cursor keys. (Settings will blink.)
- 6 Press the enter key to confirm the settings.
- 7 Press the Run key, and [Run] is lit.

Settings

| Setup Items | Settings | Setup Description | |
|-------------|----------|----------------------------------|--|
| A09 | 3 | MECHATROLINK-III station address | |

Notes

3.29 Setting Example 29

- Settings of GP-Pro EX
- Communication Settings

To display the setup screen, from the [Project] menu, point to [System Settings] and select [Device/PLC].

| Device/PLC 1 | | |
|-------------------------------------|--|--------------------|
| Summary | | Change Device/PLC |
| Manufacturer YASK | AWA Electric Corporation Series MP Ethemet/MECHATROLINK | Port Ethemet (UDP) |
| Text Data Mode | 1 Change | |
| Communication Setting | 5 | |
| Port No. | 1024 🗾 🖌 Auto | |
| Timeout | 3 (sec) | |
| Retry | 2 * | |
| Wait To Send | 0 (ms) Default | |
| Device-Specific Setting | s | |
| Allowable Number of Devices/PLCs | 32 Add Device Increase Allowable Number of Devices/PLCs | Add Indirect |
| No. Device Name | Settings | Device |
| 👗 1 PLC1 | Series=K1G(M-III),IP Address=192.168.000.001,Station | ; |

Device Setting

To display the [Individual Device Settings] dialog box, from [Device-Specific Settings] in the [Device/PLC] window, select the External Device and click [Settings] I. To connect multiple External Devices, from [Device-Specific Settings] in the [Device/PLC] window, click [Add Device] to add another External Device.

| 🚰 Individual Device Settings 🛛 🔀 | | | |
|---|------------------------|--|--|
| PLC1 | | | |
| Product | I/O(Azbil) | | |
| Series | К1G(M-Ш) | | |
| If you change the product or series, please reconfirm all address settings. | | | |
| Station Address(I/O) 3 | | | |
| Relay Controler Setting | | | |
| IP Addres | s 192. 168. 0. 1 | | |
| D | evice Type Circuit No. | | |
| 1 MPU-01 | 3 | | |
| 2 MECHAT | ROLINK 🗾 1 🚍 | | |
| | | | |
| | Default | | |
| | | | |
| | OK (O) Cancel | | |

- Check with a network administrator about IP address. Do not set the duplicate IP address.
- Set IP address on the External Device address in the [Individual Device Settings] dialog box.
- You need to set IP address on the Display in the offline mode of the Display.

Use the ladder software (MP720 Ver.7) to set up communication settings. Set the next contents. (1) Main CPU settings

- (2) MPU-01 settings
- (3) Controller settings

For details on communication settings, please refer to the manual of the External Device.

Main CPU Settings

- 1 Start the ladder software.
- **2** Make a project file. From the [Model] list, select the main CPU.
- **3** From the [Start] tab, click [Module Configuration].

[MC-Configurator] starts up.

- 4 On the CPU you want to use, double-click [218IFD].
- 5 Click the [Parameters] tab.
- **6** In the [Transmission Parameters] group define the [IP Address] and [Subnet Mask] as follows.

| Setup Items | Setup Description |
|-------------|-------------------|
| IP Address | 192.168.0.1 |
| Subnet Mask | 255.255.255.0 |

- 7 Double-click the module number associated with the option slot attached to MPU-01 in the [MC-Configurator].
- **8** In the [Module] dialog box, select [MPU-01] and click [OK].
- **9** In the [MC-Configurator], set [MPU-01]'s circuit number to "3".

Set up the same value as the Display's circuit number.

10 Write the settings to the External Device.

IMPORTANT
 To write the settings, select the [Save to flash after transferring to the controller] check box.
 If the data is transferred without selecting the check box, the transferred data is deleted when restarting the External Device.

- ♦ MPU-01 Settings
- 1 Start the ladder software.
- 2 Make a project file. Select "MPU-01" from [Model].
- **3** From the tree view, click [Module Configuration]. [MC-Configurator] starts.
- 4 Expand [SVC] of [MPU-01] module, and double-click [01 UNDEFINED].
- 5 Select the using Controller of [Slave] dialog box, and click [OK].
- 6 Set "1" to the circuit number of [SVC].
- 7 Set "3" to the station address of the added Controller.

- **8** Write the settings to the MPU-01 series.
 - IMPORTANT To write the settings, select the [Save to flash after transferring to the controller] check box.

If the data is transferred without selecting the check box, the transferred data is deleted when restarting the External Device.

Controller Settings

To configure communication settings for the External Device, use the CPU unit's Run, para, enter and cursor keys. Refer to your External Device manual for details.

Procedure

- 1 When [Run] is lit, press and hold the Run key for 3 seconds.
- **2** Press the para key to display parameters.
- $\mathbf{3}$ Use the up/down cursor keys to display the setup items. (Setup items will blink.)
- **4** Press the enter key to select a setup item.
- 5 Select the settings with the cursor keys. (Settings will blink.)
- 6 Press the enter key to confirm the settings.
- 7 Press the Run key, and [Run] is lit.

Settings

| Setup Items | Settings | Setup Description |
|-------------|------------------------------------|-------------------|
| A09 | 3 MECHATROLINK-III station address | |

Notes

3.30 Setting Example 30

Settings of GP-Pro EX

Communication Settings

To display the setup screen, from the [Project] menu, point to [System Settings] and select [Device/PLC].

| Device/PLC 1 | | |
|-------------------------------------|---|--------------------|
| Summary | | Change Device/PLC |
| Manufacturer YASKA | WA Electric Corporation Series MP Ethemet/MECHATROLINK | Port Ethemet (UDP) |
| Text Data Mode | 1 Change | |
| Communication Settings | | |
| Port No. | 1024 🗾 Auto | |
| Timeout | 3 (sec) | |
| Retry | 2 🛨 | |
| Wait To Send | 0 (ms) Default | |
| Device-Specific Settings | | |
| Allowable Number of Devices/PLCs | Add Device Increase Allowable 32 Number of Devices/PLCs | Add Indirect |
| No. Device Name | Settings | Device |
| 👗 1 PLC1 | Series=K1G(M-III),IP Address=192.168.000.001,Station | . |

Device Setting

To display the [Individual Device Settings] dialog box, from [Device-Specific Settings] in the [Device/PLC] window, select the External Device and click [Settings] III. To connect multiple External Devices, from [Device-Specific Settings] in the [Device/PLC] window, click [Add Device] to add another External Device.

| 🎒 Individual D | evice Settings X |
|---------------------------------------|---|
| PLC1 | |
| Product | I/O(Azbil) |
| Series | K1G(M-III) |
| If you change the address settings | e product or series, please reconfirm all |
| Station Address(| VO) <u>3</u> |
| Relay Control | er Setting |
| IP Addre: | ss 192. 168. 0. 1 |
| C | Device Type Circuit No. |
| 1 Sub CPL | 5 📑 |
| 2 MECHAT | FROLINK 💌 1 🗮 |
| | |
| | Default |
| | |
| | OK (O) Cancel |

- · Check with a network administrator about IP address. Do not set the duplicate IP address.
- Set IP address on the External Device address in the [Individual Device Settings] dialog box.
- You need to set IP address on the Display in the offline mode of the Display.

Use the ladder software (MP720 Ver.7) to set up communication settings. Set the next contents. (1) Main CPU settings

- (2) Sub CPU settings
- (3) Controller settings

For details on communication settings, please refer to the manual of the External Device.

Main CPU Settings

- 1 Start the ladder software.
- **2** Make a project file. From the [Model] list, select the main CPU.
- **3** From the [Start] tab, click [Module Configuration].

[MC-Configurator] starts up.

- 4 On the CPU you want to use, double-click [218IFD].
- **5** Click the [Parameters] tab.
- **6** In the [Transmission Parameters] group define the [IP Address] and [Subnet Mask] as follows.

| Setup Items | Setup Description |
|-------------|-------------------|
| IP Address | 192.168.0.1 |
| Subnet Mask | 255.255.255.0 |

- 7 Double-click the module number attached to the sub CPU in the [MC-Configurator].
- 8 In the [Module] dialog box, select the sub CPU in use and click [OK].
- **9** In the [MC-Configurator], set the sub CPU circuit number to "5".

Set up the same value as the Display's circuit number.

10 Write the settings to the External Device.

IMPORTANT
 To write the settings, select the [Save to flash after transferring to the controller] check box.
 If the data is transferred without selecting the check box, the transferred data is deleted when restarting the External Device.

- ♦ Sub CPU Settings
- 1 Start the ladder software.
- **2** Make a project file. Select a Sub CPU to be used from [Model].
- **3** From the tree view, click [Module Configuration]. [MC-Configurator] starts.
- 4 Expand [SVC] of Sub CPU, and double-click [01 UNDEFINED].
- 5 Select the using Controller of [Slave] dialog box, and click [OK].
- 6 Set "1" to the circuit number of [SVC].
- 7 Set "3" to the station address of the added Controller.

8 Write the settings to the Sub CPU.

IMPORTANT

• To write the settings, select the [Save to flash after transferring to the controller] check box.

If the data is transferred without selecting the check box, the transferred data is deleted when restarting the External Device.

Controller Settings

To configure communication settings for the External Device, use the CPU unit's Run, para, enter and cursor keys. Refer to your External Device manual for details.

Procedure

- **1** When [Run] is lit, press and hold the Run key for 3 seconds.
- **2** Press the para key to display parameters.
- **3** Use the up/down cursor keys to display the setup items. (Setup items will blink.)
- **4** Press the enter key to select a setup item.
- 5 Select the settings with the cursor keys. (Settings will blink.)
- 6 Press the enter key to confirm the settings.
- 7 Press the Run key, and [Run] is lit.

Settings

| Setup Items | Settings | Setup Description |
|-------------|----------|----------------------------------|
| A09 | 3 | MECHATROLINK-III station address |

Notes

3.31 Setting Example 31

Settings of GP-Pro EX

Communication Settings

To display the setup screen, from the [Project] menu, point to [System Settings] and select [Device/PLC].

| Device/PLC 1 | |
|---|----------------------------|
| Summary | Change Device/PLC |
| Manufacturer YASKAWA Electric Corporation Series MP Ethemet/MECHATROLINK | Port Ethemet (UDP) |
| Text Data Mode 1 Change | |
| Communication Settings | |
| Port No. 1024 📑 🔽 Auto | |
| Timeout 3 🔆 (sec) | |
| Retry 2 | |
| Wait To Send 0 📑 (ms) Default | |
| Device-Specific Settings | |
| Allowable Number Add Device Increase Allowable of Devices/PLCs 32 Number of Devices/PLCs | |
| No. Device Name Settings | Add Indirect Device |
| 1 PLC1 III Series=AZ Series Multi-Axis Driver(M-III),IP Address=15 | 1 |
| | |
| IMPORTANT • To connect AZ Series using a 1:n connection, [W | ait To SendI must be 100ms |
| | |

Device Setting

more.

To display the [Individual Device Settings] dialog box, from [Device-Specific Settings] in the [Device/PLC] window, select the External Device and click [Settings] I. To connect multiple External Devices, from [Device-Specific Settings] in the [Device/PLC] window, click [Add Device] to add another External Device.

| 🎒 Individual De | vice Settings | |
|--|---|--|
| PLC1 | | |
| Product | Stepping(Orientalmotor) | |
| Series | AZ Series Multi-Axis Driver(M-III) | |
| If you change the address settings. | product or series, please reconfirm all | |
| Station Address(S | tepping) 3 🔆 Axis No. 1 🔅 | |
| Relay Controle | r Setting | |
| IP Address | s 192. 168. 0. 1 | |
| De | evice Type Circuit No. | |
| 1 MECHATI | ROLINK 🔽 1 🗮 | |
| | | |
| | | |
| | Default | |
| | OK (0) Cancel | |

- Check with a network administrator about IP address. Do not set the duplicate IP address.
- Set IP address on the External Device address in the [Individual Device Settings] dialog box.
- You need to set IP address on the Display in the offline mode of the Display.

Use the ladder software (MP720 Ver.7.33.0100) to set up communication settings. Set the next contents. (1) Main CPU settings

(2) Stepping motor settings

For details on communication settings, please refer to the manual of the External Device.

Main CPU Settings

- 1 Start the ladder software.
- **2** Make a project file. From the [Model] list, select the main CPU.
- **3** From the [Start] tab, click [Module Configuration].

[MC-Configurator] starts up.

- **4** On the CPU you want to use, double-click [218IFD].
- 5 Click the [Parameters] tab.
- 6 In the [Transmission Parameters] group define the [IP Address] and [Subnet Mask] as follows.

| Setup Items | Setup Description |
|-------------|-------------------|
| IP Address | 192.168.0.1 |
| Subnet Mask | 255.255.255.0 |

7 On the CPU you want to use, set the [SVC32] circuit number to "1".

Set up the same value as the Display's circuit number.

- $\boldsymbol{8}$ On the CPU you want to use, open [SVC32], and double-click [01 UNDEFINED].
- 9 In the tree view, from [Stepping], select [Wild Card SteppingMotorDRV], and click [OK].
- 10 For the [Wild Card SteppingMotorDRV] station number, set "3".
- **11** Write the settings to the External Device.

IMPORTANT • To write the settings, select the [Save to flash after transferring to the controller] check box. If the data is transferred without selecting the check box, the transferred data is deleted when restarting the External Device.

Stepping Motor Settings

Set up communication settings with rotary switches (S1 and S2). For details on communication settings, please refer to the manual of the External Device.

| Rotary Switch | Settings | Setup Description |
|---------------|----------|-------------------|
| S1 (x10) | 0 | Station address |
| S2 (x1) | 3 | |

Notes

3.32 Setting Example 32

- Settings of GP-Pro EX
- Communication Settings

To display the setup screen, from the [Project] menu, point to [System Settings] and select [Device/PLC].

| Device/PLC 1 |
|--|
| Summary Change Device/PLC |
| Manufacturer YASKAWA Electric Corporation Series MP Ethemet/MECHATROLINK Port Ethemet (UDP) |
| Text Data Mode 1 Change |
| Communication Settings |
| Port No. 1024 😴 🔽 Auto |
| Timeout 3 (sec) |
| Retry 2 |
| Wait To Send 0 (ms) Default |
| Device-Specific Settings |
| Allowable Number Add Device Increase Allowable of Devices/PLCs 32 Number of Devices/PLCs Add Indirect |
| No. Device Name Settings Device |
| 1 PLC1 Im Series=AZ Series Multi-Axis Driver(M-III),IP Address=15 |

Device Setting

To display the [Individual Device Settings] dialog box, from [Device-Specific Settings] in the [Device/PLC] window, select the External Device and click [Settings] I. To connect multiple External Devices, from [Device-Specific Settings] in the [Device/PLC] window, click [Add Device] to add another External Device.

| 🎒 Individual De | vice Settings | × | |
|-------------------------------------|-------------------------------|------------|--|
| PLC1 | | | |
| Product | t Stepping(Orientalmotor) | | |
| Series | AZ Series Multi-Axis Driver | (M-III) | |
| If you change the address settings. | product or series, please rec | onfirm all | |
| Station Address(S | itepping) 👔 🔆 Axi | is No. 1 | |
| Relay Controle | r Setting | | |
| IP Addres | s 192. 168. O. | 1 | |
| De | evice Type Cir | cuit No. | |
| 1 MPU-01 | ▼ 3 | | |
| 2 MECHAT | ROLINK 🔽 1 | | |
| | | | |
| | | Default | |
| | | | |
| | OK (0) | Cancel | |

- Check with a network administrator about IP address. Do not set the duplicate IP address.
- Set IP address on the External Device address in the [Individual Device Settings] dialog box.
- You need to set IP address on the Display in the offline mode of the Display.

Use the ladder software (MP720 Ver.7) to set up communication settings. Set the next contents. (1) Main CPU settings

- (2) MPU-01 settings
- (3) Stepping motor settings

For details on communication settings, please refer to the manual of the External Device.

Main CPU Settings

- 1 Start the ladder software.
- **2** Make a project file. From the [Model] list, select the main CPU.
- **3** From the [Start] tab, click [Module Configuration]. [MC-Configurator] starts up.
- 4 On the CPU you want to use, double-click [218IFD].
- **5** Click the [Parameters] tab.
- 6 In the [Transmission Parameters] group define the [IP Address] and [Subnet Mask] as follows.

| Setup Items | Setup Description |
|-------------|-------------------|
| IP Address | 192.168.0.1 |
| Subnet Mask | 255.255.255.0 |

- 7 Double-click the module number associated with the option slot attached to MPU-01 in the [MC-Configurator].
- **8** In the [Module] dialog box, select [MPU-01] and click [OK].
- **9** In the [MC-Configurator], set [MPU-01]'s circuit number to "3".

Set up the same value as the Display's circuit number.

10 Write the settings to the External Device.

IMPORTANT
 To write the settings, select the [Save to flash after transferring to the controller] check box.
 If the data is transferred without selecting the check box, the transferred data is deleted when restarting the External Device.

- ♦ MPU-01 Settings
- 1 Start the ladder software.
- **2** Make a project file. Select "MPU-01" from [Model].
- **3** From the tree view, click [Module Configuration]. [MC-Configurator] starts.
- 4 Expand [SVC] of [MPU-01] module, and double-click [01 UNDEFINED].
- 5 In the tree view of [Slave] dialog box, from [Stepping], select [Wild Card SteppingMotorDRV], and click [OK].
- 6 Set "1" to the circuit number of [SVC].
- 7 Set "3" to the station address of the added Wild Card SteppingMotorDRV.

8 Write the settings to the MPU-01 series.

IMPORTANT • To write the settings, select the [Save to flash after transferring to the controller] check box.

If the data is transferred without selecting the check box, the transferred data is deleted when restarting the External Device.

Stepping Motor Settings

Set up communication settings with rotary switches (S1 and S2). For details on communication settings, please refer to the manual of the External Device.

| Rotary Switch | Settings | Setup Description |
|---------------|----------|-------------------|
| S1 (x10) | 0 | Station address |
| S2 (x1) | 3 | |

Notes

3.33 Setting Example 33

Settings of GP-Pro EX

Communication Settings

To display the setup screen, from the [Project] menu, point to [System Settings] and select [Device/PLC].

| Device/PLC 1 |
|--|
| Summary Change Device/PLC |
| Manufacturer YASKAWA Electric Corporation Series MP Ethemet/MECHATROLINK Port Ethemet (UDP) |
| Text Data Mode 1 Change |
| Communication Settings |
| Port No. 1024 😴 🔽 Auto |
| Timeout 3 (sec) |
| Retry 2 |
| Wait To Send 0 (ms) Default |
| Device-Specific Settings |
| Allowable Number Add Device Increase Allowable of Devices/PLCs 32 Number of Devices/PLCs Add Indirect |
| No. Device Name Settings Device |
| 1 PLC1 Im Series=AZ Series Multi-Axis Driver(M-III),IP Address=15 |

Device Setting

To display the [Individual Device Settings] dialog box, from [Device-Specific Settings] in the [Device/PLC] window, select the External Device and click [Settings] I. To connect multiple External Devices, from [Device-Specific Settings] in the [Device/PLC] window, click [Add Device] to add another External Device.

| 🎒 Individual De | evice Settings | x |
|--|---|---|
| PLC1 | | |
| Product Stepping(Orientalmotor) | | |
| Series | AZ Series Multi-Axis Driver(M-III) | • |
| If you change the address settings. | product or series, please reconfirm all | |
| Station Address(S | Stepping) 🛛 📑 Axis No. 📋 | |
| Relay Controle | er Setting | |
| IP Addres | s 192. 168. 0. 1 | |
| De | evice Type Circuit No. | |
| 1 Sub CPU | 5 🗮 | |
| 2 MECHAT | ROLINK 🔽 1 🗮 | |
| | | |
| | Defaul | t |
| | | _ |
| | OK (0) Cancel | |

- · Check with a network administrator about IP address. Do not set the duplicate IP address.
- Set IP address on the External Device address in the [Individual Device Settings] dialog box.
- You need to set IP address on the Display in the offline mode of the Display.

Use the ladder software (MP720 Ver.7) to set up communication settings. Set the next contents. (1) Main CPU settings

- (2) Sub CPU settings
- (3) Stepping motor settings

For details on communication settings, please refer to the manual of the External Device.

Main CPU Settings

- 1 Start the ladder software.
- **2** Make a project file. From the [Model] list, select the main CPU.
- **3** From the [Start] tab, click [Module Configuration]. [MC-Configurator] starts up.
- 4 On the CPU you want to use, double-click [218IFD].
- **5** Click the [Parameters] tab.
- 6 In the [Transmission Parameters] group define the [IP Address] and [Subnet Mask] as follows.

| Setup Items | Setup Description |
|-------------|-------------------|
| IP Address | 192.168.0.1 |
| Subnet Mask | 255.255.255.0 |

- 7 Double-click the module number attached to the sub CPU in the [MC-Configurator].
- **8** In the [Module] dialog box, select the sub CPU in use and click [OK].
- **9** In the [MC-Configurator], set the sub CPU circuit number to "5".

Set up the same value as the Display's circuit number.

10 Write the settings to the External Device.

IMPORTANT
 To write the settings, select the [Save to flash after transferring to the controller] check box.
 If the data is transferred without selecting the check box, the transferred data is deleted when restarting the External Device.

- Sub CPU Settings
- 1 Start the ladder software.
- **2** Make a project file. Select a Sub CPU to be used from [Model].
- **3** From the tree view, click [Module Configuration]. [MC-Configurator] starts.
- 4 Expand [SVC] of Sub CPU, and double-click [01 UNDEFINED].
- 5 In the tree view of [Slave] dialog box, from [Stepping], select [Wild Card SteppingMotorDRV], and click [OK].
- 6 Set "1" to the circuit number of [SVC].
- 7 Set "3" to the station address of the added Wild Card SteppingMotorDRV.

8 Write the settings to the Sub CPU.

IMPORTANT • To write the settings, select the [Save to flash after transferring to the controller] check box.

If the data is transferred without selecting the check box, the transferred data is deleted when restarting the External Device.

Stepping Motor Settings

Set up communication settings with rotary switches (S1 and S2). For details on communication settings, please refer to the manual of the External Device.

| Rotary Switch | Settings | Setup Description |
|---------------|----------|-------------------|
| S1 (x10) | 0 | Station address |
| S2 (x1) | 3 | |

Notes

3.34 Setting Example 34

Settings of GP-Pro EX

Communication Settings

To display the setup screen, from the [Project] menu, point to [System Settings] and select [Device/PLC].

| Device/PLC 1 | |
|---|------------------------|
| Summary | Change Device/PLC |
| Manufacturer YASKAWA Electric Corporation Series MP Ethemet/MECHATROLINK | Port Ethemet (UDP) |
| Text Data Mode 1 Change | |
| Communication Settings | |
| Port No. 1024 🖉 Auto | |
| Timeout 3 🙁 (sec) | |
| Retry 2 | |
| Wait To Send 0 (ms) Default | |
| Device-Specific Settings | |
| Allowable Number <u>Add Device</u> Increase Allowable of Devices/PLCs 32 <u>Number of Devices/PLCs</u> | Add Indirect |
| No. Device Name Settings | Device |
| 1 PLC1 Series=R7G4HML3-STYVS1(M-III),IP Address=192.16 | . |
| | |
| | |
| • To connect Remote I/O Series using a 1:n connecti | on, [vvait to Send] mu |
| 100ms or more. | |

Device Setting

To display the [Individual Device Settings] dialog box, from [Device-Specific Settings] in the [Device/PLC] window, select the External Device and click [Settings] III. To connect multiple External Devices, from [Device-Specific Settings] in the [Device/PLC] window, click [Add Device] to add another External Device.

| 🎒 Individual De | vice Settings | < | |
|-------------------------------------|---|---|--|
| PLC1 | | | |
| Product | I/O(M-System) | | |
| Series | R7G4HML3-STYVS1(M-III) |] | |
| If you change the address settings. | product or series, please reconfirm all | | |
| Station Address(I | /0) 3 🗄 | | |
| Relay Controle | r Setting | | |
| IP Addres | s 192. 168. 0. 1 | | |
| De | evice Type Circuit No. | | |
| 1 MECHAT | ROLINK 🔽 1 🚍 | | |
| | | | |
| | | | |
| | Default | | |
| | OK (0) Cancel | | |

- · Check with a network administrator about IP address. Do not set the duplicate IP address.
- Set IP address on the External Device address in the [Individual Device Settings] dialog box.
- You need to set IP address on the Display in the offline mode of the Display.

Use the ladder software (MP720 Ver.7) to set up communication settings. Set the next contents. (1) Main CPU settings

(2) Remote I/O settings

For details on communication settings, please refer to the manual of the External Device.

Main CPU Settings

- 1 Start the ladder software.
- **2** Make a project file. From the [Model] list, select the main CPU.
- **3** From the [Start] tab, click [Module Configuration].

[MC-Configurator] starts up.

- **4** On the CPU you want to use, double-click [218IFD].
- 5 Click the [Parameters] tab.
- 6 In the [Transmission Parameters] group define the [IP Address] and [Subnet Mask] as follows.

| Setup Items | Setup Description |
|-------------|-------------------|
| IP Address | 192.168.0.1 |
| Subnet Mask | 255.255.255.0 |

7 On the CPU you want to use, set the [SVC32] circuit number to "1".

Set up the same value as the Display's circuit number.

- **8** On the CPU you want to use, open [SVC32], and double-click [01 UNDEFINED].
- 9 In the tree view, from [I/O]-[Other], select [WILDCARD I/O], and click [OK].
- 10 For the [WILDCARD I/O] station number, set "3".
- **11** Write the settings to the External Device.

To write the settings, select the [Save to flash after transferring to the controller] check box.
 If the data is transferred without selecting the check box, the transferred data is deleted when restarting the External Device.

Remote I/O Settings

Set up communication settings with rotary switches (S1 and S2). For details on communication settings, please refer to the manual of the External Device.

| Rotary Switch | Settings | Setup Description |
|---------------|----------|-------------------|
| S1 (x16) | 0 | Station address |
| S2 (x1) | 3 | |

Notes

3.35 Setting Example 35

Settings of GP-Pro EX

Communication Settings

To display the setup screen, from the [Project] menu, point to [System Settings] and select [Device/PLC].

| Device/PLC 1 | | |
|-------------------------------------|--|--------------------|
| Summary | | Change Device/PLC |
| Manufacturer YASK | AWA Electric Corporation Series MP Ethemet/MECHATROLINK | Port Ethemet (UDP) |
| Text Data Mode | 1 Change | |
| Communication Settings | \$ | |
| Port No. | 1024 Auto | |
| Timeout | 3 (sec) | |
| Retry | 2 🔅 | |
| Wait To Send | 0 (ms) Default | |
| Device-Specific Setting | S | |
| Allowable Number of Devices/PLCs | 32 Add Device Increase Allowable Number of Devices/PLCs | Add Indirect |
| No. Device Name | Settings | Device |
| 👗 1 PLC1 | Series=R7G4HML3-STYVS1(M-III),IP Address=192.16 | 5 . |

Device Setting

To display the [Individual Device Settings] dialog box, from [Device-Specific Settings] in the [Device/PLC] window, select the External Device and click [Settings] I. To connect multiple External Devices, from [Device-Specific Settings] in the [Device/PLC] window, click [Add Device] to add another External Device.

| 🎒 Individual D | evice Settings X | | |
|---------------------------------------|---|--|--|
| PLC1 | | | |
| Product | Product I/O(M-System) | | |
| Series | R7G4HML3-STYVS1(M-III) | | |
| If you change the address settings | product or series, please reconfirm all | | |
| Station Address(| I/O) <u>3</u> | | |
| Relay Control | er Setting | | |
| IP Addres | s 192. 168. 0. 1 | | |
| D | evice Type Circuit No. | | |
| 1 MPU-01 | 3 | | |
| 2 MECHAT | ROLINK 🔽 1 🗮 | | |
| | | | |
| | Default | | |
| | OK (0) Cancel | | |

- Check with a network administrator about IP address. Do not set the duplicate IP address.
- Set IP address on the External Device address in the [Individual Device Settings] dialog box.
- You need to set IP address on the Display in the offline mode of the Display.

Use the ladder software (MP720 Ver.7) to set up communication settings. Set the next contents. (1) Main CPU settings

- (2) MPU-01 settings
- (3) Remote I/O settings

For details on communication settings, please refer to the manual of the External Device.

Main CPU Settings

- 1 Start the ladder software.
- **2** Make a project file. From the [Model] list, select the main CPU.
- **3** From the [Start] tab, click [Module Configuration].

[MC-Configurator] starts up.

- 4 On the CPU you want to use, double-click [218IFD].
- **5** Click the [Parameters] tab.
- **6** In the [Transmission Parameters] group define the [IP Address] and [Subnet Mask] as follows.

| Setup Items | Setup Description |
|-------------|-------------------|
| IP Address | 192.168.0.1 |
| Subnet Mask | 255.255.255.0 |

- 7 Double-click the module number associated with the option slot attached to MPU-01 in the [MC-Configurator].
- **8** In the [Module] dialog box, select [MPU-01] and click [OK].
- **9** In the [MC-Configurator], set [MPU-01]'s circuit number to "3".

Set up the same value as the Display's circuit number.

10 Write the settings to the External Device.

IMPORTANT
 To write the settings, select the [Save to flash after transferring to the controller] check box.
 If the data is transferred without selecting the check box, the transferred data is deleted when restarting the External Device.

MPU-01 Settings

- 1 Start the ladder software.
- 2 Make a project file. Select "MPU-01" from [Model].
- **3** From the tree view, click [Module Configuration]. [MC-Configurator] starts.
- **4** Expand [SVC] of [MPU-01] module, and double-click [01 UNDEFINED].
- 5 Select the using Remote I/O of [Slave] dialog box, and click [OK].
- 6 Set "1" to the circuit number of [SVC].
- 7 Set "3" to the station address of the added Remote I/O.

8 Write the settings to the MPU-01 series.

IMPORTANT • To write the settings, select the [Save to flash after transferring to the controller] check box.

If the data is transferred without selecting the check box, the transferred data is deleted when restarting the External Device.

Remote I/O Settings

Set up communication settings with rotary switches (S1 and S2). For details on communication settings, please refer to the manual of the External Device.

| Rotary Switch | Settings | Setup Description |
|---------------|----------|-------------------|
| S1 (x16) | 0 | Station address |
| S2 (x1) | 3 | |

Notes

3.36 Setting Example 36

- Settings of GP-Pro EX
- Communication Settings

To display the setup screen, from the [Project] menu, point to [System Settings] and select [Device/PLC].

| Device/PLC 1 | | |
|--|--|--|
| Summary | | Change Device/PLC |
| Manufacturer YASKAWA E | ectric Corporation Series MP Etheme | et/MECHATROLINK Port Ethemet (UDP) |
| Text Data Mode | Change | |
| Communication Settings | | |
| Port No. 102 | 4 🕂 🖌 Auto | |
| Timeout 3 | (sec) | |
| Retry 2 | - | |
| Wait To Send 0 | (ms) Default | |
| Device-Specific Settings | | |
| Allowable Number of Devices/PLCs 32 | Add Device Increase Allo Number of Device | owable levices/PLCs Add Indirect |
| No. Device Name | Settings | Device |
| 👗 1 PLC1 | Series=R7G4HML3-STYVS1(M-III),IP A | \ddress=192.16 |

Device Setting

To display the [Individual Device Settings] dialog box, from [Device-Specific Settings] in the [Device/PLC] window, select the External Device and click [Settings] III. To connect multiple External Devices, from [Device-Specific Settings] in the [Device/PLC] window, click [Add Device] to add another External Device.

| 🎒 Individual D | evice Settings X | |
|---------------------------------------|---|--|
| PLC1 | | |
| Product | I/O(M-System) | |
| Series | R7G4HML3-STYVS1(M-III) | |
| If you change the address settings | e product or series, please reconfirm all | |
| Station Address(| VO) <u>3</u> | |
| Relay Control | er Setting | |
| IP Addre: | ss 192. 168. 0. 1 | |
| C | Device Type Circuit No. | |
| 1 Sub CPL | 5 📑 | |
| 2 MECHAT | TROLINK 💌 1 🗮 | |
| | | |
| | Default | |
| | OK (0) Cancel | |

- Check with a network administrator about IP address. Do not set the duplicate IP address.
- Set IP address on the External Device address in the [Individual Device Settings] dialog box.
- You need to set IP address on the Display in the offline mode of the Display.

Use the ladder software (MP720 Ver.7) to set up communication settings. Set the next contents. (1) Main CPU settings

- (2) MPU-01 settings
- (3) Remote I/O settings

For details on communication settings, please refer to the manual of the External Device.

Main CPU Settings

- 1 Start the ladder software.
- **2** Make a project file. From the [Model] list, select the main CPU.
- **3** From the [Start] tab, click [Module Configuration].

[MC-Configurator] starts up.

- 4 On the CPU you want to use, double-click [218IFD].
- **5** Click the [Parameters] tab.
- **6** In the [Transmission Parameters] group define the [IP Address] and [Subnet Mask] as follows.

| Setup Items | Setup Description |
|-------------|-------------------|
| IP Address | 192.168.0.1 |
| Subnet Mask | 255.255.255.0 |

- 7 Double-click the module number attached to the sub CPU in the [MC-Configurator].
- 8 In the [Module] dialog box, select the sub CPU in use and click [OK].
- **9** In the [MC-Configurator], set the sub CPU circuit number to "5".

Set up the same value as the Display's circuit number.

10 Write the settings to the External Device.

IMPORTANT
 To write the settings, select the [Save to flash after transferring to the controller] check box.
 If the data is transferred without selecting the check box, the transferred data is deleted when restarting the External Device.

- ♦ Sub CPU Settings
- 1 Start the ladder software.
- **2** Make a project file. Select a Sub CPU to be used from [Model].
- **3** From the tree view, click [Module Configuration]. [MC-Configurator] starts.
- 4 Expand [SVC] of Sub CPU, and double-click [01 UNDEFINED].
- 5 Select the using Remote I/O of [Slave] dialog box, and click [OK].
- 6 Set "1" to the circuit number of [SVC].
- 7 Set "3" to the station address of the added Remote I/O.

8 Write the settings to the Sub CPU.

IMPORTANT • To write the settings, select the [Save to flash after transferring to the controller] check box.

If the data is transferred without selecting the check box, the transferred data is deleted when restarting the External Device.

Remote I/O Settings

Set up communication settings with rotary switches (S1 and S2). For details on communication settings, please refer to the manual of the External Device.

| Rotary Switch | Settings | Setup Description |
|---------------|----------|-------------------|
| S1 (x16) | 0 | Station address |
| S2 (x1) | 3 | |

Notes

3.37 Setting Example 37

Settings of GP-Pro EX

Communication Settings

To display the setup screen, from the [Project] menu, point to [System Settings] and select [Device/PLC].

| Device/PLC 1 | |
|--|---------------|
| Summary Change | Device/PLC |
| Manufacturer YASKAWA Electric Corporation Series MP Ethemet/MECHATROLINK Port Ethem | net (UDP) |
| Text Data Mode 1 Change | |
| Communication Settings | |
| Port No. 1024 🚔 🔽 Auto | |
| Timeout 3 🔆 (sec) | |
| Retry 2 | |
| Wait To Send 0 (ms) Default | |
| Device-Specific Settings | |
| Allowable Number <u>Add Device</u> Increase Allowable of Devices/PLCs 32 Number of Devices/PLCs | |
| Add Indirec No. Device Name Settings Device | t |
| 1 PLC1 Series=R7G4HML3-LC2A(M-III),IP Address=192.168.0 | |
| | |
| | |
| IMPORTANT • To connect Remote I/O Series using a 1:n connection, [Wait | To Send] must |
| 100ms or more. | |

Device Setting

To display the [Individual Device Settings] dialog box, from [Device-Specific Settings] in the [Device/PLC] window, select the External Device and click [Settings] III. To connect multiple External Devices, from [Device-Specific Settings] in the [Device/PLC] window, click [Add Device] to add another External Device.

| 🎒 Individual De | vice Settings X | |
|--|---|--|
| PLC1 | | |
| Product | I/O(M-System) | |
| Series | R7G4HML3-LC2A(M-III) | |
| If you change the address settings. | product or series, please reconfirm all | |
| Station Address(I | /0) 3 🗄 | |
| Relay Controle | r Setting | |
| IP Addres | s 192. 168. 0. 1 | |
| De | evice Type Circuit No. | |
| 1 MECHAT | ROLINK 🔽 1 🚍 | |
| | | |
| | | |
| | Default | |
| | OK (O) Cancel | |

- Check with a network administrator about IP address. Do not set the duplicate IP address.
- Set IP address on the External Device address in the [Individual Device Settings] dialog box.
- You need to set IP address on the Display in the offline mode of the Display.

Use the ladder software (MP720 Ver.7) to set up communication settings. Set the next contents. (1) Main CPU settings

(2) Remote I/O settings

For details on communication settings, please refer to the manual of the External Device.

Main CPU Settings

- 1 Start the ladder software.
- **2** Make a project file. From the [Model] list, select the main CPU.
- **3** From the [Start] tab, click [Module Configuration].

[MC-Configurator] starts up.

- **4** On the CPU you want to use, double-click [218IFD].
- 5 Click the [Parameters] tab.
- 6 In the [Transmission Parameters] group define the [IP Address] and [Subnet Mask] as follows.

| Setup Items | Setup Description |
|-------------|-------------------|
| IP Address | 192.168.0.1 |
| Subnet Mask | 255.255.255.0 |

7 On the CPU you want to use, set the [SVC32] circuit number to "1".

Set up the same value as the Display's circuit number.

- **8** On the CPU you want to use, open [SVC32], and double-click [01 UNDEFINED].
- 9 In the tree view, from [I/O]-[Other], select [WILDCARD I/O], and click [OK].
- 10 For the [WILDCARD I/O] station number, set "3".
- **11** Write the settings to the External Device.

To write the settings, select the [Save to flash after transferring to the controller] check box.
 If the data is transferred without selecting the check box, the transferred data is deleted when restarting the External Device.

Remote I/O Settings

Set up communication settings with rotary switches (S1 and S2). For details on communication settings, please refer to the manual of the External Device.

| Rotary Switch | Settings | Setup Description |
|---------------|----------|-------------------|
| S1 (x16) | 0 | Station address |
| S2 (x1) | 3 | |

Notes

3.38 Setting Example 38

- Settings of GP-Pro EX
- Communication Settings

To display the setup screen, from the [Project] menu, point to [System Settings] and select [Device/PLC].

| Device/PLC 1 | | |
|-------------------------------------|--|--------------------|
| Summary | | Change Device/PLC |
| Manufacturer YASK | AWA Electric Corporation Series MP Ethemet/MECHATROLINK | Port Ethemet (UDP) |
| Text Data Mode | 1 Change | |
| Communication Settings | 5 | |
| Port No. | 1024 🗾 Auto | |
| Timeout | 3 (sec) | |
| Retry | 2 4 | |
| Wait To Send | 0 (ms) Default | |
| Device-Specific Setting | S | |
| Allowable Number of Devices/PLCs | 32 Add Device Increase Allowable Number of Devices/PLCs | Add Indirect |
| No. Device Name | Settings | Device |
| 👗 1 PLC1 | Series=R7G4HML3-LC2A(M-III),IP Address=192.168.0 | F . |

Device Setting

To display the [Individual Device Settings] dialog box, from [Device-Specific Settings] in the [Device/PLC] window, select the External Device and click [Settings] I. To connect multiple External Devices, from [Device-Specific Settings] in the [Device/PLC] window, click [Add Device] to add another External Device.

| 🎒 Individual D | evice Settings | |
|---------------------------------------|---|--|
| PLC1 | | |
| Product | I/O(M-System) | |
| Series | R7G4HML3-LC2A(M-III) | |
| If you change the address settings | e product or series, please reconfirm all | |
| Station Address(| I/O) <u>3</u> | |
| Relay Control | er Setting | |
| IP Addres | ss 192. 168. 0. 1 | |
| D | levice Type Circuit No. | |
| 1 MPU-01 | 3 🗄 | |
| 2 MECHAT | ROLINK 🔽 1 🗮 | |
| | | |
| | Default | |
| | OK (O) Cancel | |

- · Check with a network administrator about IP address. Do not set the duplicate IP address.
- Set IP address on the External Device address in the [Individual Device Settings] dialog box.
- You need to set IP address on the Display in the offline mode of the Display.

Use the ladder software (MP720 Ver.7) to set up communication settings. Set the next contents. (1) Main CPU settings

- (2) MPU-01 settings
- (3) Remote I/O settings

For details on communication settings, please refer to the manual of the External Device.

Main CPU Settings

- 1 Start the ladder software.
- **2** Make a project file. From the [Model] list, select the main CPU.
- **3** From the [Start] tab, click [Module Configuration].

[MC-Configurator] starts up.

- 4 On the CPU you want to use, double-click [218IFD].
- **5** Click the [Parameters] tab.
- **6** In the [Transmission Parameters] group define the [IP Address] and [Subnet Mask] as follows.

| Setup Items | Setup Description |
|-------------|-------------------|
| IP Address | 192.168.0.1 |
| Subnet Mask | 255.255.255.0 |

- 7 Double-click the module number associated with the option slot attached to MPU-01 in the [MC-Configurator].
- 8 In the [Module] dialog box, select [MPU-01] and click [OK].
- **9** In the [MC-Configurator], set [MPU-01]'s circuit number to "3".

Set up the same value as the Display's circuit number.

10 Write the settings to the External Device.

IMPORTANT
 To write the settings, select the [Save to flash after transferring to the controller] check box.
 If the data is transferred without selecting the check box, the transferred data is deleted when restarting the External Device.

MPU-01 Settings

- 1 Start the ladder software.
- 2 Make a project file. Select "MPU-01" from [Model].
- **3** From the tree view, click [Module Configuration]. [MC-Configurator] starts.
- **4** Expand [SVC] of [MPU-01] module, and double-click [01 UNDEFINED].
- 5 Select the using Remote I/O of [Slave] dialog box, and click [OK].
- 6 Set "1" to the circuit number of [SVC].
- 7 Set "3" to the station address of the added Remote I/O.

8 Write the settings to the MPU-01 series.

IMPORTANT • To write the settings, select the [Save to flash after transferring to the controller] check box.

If the data is transferred without selecting the check box, the transferred data is deleted when restarting the External Device.

Remote I/O Settings

Set up communication settings with rotary switches (S1 and S2). For details on communication settings, please refer to the manual of the External Device.

| Rotary Switch | Settings | Setup Description |
|---------------|----------|-------------------|
| S1 (x16) | 0 | Station address |
| S2 (x1) | 3 | |

Notes

3.39 Setting Example 39

- Settings of GP-Pro EX
- Communication Settings

To display the setup screen, from the [Project] menu, point to [System Settings] and select [Device/PLC].

| Device/PLC 1 | | |
|-------------------------------------|--|--------------------|
| Summary | | Change Device/PLC |
| Manufacturer YASK | AWA Electric Corporation Series MP Ethemet/MECHATROLINK | Port Ethemet (UDP) |
| Text Data Mode | 1 Change | |
| Communication Settings | 5 | |
| Port No. | 1024 🗾 Auto | |
| Timeout | 3 (sec) | |
| Retry | 2 4 | |
| Wait To Send | 0 (ms) Default | |
| Device-Specific Setting | S | |
| Allowable Number of Devices/PLCs | 32 Add Device Increase Allowable Number of Devices/PLCs | Add Indirect |
| No. Device Name | Settings | Device |
| 👗 1 PLC1 | Series=R7G4HML3-LC2A(M-III),IP Address=192.168.0 | F . |

Device Setting

To display the [Individual Device Settings] dialog box, from [Device-Specific Settings] in the [Device/PLC] window, select the External Device and click [Settings] I. To connect multiple External Devices, from [Device-Specific Settings] in the [Device/PLC] window, click [Add Device] to add another External Device.

| 🎒 Individual D | evice Settings X |
|---------------------------------------|---|
| PLC1 | |
| Product | I/O(M-System) 		 ▼ |
| Series | R7G4HML3-LC2A(M-III) |
| If you change the address settings | e product or series, please reconfirm all |
| Station Address(| I/O) <u>3</u> |
| Relay Control | er Setting |
| IP Addre | ss 192. 168. 0. 1 |
| [| Device Type Circuit No. |
| 1 Sub CPL | J 💌 5 🚍 |
| 2 MECHA | |
| | |
| | Default |
| | OK (0) Cancel |

- Check with a network administrator about IP address. Do not set the duplicate IP address.
- Set IP address on the External Device address in the [Individual Device Settings] dialog box.
- You need to set IP address on the Display in the offline mode of the Display.

Use the ladder software (MP720 Ver.7) to set up communication settings. Set the next contents. (1) Main CPU settings

- (2) MPU-01 settings
- (3) Remote I/O settings

For details on communication settings, please refer to the manual of the External Device.

Main CPU Settings

- 1 Start the ladder software.
- **2** Make a project file. From the [Model] list, select the main CPU.
- **3** From the [Start] tab, click [Module Configuration].

[MC-Configurator] starts up.

- 4 On the CPU you want to use, double-click [218IFD].
- **5** Click the [Parameters] tab.
- **6** In the [Transmission Parameters] group define the [IP Address] and [Subnet Mask] as follows.

| Setup Items | Setup Description |
|-------------|-------------------|
| IP Address | 192.168.0.1 |
| Subnet Mask | 255.255.255.0 |

- 7 Double-click the module number attached to the sub CPU in the [MC-Configurator].
- 8 In the [Module] dialog box, select the sub CPU in use and click [OK].
- **9** In the [MC-Configurator], set the sub CPU circuit number to "5".

Set up the same value as the Display's circuit number.

10 Write the settings to the External Device.

IMPORTANT
 To write the settings, select the [Save to flash after transferring to the controller] check box.
 If the data is transferred without selecting the check box, the transferred data is deleted when restarting the External Device.

- ♦ Sub CPU Settings
- 1 Start the ladder software.
- **2** Make a project file. Select a Sub CPU to be used from [Model].
- **3** From the tree view, click [Module Configuration]. [MC-Configurator] starts.
- **4** Expand [SVC] of Sub CPU, and double-click [01 UNDEFINED].
- 5 Select the using Remote I/O of [Slave] dialog box, and click [OK].
- 6 Set "1" to the circuit number of [SVC].
- 7 Set "3" to the station address of the added Remote I/O.

8 Write the settings to the Sub CPU.

IMPORTANT • To write the settings, select the [Save to flash after transferring to the controller] check box.

If the data is transferred without selecting the check box, the transferred data is deleted when restarting the External Device.

Remote I/O Settings

Set up communication settings with rotary switches (S1 and S2). For details on communication settings, please refer to the manual of the External Device.

| Rotary Switch | Settings | Setup Description |
|---------------|----------|-------------------|
| S1 (x16) | 0 | Station address |
| S2 (x1) | 3 | |

Notes

3.40 Setting Example 40

- Settings of GP-Pro EX
- Communication Settings

To display the setup screen, from the [Project] menu, point to [System Settings] and select [Device/PLC].

| Device/PLC 1 | |
|--|-----------|
| Summary Change Device/PL | <u>.c</u> |
| Manufacturer VASKAWA Electric Corporation Series MP Ethemet/MECHATROLINK Port Ethemet (UDP) | |
| Text Data Mode 1 Change | |
| Communication Settings | |
| Port No. 1024 🔽 🔽 Auto | |
| Timeout 3 (sec) | |
| Retry 2 | |
| Wait To Send 0 📩 (ms) Default | |
| Device-Specific Settings | |
| Allowable Number Add Device Increase Allowable of Devices/PLCs 32 Number of Devices/PLCs Add Indirect | |
| No. Device Name Settings Device | |
| 1 PLC1 Series=Sigma-7C Series Servo pack(M-III),IP Address= | |

Device Setting

To display the [Individual Device Settings] dialog box, from [Device-Specific Settings] in the [Device/PLC] window, select the External Device and click [Settings] III. To connect multiple External Devices, from [Device-Specific Settings] in the [Device/PLC] window, click [Add Device] to add another External Device.

| <i>拳</i> Individual D | evice Settings |
|---------------------------------------|---|
| PLC1 | |
| Product | Servo |
| Series | Sigma-7C Series Servo pack(M-III) 💽 |
| If you change the address settings | e product or series, please reconfirm all |
| Station Address | (Servo) 1 🚍 Axis No. 1 🚍 |
| Controler Set | ting |
| IP Addre | ss 192. 168. 0. 1 |
| [| Device Type Circuit No. |
| 1 SVD | <u>v</u> 1 芸 |
| | |
| | |
| | Default |
| | OK (0) Cancel |

- Check with a network administrator about IP address. Do not set the duplicate IP address.
- Set IP address on the External Device address in the [Individual Device Settings] dialog box.
- You need to set the Display's IP address in its offline mode.

Use the ladder software (MP720 Ver.7) to set up communication settings. For details on communication settings, please refer to the manual of the External Device.

- 1 Start the ladder software.
- 2 Make a project file.

In the [TypeSelect] area, set the [Series] and [Controller].

| Setup Items | Setup Description |
|-------------|-------------------|
| Series | MP3000 |
| Controller | SIGMA-7C |

- **3** Click [Module Configuration] to start [MC-Configurator].
- **4** Double-click [218IFD] on the CPU you want to use.
- **5** Click the [Transmission Parameters] tab.
- 6 In [Transmission Parameters], set the [IP Address] and [Subnet Mask].

| Setup Items | Setup Description |
|-------------|-------------------|
| IP Address | 192.168.0.1 |
| Subnet Mask | 255.255.255.0 |

- 7 For the CPU you want to use in [MC-Configurator], set [SVD] to [Circuit No1].
- $\mathbf{8}$ Write the settings to the External Device.
- **9** Turn ON the External Device again.

Notes

4 Setup Items

Set up the Display's communication settings in GP Pro-EX or in the Display's offline mode. The setting of each parameter must match that of the External Device. "" "3 Communication Settings" (page 28)

• Set the Display's IP address in offline mode. Cf. Maintenance/Troubleshooting Guide "Ethernet Settings"

4.1 Setup Items in GP-Pro EX

Communication Settings

To display the setup screen, from the [Project] menu, point to [System Settings] and select [Device/PLC].

| Device/PLC 1 | | |
|-------------------------------------|---|------------------------|
| Summary | | Change Device/PLC |
| Manufacturer YAS | SKAWA Electric Corporation Series MP Ethemet/MECHATROLINK | Port Ethemet (UDP) |
| Text Data Mode | 1 Change | |
| Communication Settin | igs | |
| Port No. | 1024 🔀 Auto | |
| Timeout | 3 (sec) | |
| Retry | 2 | |
| Wait To Send | 0 (ms) Default | |
| Device-Specific Setti | ngs | |
| Allowable Number of Devices/PLCs | Add Device Increase Allowable 32 Number of Devices/PLCs | Adder |
| No. Device Nam | e Settings | Add Indirect Device |
| 👗 1 PLC1 | Series=MP2000 Series, Access to MPU-01=OFF, IP Add | F |

| Setup Items | Setup Description | |
|--|---|--|
| Port No. | Enter a port number of the External Device, using 1024 to 65535. Check into [Auto], and a port number is set automatically. | |
| Timeout | Use an integer from 1 to 127 to enter the time (s) for which Display waits for the response from External Device. | |
| Retry | In case of no response from the External Device, use an integer from 0 to 255 to enter how many times the Display retransmits the command. | |
| Wait To Send | Use an integer from 0 to 255 to enter standby time (ms) for the Display from receiving packets to transmitting next commands. | |
| Increase Allowable Number of Devices/ PLCs | When clicked, the [Increase Allowable Number of Devices/PLCs] dialog box is displayed. When you check [Increase allowable number of Devices/PLCs], the settings for [Allowable Number of Devices/PLCs] can be extended to "64". Increase Allowable Number of Devices/PLCs OK (0) Cancel | |

NOTE

• Refer to the GP-Pro EX Reference Manual for Indirect Device.

Cf. GP-Pro EX Reference Manual "Changing the Device/PLC at Runtime (Indirect Device)"

Device Setting

To display the [Individual Device Settings] dialog box, from [Device-Specific Settings] in the [Device/PLC] window, select the External Device and click [Settings] III. To connect multiple External Devices, from [Device-Specific Settings] in the [Device/PLC] window, click [Add Device] to add another External Device.

| MP2000 Series | MP3000 Series |
|--|--|
| Findividual Device Settings | 🏄 Individual Device Settings 🛛 🔀 |
| PLC1 | PLC1 |
| Product MP2000 Series 💌 | Product MP3000 Series |
| Access to MPU-01 | C Access to Sub CPU |
| If you change the product or series, please reconfirm all address settings. | If you change the product or series, please reconfirm all address settings. |
| IP Address 192. 168. 0. 1 | IP Address 192. 168. 0. 1 |
| | |
| | |
| | |
| | |
| | |
| Default | Default |
| OK (0) Cancel | OK (0) Cancel |

| Setup Items | Setup Description |
|---|--|
| Product | Select the product name of the External Device. |
| Access to MPU-01 / Access to Sub CPU | Uncheck the check box when communicating with MP2000 series / MP3000 series. |
| IP Address | Set IP address of the External Device. NOTE Check with a network administrator about IP address. Do not set the duplicate IP address. |

MPU-01

| Sub | CPU |
|-----|-----|
|-----|-----|

| 🎒 Individual D | evice Settings X | 🕌 Individual Device Settings | × |
|--|--|--|----|
| PLC1 | | PLC1 | |
| Product | MP2000 Series | Product MP3000 Series | |
| | Access to MPU-01 | ☑ Access to Sub CPU | |
| If you change the address settings. | product or series, please reconfirm all | If you change the product or series, please reconfirm all address settings. | |
| Relay Control IP Addre: 1 MPU-01 | ss 192. 168. 0. 1 Device Type Circuit No. | Relay Controler Setting IP Address 192 168 0. 1 Device Type Circuit No. 1 Sub CPU 5 5 | |
| | Default OK (0) Cancel | Defau OK (0) Cancel | lt |

| Setup Items | Setup Description |
|---|--|
| Product | Select the product name of the External Device. |
| Access to MPU-01 / Access to Sub CPU | Check the check box when using MPU-01 and Sub CPU. NOTE Uncheck the check box when using an Ethernet port on the Sub CPU. |
| IP Address | Set IP address of the relay device (MP series / Σ-7C (Controller section)). NOTE Check with a network administrator about IP address. Do not set the duplicate IP address. |
| Device Type | Select a device type to be used for relay. |
| Circuit No. | Enter the circuit number, from 1 to 16. |

| 🎒 Individual Dev | vice Settings |
|---|--|
| PLC1 | |
| Product | Inverter |
| Series | V1000 |
| If you change the pr address settings. | roduct or series, please reconfirm all |
| Station Address(In | verter) 33 芸 |
| Relay Controler | Setting |
| IP Address | 192. 168. 0. 1 |
| Der | vice Type Circuit No. |
| 1 MECHATR | ROLINK 🗾 1 🚍 |
| | |
| | |
| | Default |
| | OK (O) Cancel |

Inverter Series

Servo Series

| 🎒 Individual De | evice Settings | × |
|--|---|---|
| PLC1 | | |
| Product | Servo | |
| Series | Sigma-7W series Servo pack(M-III) | ┓ |
| If you change the p address settings. | product or series, please reconfirm all | |
| Station Address(S | Servo) 🛛 🔋 🗄 Axis No. 🕇 | Ð |
| Relay Controle | er Setting | |
| IP Addres | s 192. 168. 0. 1 | |
| De | evice Type Circuit No. | |
| 1 MPU-01 | 3 🚍 | |
| 2 MECHAT | ROLINK 🔽 1 🗮 | |
| | | |
| | Default | |
| | OK (0) Cancel | |

Stepping

| I/O | Stepping |
|--|---|
| 🚰 Individual Device Settings 🛛 🔀 | ➢Individual Device Settings |
| PLC1 | PLC1 |
| Product I/O(M-System) | Product Stepping(Orientalmotor) |
| Series R7G4HML3-LC2(M-III) | Series AZ Series Multi-Axis Driver(M-III) |
| If you change the product or series, please reconfirm all address settings. | If you change the product or series, please reconfirm all address settings. |
| Station Address(I/O) 3 | Station Address(Stepping) 3 🚊 Axis No. 1 🚊 |
| Relay Controler Setting IP Address 192 168 0 1 Device Type Circuit No. 1 MECHATROLINK 1 | Relay Controler Setting IP Address 192. 168. 0. 1 Device Type Circuit No. 1 MECHATROLINK I 1 |
| OK (0) Cancel | OK (0) Cancel |

| Setup Items | Setup Description | |
|-----------------|--|--|
| Product | Select the product name of the External Device. | |
| Series | Select the series of the External Device. | |
| Station Address | Inverter Series: Enter the station number, from 1 to 255. Servo Series: Enter the station number as follows. MECHATROLINK-II: "65 to 79" and "80 to 95" MECHATROLINK-III: "3 to 239" I/O: Enter the station address, from 3 to 239. Stepping: Enter the station address, from 3 to 239. | |
| Axis No. | Σ -7W/ Σ -7C series: Enter the Axis number, from 1 to 2. AZ series: Enter the Axis number of stepping, from 1 to 255. | |
| IP Address | Set IP address of the relay device (MP series / Σ-7C (Controller section)). NOTE Check with a network administrator about IP address. Do not set the duplicate IP address. | |
| Device Type | Select a device type to be used for relay. | |

| Setup Items | Setup Description | |
|-------------|--|--|
| Circuit No. | Enter the circuit number, from 1 to 16. | |
| s | Vhen communicating with the Servo Series, the first three octets in the subnet mask hould be set to 255. | |

4.2 Setup Items in Offline Mode

• Please refer to Maintenance/Troubleshooting Guide for more information on how to enter offline mode or about operation.

Cf. Maintenance/Troubleshooting Guide "Offline Mode"

• The number of the setup items to be displayed for 1 page in the offline mode depends on the Display in use. Please refer to the Reference manual for details.

Communication Settings

To display the setting screen, touch [Device/PLC Settings] from [Peripheral Settings] in offline mode. Touch the External Device you want to set from the displayed list.

| Comm. | Device | | | |
|-----------------|---|---------|-------------------------|------------------------|
| MP Ethernet/MEC | HATROL INK | | [UDP] | Page 1/1 |
| | Port No. | ⊙ Fixed | ● Auto 1024 ▼ ▲ |] |
| | Timeout(s) Retry Wait To Send(ms) | | 3 ▼ ▲ 2 ▼ ▲ 0 ▼ ▲ | |
| | | | | |
| | | | | |
| | Exit | - | Back | 2014/11/19 17:11:29 |

| Setup Items | Setup Description |
|--------------|--|
| Port No. | Enter a port number of the Display. Select either of "Fixed" "Auto". Enter a port number of the Display with "1024-65535", when select "Fixed". Assign automatically without affecting the input value, when select "Auto". |
| Timeout | Use an integer from 1 to 127 to enter the time (s) for which Display waits for the response from External Device. |
| Retry | In case of no response from the External Device, use an integer from 0 to 255 to enter how many times the Display retransmits the command. |
| Wait To Send | Use an integer from 0 to 255 to enter standby time (ms) for the Display from receiving packets to transmitting next commands. |

Device Setting

To display the setting screen, touch [Device/PLC Settings] from [Peripheral Settings] in offline mode. Touch the External Device you want to set from the displayed list, and touch [Device].

| Comm. | Device | | | |
|-----------------|------------|------|---------------|------------------------|
| | | | | |
| MP Ethernet/MEC | HATROLINK | | [UDP] | Page 1/6 |
| Devic | e/PLC Name | PLC1 | | |
| S | Series | | MP2000 Series | |
| Ι | P Address | | 192 168 Ø | 1 |
| | | | | |
| | | | | |
| | | | | |
| | | | | |
| | | | | • |
| | Exit | | Back | 2014/11/19 17:11:39 |

| Setup Items | Setup Description |
|-----------------|---|
| Device/PLC Name | Select the External Device for device setting. Device name is a title of the External Device set with GP-Pro EX. (Initial value [PLC1]) |
| Series | Display the series of the External Device. |
| | Set IP addresses used by the External Device or relay device (MP series / Σ -7C (Controller section)). |
| IP Address | NOTE Check with a network administrator about IP address. Do not set the duplicate IP address. |

• MP2000/MP3000 Series (Page 2 - 3)

| Comm. | Device | | | |
|-----------------|------------------------|----|------------------|------------------------|
| | | | | |
| MP Ethernet/MEC | HATROLINK | | [UDP] | Page 3/6 |
| Devic | e/PLC Name PL | 01 | | |
| | Product | | MP3000 Series | |
| | Access to Sub CP | ۲U | ON | |
| | Device Type Sub CPU | | Circuit No. 5 | |
| | | | | ◆ ◆ |
| | Exit | | Back | 2014/11/19 17:27:18 |

| Setup Items | Setup Description |
|---|---|
| Device/PLC Name | Select the External Device for device setting. Device name is a title of the External Device set with GP-Pro EX. (Initial value [PLC1]) |
| Product | Display the product to connect. |
| Access to MPU-01 / Access to Sub CPU | Display the setting state. |
| Device Type | Displays the device type to be used for the relay. |
| Circuit No. | Display the circuit number. |

• Servo Series (Page 4)

| Comm. | Device | | | |
|-----------------|------------------------------------|----|--------------------------|------------------------|
| MP Ethernet/MEC | HATROL INK | | [VDP] | Page 4/6 |
| Devic | e/PLC Name PL | C1 | | - |
| | Product | | Servo | |
| | Station Address Axis No. | | 65 | |
| | Device Type MECHATROLINK-II | | Circuit No. 1 | |
| | | | | + + |
| | Exit | | Back | 2014/11/19 17:16:23 |

| Setup Items | Setup Description |
|-----------------|---|
| Device/PLC Name | Select the External Device for device setting. Device name is a title of the External Device set with GP-Pro EX. (Initial value [PLC1]) |
| Product | Display the product to connect. |
| Station Address | Display the station address. |
| Axis No. | Display the Axis number. Available with Σ -7W/ Σ -7C series only. |
| Device Type | Displays the device type to be used for the relay. |
| Circuit No. | Display the circuit number. |

• Inverter Series / I/O / Stepping (Page 5 - 6)

| Comm. | Device | | | |
|---|-----------------|----|--------------------------|------------------------|
| | | | | |
| MP Ethernet/MEC | HATROLINK | | [UDP] | Page 6/6 |
| Devic | e/PLC Name PL | 01 | | - |
| | Product | | I/O(M-System) | |
| | Station Address | | 3 | |
| Device Type 1 MECHATROLINK-III 2 3 | | | Circuit No. 1 | |
| | | | | + |
| | Exit | | Back | 2015/07/13 14:15:34 |

| Setup Items | Setup Description |
|-----------------|---|
| Device/PLC Name | Select the External Device for device setting. Device name is a title of the External Device set with GP-Pro EX. (Initial value [PLC1]) |
| Product | Display the product to connect. |
| Station Address | Display the station address. |
| Device Type | Displays the device type to be used for the relay. |
| Circuit No. | Display the circuit number. |

5 Supported Devices

Range of supported device address is shown in the table below. Please note that the actually supported range of the devices varies depending on the External Device to be used. Please check the actual range in the manual of your External Device.

5.1 MP2000 Series / MPU-01

This address can be specified as system data area.

| Device | Bit Address | Word Address | 32 bits | Notes |
|------------------|---------------------|-------------------|------------|-------|
| System registers | SB000000 - SB08191F | SW00000 - SW08191 | | |
| Input registers | IB00000 - IBFFFFF | IW0000 - IWFFFF | ΓL / H) | *1 |
| Output registers | OB00000 - OBFFFFF | OW0000 - OWFFFF | | *1 |
| Data registers | MB000000 - MB65534F | MW00000 - MW65534 | | |

*1 As for Input and Output registers, device 0x9000-0xFFFF cannot be written.

NOTE

Π

• Please refer to the GP-Pro EX Reference Manual for system data area.

Cf. GP-Pro EX Reference Manual "LS Area (Direct Access Method Area)"
Please refer to the precautions on manual notation for icons in the table.

"Manual Symbols and Terminology"

5.2 MP3000 Series / Sub CPU

This address can be specified as system data area.

| Device | Bit Address | Word Address | 32 bits | Notes |
|------------------|-----------------------------|----------------------------|---------------------|-------|
| System registers | SB000000 - SB65534F | SW00000 - SW65534 | | |
| Input registers | IB000000 - IB27FFFF | IW00000 - IW27FFF | | *1 |
| Output registers | OB000000 - OB27FFFF | OW00000 - OW27FFF | (1) | *1 |
| Data registers | MB00000000 - MB1048575F | MW0000000 - MW1048575 | ן <u>נוו</u> אן | |
| G registers | GB00000000 - GB02097151F | GW00000000 - GW02097151 | 1 | |

*1 As for Input and Output registers, device 0x9000-0xFFFF cannot be written.



Please refer to the GP-Pro EX Reference Manual for system data area.

Cf. GP-Pro EX Reference Manual "LS Area (Direct Access Method Area)"

• Please refer to the precautions on manual notation for icons in the table.

5.3 Inverter Series

E

This address can be specified as system data area.

| Device | Bit Address | Word Address | 32 bits | Notes |
|-----------------------------|---------------------|--------------|------------|-------------------|
| Bit registers ^{*1} | BR0000.0 - BR195C.F | - | - | *2 |
| Registers ^{*1} | - | 0000~195C | [L / H] | Bit F] *2 |

*1 In the Inverter, bit registers and registers use the same device. Bit registers are used only for bit addresses.

The access method when specifying bits varies depending on the device.

| Bit registers | BR0000.0 - BR195C.F |
|---------------|---------------------|
| | - |

Registers

*2 The available register numbers and available read/write operations differ depending on the External Device model. For further information, refer to the instruction manual for your External Device.

NOTE

• You can only set the Read Area Size for the system area in the External Device. Please refer to the GP-Pro EX Reference Manual for Read Area Size.

- Please refer to the GP-Pro EX Reference Manual for system data area.
 Cf. GP-Pro EX Reference Manual "LS Area (Direct Access Method Area)"
- Please refer to the precautions on manual notation for icons in the table.
 - "Manual Symbols and Terminology"

5.4 Σ-V Series

This address can be specified as system data area.

| Device | Bit Address | Word Address | 32 bits | Notes |
|---------------------------|-----------------|--------------|------------|-------|
| Normal Parameters Area | 0000.0 - 0FFF.F | 0000 - 0FFF | | *1 *2 |
| Temporary Parameters Area | 1000.0 - 1FFF.F | 1000 - 1FFF | [L/H] | *1 *2 |
| Monitor Area | E000.0 - EFFF.F | E000 - EFFF | | *1 *2 |

*1 When you write to the bit address, the Display reads the entire word, sets the defined bit, then returns the new word value to the External Device. If the ladder program writes data to this word address during the bit write process, the resulting data may be incorrect.

*2 The following addresses are 32 bit parameters. Please use two words when reading or writing.

 Normal Parameters Area

 020AH / 020EH / 0210H / 0212H / 0282H / 051BH / 0520H / 0522H / 0524H / 0526H / 0531H /

 0804H / 0806H / 0808H / 0814H / 0819H / 0820H / 0822H / 0834H / 0836H / 0838H / 083AH /

 083CH / 083EH / 0840H / 0890H / 0892H / 0894H / 0896H / 0898H / 089AH / 089CH / 089EH /

 0806H / 0840H / 0840H / 0890H / 0892H / 0894H / 0896H / 0898H / 089AH / 089CH / 089EH /

 0806H / 0840H / 0840H / 0846H / 0846H / 0848H / 084AH / 084CH / 084EH / 0880H / 0882H / 0882H /

 0806H / 0844H / 0846H / 0846H / 0848H / 084AH / 0406H / 0406H / 0408H / 040AH /

 0806H / 0812H / 0812H / 0414H / 0416H / 0418H / 0442H / 0446H / 0446H / 0448H / 044AH /

 044CH / 044EH / 0450H / 0452H / 0482H / 0484H / 0486H / 0488H / 0484H / 0446H / 0486H / 048EH /

 0490H / 0492H / 0422H / 0424H / 0426H / 0428H / 0424H / 0424H / 0426H / 0426H / 0482H /

 0490H / 0492H / 0422H / 0424H / 0426H / 0428H / 0424H / 0446H / 0486H / 0488H /

 0406H / 0808H / 080AH / 080CH / 080EH / 0428H / 0424H / 0424H / 0426H / 0426H / 0482H /

 0406H / 0492H / 0424H / 0424H / 0426H / 0428H / 0424H / 0424H / 0426H / 0426H / 0482H /

 0490H / 0492H / 0424H / 0424H / 0426H / 0428H / 0424H /

 0406H / 0808H / 080AH / 080CH / 080EH / 0802H / 0810H /

 0806H / 0808H / 080AH / 080CH / 080EH / 0810H /

 0810H / 0816H / 0814H / 0816H / 0814H /

 0810H / 0812H / 0820H / 0822H / 0824H / 0826H /

Temporary Parameters Area

 120AH / 120EH / 1210H / 1212H / 1282H / 151BH / 1520H / 1522H / 1524H / 1526H / 1531H /

 1804H / 1806H / 1808H / 1814H / 1819H / 1820H / 1822H / 1834H / 1836H / 1838H / 183AH /

 183CH / 183EH / 1840H / 1890H / 1892H / 1894H / 1896H / 1898H / 189AH / 189CH / 189EH /

 18A0H / 18A2H / 1840H / 1890H / 1892H / 1894H / 1896H / 1898H / 189AH / 189CH / 189EH /

 18A0H / 18A2H / 18A4H / 18A6H / 18A8H / 18AAH / 18ACH / 18AEH / 180H / 189CH / 189EH /

 18B6H / 18B8H / 18BAH / 18BCH / 18BEH / 1A02H / 1A04H / 1A06H / 1A08H / 1A0AH / 1A0CH /

 1A0EH / 1A10H / 1A12H / 1A14H / 1A16H / 1A18H / 1A42H / 1A44H / 1A46H / 1A48H / 1A4AH /

 1A4CH / 1A4EH / 1A50H / 1A52H / 1A82H / 1A84H / 1A86H / 1A88H / 1A8AH / 1A8CH / 1A8EH /

 1A90H / 1A92H / 1AC2H / 1AC4H / 1AC6H / 1AC8H / 1ACAH / 1ACCH / 1ACEH / 1B02H / 1B04H /

 1B06H / 1B08H / 1B0AH / 1B0CH / 1B0EH / 1B10H / 1B12H / 1B14H / 1B16H / 1B18H / 1B1AH /

 1B1CH / 1B1EH / 1B20H / 1B22H / 1B24H / 1B26H /

Monitor Area

E003H / E009H / E00EH / E010H / E012H / E016H / E01BH / E084H / E52AH / E52CH / E52EH / E530H / E532H / E534H / E536H / E538H / E53AH / E53CH / E601H / E603H / E605H / E707H

| NOTE | • You can only set the Read Area Size for the system area available to use in the External |
|------|--|
| | Device. Please refer to the GP-Pro EX Reference Manual for Read Area Size. |
| | Please refer to the GP-Pro EX Reference Manual for system data area. |
| | Cf. GP-Pro EX Reference Manual "LS Area (Direct Access Method Area)" |
| | • Please refer to the precautions on manual notation for icons in the table. |
| | "Manual Symbols and Terminology" |
| | |

Normal Parameters Area

This area is used to map the External Device's user constant parameters. The register number is defined by adding the Pn number and the offset value. The normal parameters area offset value is 0000H. For details on the Pn number and register mapping, please refer to the manual of the External Device.

| Operation | Description |
|-----------|---|
| Read | Reads volatile memory such as RAM for values. Unable to read values from non-volatile memory such as EEPROM. |
| Write | Writes values to volatile memory such as RAM, and non-volatile memory such as EEPROM. |
| NOTE | You cannot run consecutive reads from, or consecutive writes to, different register groups. Example: When consecutively reading from or writing to 07FFH to 0800H, the message "Data Consistency Error (33H)" or "Access Denied Error (31H)" is displayed. If you specify a nonexistent register number, the message "Access Denied Error (31H)," is |

Temporary Parameters Area

displayed.

This area is used to map the External Device's user constant parameters. The register number is defined by adding the Pn number and the offset value. The temporary parameters area offset value is 1000H. For details on the Pn number and register mapping, please refer to the manual of the External Device.

| Operation | Description | | | |
|-----------|---|--|--|--|
| Read | Reads volatile memory such as RAM for values. | | | |
| Write | Writes values to volatile memory such as RAM. | | | |

Since writing to Temporary Parameters Area is run in volatile memory (such as RAM), values are cleared when the External Device is turned OFF.

If there is an operation, such as servo tuning, that requires an extreme number of write operations to memory, running the operation in the Temporary Parameters Area generates the following advantages.

- You can increase the life of non-volatile memory.
- You can reduce processing time.

• You cannot run consecutive reads from, or consecutive writes to, different register groups. Example: When consecutively reading from or writing to 17FFH to 1800H, the message "Data Consistency Error (33H)" or "Access Denied Error (31H)" is displayed.

• If you specify a nonexistent register number, the message "Access Denied Error (31H)," is displayed.

Monitor Area

This area is used to reference internal information (such as operating condition, alarm status, and various status flags) on the External Device. By referring to the value of a register number, you can check the status of the External Device. While the External Device is running, register values change constantly.

| Register No. | Name | Unit | No. of Registers | Sign | Remarks | |
|-----------------|--|---------------------------|---------------------|------|--|--|
| E000H | Motor Dotational/Translational Speed | Rotary: min ⁻¹ | 1 | S | Un000 | |
| EUUUH | Motor Rotational/Translational Speed | Linear: mm/s | 1 | 3 | | |
| E001H | Deference Speed | Rotary: min ⁻¹ | 1 | G | Un001 | |
| EUUTH | Reference Speed | Linear: mm/s | 1 | S | | |
| E002H | Internal Torque/Thrust Force Reference | % | 1 | S | Un002 | |
| E003H | Rotational Angle 1 (Number of Pulses from the Origin) | Pulse | 2 | U | Un003 | |
| E005H | Rotational Angle 2 (Angle from the Origin) | deg | 1 | U | Un004 | |
| E006H | Input Signal Monitor | - | 1 | - | Un005 | |
| E007H | Output Signal Monitor | - | 1 | - | Un006 | |
| E008H | Input Reference Pulse Speed | Rotary: min ⁻¹ | 1 | S | Un007 | |
| LUUGIT | input Reference Fuise Speed | Linear: mm/s | 1 | 5 | 011007 | |
| E009H | Position Error Counter | Reference unit | 2 | S | Un008 | |
| E00BH | Accumulated Load Rate | %(10s cycle) | 1 | U | Un009 | |
| E00CH | Regenerative Load Rate | %(10s cycle) | 1 | U | Un00A | |
| E00DH | Dynamic Break Consumption Power | %(10s cycle) | 1 | U | Un00B | |
| E00EH | Input Reference Pulse Counter (32bit) | Pulse | 2 | S | Un00C | |
| E010H | Feedback Pulse Counter (32bit) | Pulse | 2 | S | Un00D | |
| E012H | Fully-closed Feedback Pulse Counter (32bit) | Pulse | 2 | S | Un00E | |
| E016H | Total Operation Time | 100ms | 2 | U | Un012 | |
| E018H | Upper Limit of Maximum Motor Speed | mm/s | 1 | U | Un010 (Available only in linear motor) | |
| E019H | Upper Limit of Divided Pulse Output Setting | Pulse/Pitch | 1 | U | Un010 (Available only in linear motor) | |
| E01AH | Magnetic Pole Sensor Information | - | 1 | - | Un011 | |
| E01BH | Feedback Pulse Counter | Reference unit | 2 | S | Un013 | |
| E01DH | Effective Gain Set Number | - | 1 | U | Un014 | |
| E01EH | Safety I/O Signal Monitor | - | 1 | - | Un015 | |
| E084H | Linear Scale Pitch | pm | 2 | U | Un084 | |
| E086H | Linear Scale Pitch Scaling Exponent | Power of Ten | 1 | S | Un085 | |
| E500H | Alarm History Alarm Code No. = 0 | Code | 1 | U | Fn000-0 | |

| Register No. | Name | Unit | No. of Registers | Sign | Remarks |
|-----------------|----------------------------------|-------|---------------------|------|---------|
| E501H | Alarm History Alarm Code No. = 1 | Code | 1 | U | Fn000-1 |
| E502H | Alarm History Alarm Code No. = 2 | Code | 1 | U | Fn000-2 |
| E503H | Alarm History Alarm Code No. = 3 | Code | 1 | U | Fn000-3 |
| E504H | Alarm History Alarm Code No. = 4 | Code | 1 | U | Fn000-4 |
| E505H | Alarm History Alarm Code No. = 5 | Code | 1 | U | Fn000-5 |
| E506H | Alarm History Alarm Code No. = 6 | Code | 1 | U | Fn000-6 |
| E507H | Alarm History Alarm Code No. = 7 | Code | 1 | U | Fn000-7 |
| E508H | Alarm History Alarm Code No. = 8 | Code | 1 | U | Fn000-8 |
| E509H | Alarm History Alarm Code No. = 9 | Code | 1 | U | Fn000-9 |
| E50AH | Current Alarm Information | Code | 1 | U | |
| E51BH | Servo Running Status | - | 1 | U | |
| E51CH | Control Mode Status | - | 1 | U | |
| E52AH | Alarm History Time Stamp No. = 0 | 100ms | 2 | U | |
| E52CH | Alarm History Time Stamp No. = 1 | 100ms | 2 | U | |
| E52EH | Alarm History Time Stamp No. = 2 | 100ms | 2 | U | |
| E530H | Alarm History Time Stamp No. = 3 | 100ms | 2 | U | |
| E532H | Alarm History Time Stamp No. = 4 | 100ms | 2 | U | |
| E534H | Alarm History Time Stamp No. = 5 | 100ms | 2 | U | |
| E536H | Alarm History Time Stamp No. = 6 | 100ms | 2 | U | |
| E538H | Alarm History Time Stamp No. = 7 | 100ms | 2 | U | |
| E53AH | Alarm History Time Stamp No. = 8 | 100ms | 2 | U | |
| E53CH | Alarm History Time Stamp No. = 9 | 100ms | 2 | U | |

 Input Signal Monitor (E006H) MECHATROLINK Interface Type

| Bit | Status Signal | Logic | Un No. |
|-----|---------------|---------------------------------|--------|
| 0 | SI0(CN1-13) | 0 = Lo (Close) 1 = Hi (Open) | |
| 1 | SI1(CN1-7) | 0 = Lo (Close) 1 = Hi (Open) | |
| 2 | SI2(CN1-8) | 0 = Lo (Close) 1 = Hi (Open) | |
| 3 | SI3(CN1-9) | 0 = Lo (Close) 1 = Hi (Open) | Un005 |
| 4 | SI4(CN1-10) | 0 = Lo (Close) 1 = Hi (Open) | |
| 5 | SI5(CN1-11) | 0 = Lo (Close) 1 = Hi (Open) | |
| 6 | SI6(CN1-12) | 0 = Lo (Close) 1 = Hi (Open) | |
| 7 | Reserved | | |

 Output Signal Monitor (E007H) MECHATROLINK Interface Type

| Bit | Status Signal | Logic | Un No. |
|-----|----------------|---------------------------------|--------|
| 0 | ALM(CN1-3,4) | 0 = Lo (Close) 1 = Hi (Open) | |
| 1 | SO1(CN1-1,2) | 0 = Lo (Close) 1 = Hi (Open) | |
| 2 | SO2(CN1-23,24) | 0 = Lo (Close) 1 = Hi (Open) | |
| 3 | SO3(CN1-25,26) | 0 = Lo (Close) 1 = Hi (Open) | Un006 |
| 4 | Reserved | | |
| 5 | Reserved | | |
| 6 | Reserved | | |
| 7 | Reserved | | |

• Safety I/O Signal Monitor (E01EH)

| Bit | Status Signal | Logic | Un No. |
|--------|-----------------|---------------------------------|--------|
| 0 | /HWBB1(CN8-3,4) | 0 = Lo (Close) 1 = Hi (Open) | |
| 1 | /HWBB2(CN8-5,6) | 0 = Lo (Close) 1 = Hi (Open) | Un015 |
| 2 to 7 | Reserved | | |

NOTE

• /HWBB1 and /HWBB2 are valid only when the safety option card is not connected. When the safety option card is connected, they become indefinite.

• Servo Running Status (E51BH)

| Reading | Description |
|---------|---|
| 0000H | Reserved (Initial State) |
| 0001H | Alarm Occurred (A.***) |
| 0002H | Hardwired Base Blocked (HWBB) |
| 0003H | Forward / Reverse Run Prohibited (PTNT) |
| 0004H | Forward Run Prohibited (P-OT) |
| 0005H | Reverse Run Prohibited (N-OT) |
| 0006H | Base Blocked (BB) |
| 0007H | Base Enabled (RUN) |
| 0008H | Magnetic Pole Detecting (PDET) |

• Control Mode Status (E51CH)

| Reading | Description |
|---------|-----------------------|
| 0000H | Speed Control Mode |
| 0001H | Position Control Mode |
| 0002H | Torque Control Mode |

NOTE

• JOG Drive Mode, Origin Search Mode, and Internally Set Speed Control Mode become Speed control mode.

• Programmed JOG Drive Mode, Advanced Auto-Tuning Mode, and Easy FFT Mode become Position Control Mode.

5.5 Σ-7 Series

This address can be specified as system data area.

| Device | Bit Address | Word Address | 32 bits | Notes |
|---------------------------|-----------------|--------------|------------|----------|
| Normal Parameters Area | 0000.0 - 0FFF.F | 0000 - 0FFF | | *1 *2 *3 |
| Temporary Parameters Area | 1000.0 - 1FFF.F | 1000 - 1FFF | | *1 *2 *3 |
| Monitor Area | E000.0 - EFFF.F | E000 - EFFF | | *1 *3 |

*1 When you write to the bit address, the Display reads the entire word, sets the defined bit, then returns the new word value to the External Device. If the ladder program writes data to this word address during the bit write process, the resulting data may be incorrect.

- *2 You cannot run block read or block write with the following addresses. 07FFH - 0800H 17FFH - 1800H
- *3 The following addresses are 32 bit parameters. Please use two words when reading or writing. Normal Parameters Area

```
      020AH /
      0210H /
      0212H /
      0231H /
      0282H /
      051BH /
      0520H /
      0524H /
      0524H /
      0526H /

      0531H /
      0804H /
      0806H /
      0808H /
      0814H /
      0819H /
      0820H /
      0822H /
      0834H /
      0836H /
      0838H /

      083AH /
      083CH /
      083EH /
      0840H /
      0842H /
      0844H /
      0890H /
      0822H /
      0834H /
      0836H /
      0838H /

      0A08H /
      0A0AH /
      0A0CH /
      0A0EH /
      0A10H /
      0A12H /
      0A14H /
      0A16H /
      0A18H /
      0A44H /

      0A46H /
      0A4AH /
      0A4CH /
      0A4EH /
      0A50H /
      0A52H /
      0A84H /
      0A86H /
      0A88H /

      0A8AH /
      0A4AH /
      0A4CH /
      0A4EH /
      0A50H /
      0A52H /
      0A84H /
      0A86H /
      0A88H /

      0A8AH /
      0A8EH /
      0A90H /
      0A92H /
      0AC2H /
      0AC4H /
      0AC4H /
      0ACCH /
      0AC2H /
      0AC4H /
      0ACAH /
      0ACCH /

      0A8AH /
      0A8CH /
      0A90H /
      0A92H /
      0AC2H /
      0AC4H /
      0ACAH /
      0ACCH /

      0ACEH /
```

Temporary Parameters Area

 120AH /
 120EH /
 1210H /
 1212H /
 1282H /
 151BH /
 1520H /
 1522H /
 1524H /
 1526H /
 1531H /

 1804H /
 1806H /
 1808H /
 1814H /
 1819H /
 1820H /
 1822H /
 1834H /
 1836H /
 1838H /
 183AH /

 183CH /
 183EH /
 1840H /
 1890H /
 1892H /
 1894H /
 1896H /
 1898H /
 189AH /
 189CH /
 189EH /

 18A0H /
 18A2H /
 1840H /
 1890H /
 1892H /
 1894H /
 1896H /
 1898H /
 189CH /
 189EH /

 18A0H /
 18A2H /
 18A4H /
 18A6H /
 18A8H /
 18ACH /
 18ACH /
 189EH /
 180CH /
 189EH /

 18B6H /
 18B8H /
 18BAH /
 18BCH /
 18A2H /
 1A02H /
 1A04H /
 1A06H /
 1A08H /
 1A0CH /
 1A0CH /

 1A0EH /
 1A12H /
 1A14H /
 1A16H /
 1A18H /
 1A42H /
 1A44H /
 1A46H /
 1A48H /
 1A4AH /

 1A4CH /
 1A4EH /
 1A50H /
 1A52H /
 1A82H /
 1A84H /
 1A42H /
 1A48H /

Monitor Area

```
E003H / E009H / E00EH / E010H / E012H / E016H / E01BH / E030H / E032H / E035H / E037H / E084H / E52AH / E52CH / E52EH / E530H / E532H / E534H / E536H / E538H / E53AH / E53CH / E548H / E54CH / E54CH / E550H / E552H / E554H / E556H / EC00H / EC02H / EC04H / EC06H / EC08H / EC0AH / EC0CH / EC0EH / EC10H / EC12H / EC14H / EC16H
```

```
NOTE
```

• You can only set the Read Area Size for the system area available to use in the External Device. Please refer to the GP-Pro EX Reference Manual for Read Area Size.

- Please refer to the GP-Pro EX Reference Manual for system data area.
- Cf. GP-Pro EX Reference Manual "LS Area (Direct Access Method Area)"
- Please refer to the precautions on manual notation for icons in the table.
 - "Manual Symbols and Terminology"

Normal Parameters Area

This area is used to map the External Device's user constant parameters. The register number is defined by adding the Pn number and the offset value. The normal parameters area offset value is 0000H. For details on the Pn number and register mapping, please refer to the manual of the External Device.

| Operation | Description |
|-----------|---|
| Read | Reads volatile memory such as RAM for values. Unable to read values from non-volatile memory such as EEPROM. |
| Write | Writes values to volatile memory such as RAM, and non-volatile memory such as EEPROM. |
| NOTE | You cannot run consecutive reads from, or consecutive writes to, different register groups. Example: When consecutively reading from or writing to 07FFH to 0800H, the message "Data Consistency Error (33H)" or "Access Denied Error (31H)" is displayed. If you specify a nonexistent register number, the message "Access Denied Error (31H)," is |

Temporary Parameters Area

displayed.

This area is used to map the External Device's user constant parameters. The register number is defined by adding the Pn number and the offset value. The temporary parameters area offset value is 1000H.

| For detail | ls on the | Pn numbe | r and registe | r mappıng, j | please refer | to the manual | of the External | Device. |
|------------|-----------|----------|---------------|--------------|--------------|---------------|-----------------|---------|
| | | | | | | | | |

| Operation | Description | |
|-----------|---|--|
| Read | Reads volatile memory such as RAM for values. | |
| Write | Writes values to volatile memory such as RAM. | |

Since writing to Temporary Parameters Area is run in volatile memory (such as RAM), values are cleared when the External Device is turned OFF.

If there is an operation, such as servo tuning, that requires an extreme number of write operations to memory, running the operation in the Temporary Parameters Area generates the following advantages.

- You can increase the life of non-volatile memory.
- You can reduce processing time.

• You cannot run consecutive reads from, or consecutive writes to, different register groups. Example: When consecutively reading from or writing to 17FFH to 1800H, the message "Data Consistency Error (33H)" or "Access Denied Error (31H)" is displayed.

• If you specify a nonexistent register number, the message "Access Denied Error (31H)," is displayed.

Monitor Area

This area is used to reference internal information (such as operating condition, alarm status, and various status flags) on the External Device. By referring to the value of a register number, you can check the status of the External Device. While the External Device is running, register values change constantly.

| Register No. | Name | Unit | No. of Registers | Sign | Remarks |
|-----------------|--|---------------------------|---------------------|------|--|
| E000H | Motor Rotational/Translational Speed | Rotary: min ⁻¹ | 1 1 S | S | Un000 |
| LOODIT | Wotor Rotational/ Hansiational Speed | Linear: mm/s | 1 | 5 | Average 64 ms |
| E001H | Reference Speed | Rotary: min ⁻¹ | 1 | S | Un001 |
| 200111 | | Linear: mm/s | 1 | 5 | |
| E002H | Internal Torque/Thrust Force Reference | % | 1 | S | Un002 |
| E003H | Rotational Angle 1 (Number of Pulses from the Origin) | Pulse | 2 | U | Un003 |
| E005H | Rotational Angle 2 (Angle from the Origin) | deg | 1 | U | Un004 |
| E006H | Input Signal Monitor | - | 1 | - | Un005 |
| E007H | Output Signal Monitor | - | 1 | - | Un006 |
| E008H | Input Reference Pulse Speed | Rotary: min ⁻¹ | 1 | S | Un007 |
| EUUOH | input Reference Pulse Speed | Linear: mm/s | 1 | 3 | Average 64 ms |
| E009H | Position Error Counter | Reference unit | 2 | S | Un008 |
| E00BH | Accumulated Load Rate | %(10s cycle) | 1 | U | Un009 |
| E00CH | Regenerative Load Rate | %(10s cycle) | 1 | U | Un00A |
| E00DH | Dynamic Break Consumption Power | %(10s cycle) | 1 | U | Un00B |
| E00EH | Input Reference Pulse Counter (32bit) | Pulse | 2 | S | Un00C |
| E010H | Feedback Pulse Counter (32bit) | Pulse | 2 | S | Un00D |
| E012H | Fully-closed Feedback Pulse Counter (32bit) | Pulse | 2 | S | Un00E |
| E016H | Total Operation Time | 100ms | 2 | U | Un012 |
| E018H | Upper Limit of Maximum Motor Speed | mm/s | 1 | U | Un010 (Available only in linear motor) |
| E019H | Upper Limit of Divided Pulse Output Setting | Pulse/Pitch | 1 | U | Un010 (Available only in linear motor) |
| E01AH | Magnetic Pole Sensor Information | - | 1 | - | Un011 |
| E01BH | Feedback Pulse Counter | Reference unit | 2 | S | Un013 |
| E01DH | Effective Gain Set Number | - | 1 | U | Un014 |
| E01EH | Safety I/O Signal Monitor | - | 1 | - | Un015 |
| E02CH | Installation Environment monitor | % | 1 | S | Un025 |
| E02DH | Servomotor Installation Environment Monitor | % | 1 | S | Un026 |

| Register No. | Name | Unit | No. of Registers | Sign | Remarks |
|-----------------|--|----------------|---------------------|------|---------|
| E02EH | Main Circuit DC Voltage | V | 1 | S | Un023 |
| E030H | Backlash Compensation Amount | Reference unit | 2 | S | Un030 |
| E032H | Backlash Compensation Setting Upper Limit | Reference unit | 2 | U | Un031 |
| E034H | Power Consumption | [W] | 1 | S | Un032 |
| E035H | Consumed Power | [Wh] | 2 | S | Un033 |
| E037H | Cumulative Power Consumption (integral part) | [Wh] | 2 | S | Un034 |
| E039H | Cumulative Power Consumption (decimal part) | [0.001Wh] | 1 | S | |
| E050H | Built-in Fan Remaining Life Ratio | 0.01% | 1 | U | Un027 |
| E051H | Capacitor Remaining Life Ratio | 0.01% | 1 | U | Un028 |
| E052H | Surge Prevention Circuit Remaining Life Ratio | 0.01% | 1 | U | Un029 |
| E053H | Dynamic Brake Circuit Remaining Life Ratio | 0.01% | 1 | U | Un02A |
| E084H | Linear Scale Pitch | pm | 2 | U | Un084 |
| E086H | Linear Scale Pitch Scaling Exponent | Power of Ten | 1 | S | Un085 |
| E500H | Alarm History Alarm Code No. = 0 | Code | 1 | U | Fn000-0 |
| E501H | Alarm History Alarm Code No. = 1 | Code | 1 | U | Fn000-1 |
| E502H | Alarm History Alarm Code No. = 2 | Code | 1 | U | Fn000-2 |
| E503H | Alarm History Alarm Code No. = 3 | Code | 1 | U | Fn000-3 |
| E504H | Alarm History Alarm Code No. = 4 | Code | 1 | U | Fn000-4 |
| E505H | Alarm History Alarm Code No. = 5 | Code | 1 | U | Fn000-5 |
| E506H | Alarm History Alarm Code No. = 6 | Code | 1 | U | Fn000-6 |
| E507H | Alarm History Alarm Code No. = 7 | Code | 1 | U | Fn000-7 |
| E508H | Alarm History Alarm Code No. = 8 | Code | 1 | U | Fn000-8 |
| E509H | Alarm History Alarm Code No. = 9 | Code | 1 | U | Fn000-9 |
| E50AH | Current Alarm Information | Code | 1 | U | |
| E51BH | Servo Running Status | - | 1 | U | |
| E51CH | Control Mode Status | - | 1 | U | |
| E52AH | Alarm History Time Stamp No. = 0 | 100ms | 2 | U | |
| E52CH | Alarm History Time Stamp No. = 1 | 100ms | 2 | U | |
| E52EH | Alarm History Time Stamp No. = 2 | 100ms | 2 | U | |
| E530H | Alarm History Time Stamp No. = 3 | 100ms | 2 | U | |
| E532H | Alarm History Time Stamp No. = 4 | 100ms | 2 | U | |
| E534H | Alarm History Time Stamp No. = 5 | 100ms | 2 | U | |

| Register No. | Name | Unit | No. of Registers | Sign | Remarks |
|-----------------|--|-------------------------|---------------------|------|---------|
| E536H | Alarm History Time Stamp No. = 6 | 100ms | 2 | U | |
| E538H | Alarm History Time Stamp No. = 7 | 100ms | 2 | U | |
| E53AH | Alarm History Time Stamp No. = 8 | 100ms | 2 | U | |
| E53CH | Alarm History Time Stamp No. = 9 | 100ms | 2 | U | |
| E53EH | Alarm History Counter 0 | - | 1 | U | |
| E53FH | Alarm History Counter 1 | - | 1 | U | |
| E540H | Alarm History Counter 2 | - | 1 | U | |
| E541H | Alarm History Counter 3 | - | 1 | U | |
| E542H | Alarm History Counter 4 | - | 1 | U | |
| E543H | Alarm History Counter 5 | - | 1 | U | |
| E544H | Alarm History Counter 6 | - | 1 | U | |
| E545H | Alarm History Counter 7 | - | 1 | U | |
| E546H | Alarm History Counter 8 | - | 1 | U | |
| E547H | Alarm History Counter 9 | - | 1 | U | |
| E548H | Alarm Trace Data Address 0 | - | 2 | U | |
| E54AH | Alarm Trace Data Address 1 | - | 2 | U | |
| E54CH | Alarm Trace Data Address 2 | - | 2 | U | |
| E54EH | Alarm Trace Data Address 3 | - | 2 | U | |
| E550H | Alarm Trace Data Address 4 | - | 2 | U | |
| E552H | Alarm Trace Data Address 5 | - | 2 | U | |
| E554H | Alarm Trace Data Address 6 | - | 2 | U | |
| E556H | Alarm Trace Data Address 7 | - | 2 | U | |
| EC00H | Feedback position (APOS) | Reference unit | 2 | S | |
| EC02H | Current FFE(CPOS) | Reference unit | 2 | S | |
| EC04H | Position deviation (PERR) | Reference unit | 2 | S | |
| EC06H | Target position in the reference coordinate system (TPOS) | Reference unit | 2 | S | |
| EC08H | Feedback latch position in the machine coordinate system1(LPOS1) | Reference unit | 2 | S | |
| EC0AH | Feedback latch position in the machine coordinate system2(LPOS2) | Reference unit | 2 | S | |
| EC0CH | Feedback latch position in the machine coordinate system3(LPOS3) | Reference unit | 2 | S | |
| EC0EH | Target Speed (TSPD) | Speed Reference unit | 2 | S | |
| EC10H | Feedback Speed (FSPD) | Speed Reference unit | 2 | S | |

| Register No. | Name | Unit | No. of Registers | Sign | Remarks |
|-----------------|---|--------------------------|---------------------|------|-----------------------------|
| EC12H | Reference Speed (CSPD) | Speed Reference unit | 2 | S | |
| EC14H | Torque Limit(TRQ_LIM) | Torque Reference unit | 2 | U | |
| EC16H | Speed Limit(SPD_LIM) | Speed Reference unit | 2 | U | |
| EC18H | M-III Current Communications Phase | - | 1 | U | M-III only |
| EC19H | M-III Current Operating Command Code (RCMD) | - | 1 | U | M-III only (hexadecimal) |
| EC1AH | M-III Current Operating Subcommand Code (SUB_RCMD) | - | 1 | U | M-III only (hexadecimal) |

- Input Signal Monitor (E006H)
 - Σ -7S series

| Bit | Status Signal | Logic | Un No. |
|---------|---------------|---------------------------------|--------|
| 0 | SI0 | 0 = Lo (Close) 1 = Hi (Open) | |
| 1 | SI1 | 0 = Lo (Close) 1 = Hi (Open) | |
| 2 | SI2 | 0 = Lo (Close) 1 = Hi (Open) | |
| 3 | SI3 | 0 = Lo (Close) 1 = Hi (Open) | Un005 |
| 4 | SI4 | 0 = Lo (Close) 1 = Hi (Open) | |
| 5 | SI5 | 0 = Lo (Close) 1 = Hi (Open) | |
| 6 | SI6 | 0 = Lo (Close) 1 = Hi (Open) | |
| 8 to 15 | Reserved | | |

 $\Sigma\text{-}7W/\Sigma\text{-}7C$ series

| Bit | Status Signal | Logic | Un No. |
|----------|---------------|---------------------------------|--------|
| 0 | SIO | 0 = Lo (Close) 1 = Hi (Open) | |
| 1 | SI1 | 0 = Lo (Close) 1 = Hi (Open) | |
| 2 | SI2 | 0 = Lo (Close) 1 = Hi (Open) | |
| 3 | SI3 | 0 = Lo (Close) 1 = Hi (Open) | |
| 4 | SI4 | 0 = Lo (Close) 1 = Hi (Open) | |
| 5 | SI5 | 0 = Lo (Close) 1 = Hi (Open) | |
| 6 | SI6 | 0 = Lo (Close) 1 = Hi (Open) | Un005 |
| 7 | SI7 | 0 = Lo (Close) 1 = Hi (Open) | |
| 8 | SI8 | 0 = Lo (Close) 1 = Hi (Open) | |
| 9 | SI9 | 0 = Lo (Close) 1 = Hi (Open) | |
| 10 | SI10 | 0 = Lo (Close) 1 = Hi (Open) | |
| 11 | SI11 | 0 = Lo (Close) 1 = Hi (Open) | |
| 12 to 15 | Reserved | | |

• Output Signal Monitor (E007H)

 Σ -7S series

| Bit | Status Signal | Logic | Un No. |
|---------|---------------|---------------------------------|--------|
| 0 | ALM | 0 = Lo (Close) 1 = Hi (Open) | |
| 1 | SO1 | 0 = Lo (Close) 1 = Hi (Open) | |
| 2 | SO2 | 0 = Lo (Close) 1 = Hi (Open) | Un006 |
| 3 | SO3 | 0 = Lo (Close) 1 = Hi (Open) | |
| 7 to 15 | Reserved | | |

 $\Sigma\text{-}7W/\Sigma\text{-}7C$ series

| Bit | Status Signal | Logic | Un No. |
|---------|---------------|---------------------------------|--------|
| 0 | ALM | 0 = Lo (Close) 1 = Hi (Open) | |
| 1 | SO1 | 0 = Lo (Close) 1 = Hi (Open) | |
| 2 | SO2 | 0 = Lo (Close) 1 = Hi (Open) | |
| 3 | SO3 | 0 = Lo (Close) 1 = Hi (Open) | Un006 |
| 4 | SO4 | 0 = Lo (Close) 1 = Hi (Open) | |
| 5 | SO5 | 0 = Lo (Close) 1 = Hi (Open) | |
| 6 | SO6 | 0 = Lo (Close) 1 = Hi (Open) | |
| 7 to 15 | Reserved | | |

• Safety I/O Signal Monitor (E01EH)

| Bit | Status Signal | Logic | Un No. |
|---------|---------------|---------------------------------|--------|
| 0 | /HWBB1 | 0 = Lo (Close) 1 = Hi (Open) | |
| 1 | /HWBB2 | 0 = Lo (Close) 1 = Hi (Open) | Un015 |
| 2 to 15 | Reserved | | |

NOTE

• /HWBB1 and /HWBB2 are valid only when the safety option card is not connected. When the safety option card is connected, they become indefinite.

• Servo Running Status (E51BH)

| Reading | Description |
|---------|--|
| 0000H | Reserved (Initial State) |
| 0001H | Alarm Occurred (A.***) |
| 0002H | Hardwired Base Blocked (HWBB) |
| 0003H | Forward / Reverse Run Prohibited (PTNT) |
| 0004H | Forward Run Prohibited (P-OT) |
| 0005H | Reverse Run Prohibited (N-OT) |
| 0006H | Base Blocked (BB) |
| 0007H | Base Enabled (RUN) |
| 0008H | Magnetic Pole Detecting (PDET) |
| 0009H | Active Mode ON(ACT) |
| 000AH | Force Stop ON(FSTP) |
| 0103H | Safety Function Monitor ON & Forward / Reverse Run Prohibited (PTNT) |
| 0104H | Safety Function Monitor ON & Forward Run Prohibited (P-OT) |
| 0105H | Safety Function Monitor ON & Reverse Run Prohibited (N-OT) |
| 0106H | Safety Function Monitor ON & Base Blocked (BB) |
| 0107H | Safety Function Monitor ON & Base Enabled (RUN) |
| 0108H | Safety Function Monitor ON & Magnetic Pole Detecting (PDET) |
| 0109H | Safety Function Monitor ON & Active Mode ON(ACT) |
| 010AH | Safety Function Monitor ON & Force Stop ON(FSTP) |
| 0203H | Safety Function Safe ON & Forward / Reverse Run Prohibited (PTNT) |
| 0204H | Safety Function Safe ON & Forward Run Prohibited (P-OT) |
| 0205H | Safety Function Safe ON & Reverse Run Prohibited (N-OT) |
| 0206H | Safety Function Safe ON & Base Blocked (BB) |
| 0207H | Safety Function Safe ON & Base Enabled (RUN) |
| 0208H | Safety Function Safe ON & Magnetic Pole Detecting (PDET) |
| 0209H | Safety Function Safe ON & Active Mode ON(ACT) |
| 020AH | Safety Function Safe ON & Force Stop ON(FSTP) |

• Control Mode Status (E51CH)

| Reading | Description |
|---------|-----------------------|
| 0000H | Speed Control Mode |
| 0001H | Position Control Mode |
| 0002H | Torque Control Mode |

NOTE

• JOG Drive Mode, Origin Search Mode, and Internally Set Speed Control Mode become Speed control mode.

• Programmed JOG Drive Mode, Advanced Auto-Tuning Mode, and Easy FFT Mode become Position Control Mode.

5.6 I/O(M-System) R7G4HML3-LC2(M-III) Series

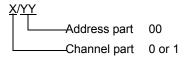
This address can be specified as system data area.

| Device | Bit Address | Word Address | 32 bits | Notes |
|------------------------|-------------------|-----------------|--------------|-----------------------------|
| Auto-Zero | - | AZ0/00~AZ1/00 | | *1 *2 |
| Zero point adjust | - | ZPA0/00~ZPA1/00 |] ⊺L / H) | *1 *2 |
| Span point adjustment | - | SPA0/00~SPA1/00 | | *1 *2 |
| Average cycle | AC0/00.0~AC1/00.F | AC0/00~AC1/00 | | B i t F *2 *3 |
| Monitor Output | - | MO0/00~MO1/00 | | *1 *2 |
| Monitor Output Release | - | MOR0/00~MOR1/00 | | *1 *2 |
| Offset Reset | - | OR0/00~OR1/00 | | *1 *2 |
| Virtual Memory Space | - | M0/0000-M0/019C | - | *4 *5 |
| CR Filter Set | CR0/00.0 | CR0/00 | | B i t F *3 |
| Voltage Set | V0/00.0 | V0/00 | | B i t F *3 |

*1 Read disable

E

^{*2} When a value is written, the corresponding processing is run. The address consists of the address part and the channel part.



- *3 When you write to the bit address, the Display reads the entire word, sets the defined bit, then returns the new word value to the External Device. If the ladder program writes data to this word address during the bit write process, the resulting data may be incorrect.
- *4 Write disable
- *5 32-bit device

NOTE

- You can only set the Read Area Size for the system area available to use in the External Device. Please refer to the GP-Pro EX Reference Manual for Read Area Size.
- Please refer to the GP-Pro EX Reference Manual for system data area.
 - Cf. GP-Pro EX Reference Manual "LS Area (Direct Access Method Area)"
- Please refer to the precautions on manual notation for icons in the table.

5.7 I/O(M-System) R7G4HML3-STYVS1(M-III) Series

This address can be specified as system data area.

| Device | Bit Address | Word Address | 32 bits | Notes |
|----------------------|---------------|--------------|------------|----------|
| Angle Offset | - | AAZ00~AAZ00 | | *1 *2 |
| Angle Offset Read | - | AOR00-AOR00 | | *3 |
| Angle Span Setting | - | ARS00~ARS00 | | |
| Virtual Memory Space | - | M0000-M019C | L/H) | *3 *4 |
| Linearization Count | LC00.0~LC00.F | LC00~LC00 | | *5 |
| Linearization | L00.0~L63.F | L00~L63 | | *5 *6 *7 |
| Output Bias | OB00.0~OB00.F | OB00~OB00 | Ĭ | *5 |
| Output Gain | OG00.0~OG00.F | OG00~OG00 | | *5 |

*1 Read disable

- *2 The process runs when a value is written.
- *3 Write disable
- *4 32-bit device
- *5 When you write to the bit address, the Display reads the entire word, sets the defined bit, then returns the new word value to the External Device. If the ladder program writes data to this word address during the bit write process, the resulting data may be incorrect.
- *6 The Display can access a maximum 32 linearization devices. The device addresses corresponding to linearization devices are as follows.

| Device Address | Linearization Device | Description |
|----------------|----------------------|--------------|
| 00 | 1.x | |
| 01 | 1.y | |
| 02 | 2.x | |
| 03 | 2.y | 16-bit value |
| : | : | |
| 62 | 32.x | |
| 63 | 32.y | |

*7 The Linearization Device reads and writes both X and Y as one set. And it always reads and writes from L0. To write to the specified address, the Display reads the corresponding word address range from L0 of the External Device, changes the word address value, then returns it to the External Device.

While the Display is reading and then returning data to the External Device, write processes by the ladder program to the word address could cause the writing of incorrect data.

Example:

Write to L30(16.X), read L0(1.X) to L31(16.Y). Then, change the value of L30 only and return to the External Device.

NOTE

- You can only set the Read Area Size for the system area available to use in the External Device. Please refer to the GP-Pro EX Reference Manual for Read Area Size.
- Please refer to the GP-Pro EX Reference Manual for system data area.
 - Cf. GP-Pro EX Reference Manual "LS Area (Direct Access Method Area)"
- Please refer to the precautions on manual notation for icons in the table.
 - "Manual Symbols and Terminology"

5.8 I/O(M-System) R7G4HML3-LC2A(M-III) Series

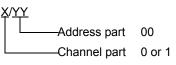
This address can be specified as system data area.

| Device | Bit Address | Word Address | 32 bits | Notes |
|------------------------|-------------------|-----------------|------------|-----------------------------|
| Auto-Zero | - | AZ0/00~AZ1/00 | | *1 *2 |
| Zero point adjust | - | ZPA0/00~ZPA1/00 | | *1 *2 |
| Span point adjustment | - | SPA0/00~SPA1/00 | | *1 *2 |
| Average cycle | AC0/00.0~AC1/00.F | AC0/00~AC1/00 | | E i t F *2 *3 |
| Monitor Output | - | MO0/00~MO1/00 | [L/H] | *1 *2 |
| Monitor Output Release | - | MOR0/00~MOR1/00 | | *1 *2 |
| Offset Reset | - | OR0/00~OR1/00 | | *1 *2 |
| Virtual Memory Space | - | M0/0000-M0/019C | | *4 *5 |
| CR Filter Set | CR0/00.0 | CR0/00 | | E i t F *3 |

*1 Read disable

Г

*2 When a value is written, the corresponding processing is run. The address consists of the address part and the channel part.



- *3 When you write to the bit address, the Display reads the entire word, sets the defined bit, then returns the new word value to the External Device. If the ladder program writes data to this word address during the bit write process, the resulting data may be incorrect.
- *4 Write disable
- *5 32-bit device

NOTE

- You can only set the Read Area Size for the system area available to use in the External Device. Please refer to the GP-Pro EX Reference Manual for Read Area Size.
- Please refer to the GP-Pro EX Reference Manual for system data area.
 Cf. GP-Pro EX Reference Manual "LS Area (Direct Access Method Area)"
- Please refer to the precautions on manual notation for icons in the table.

5.9 I/O(Azbil) K1G Series

Γ

This address can be specified as system data area.

| Device | Bit Address | Word Address | 32 bits | Notes |
|--------|--|----------------------------|------------|-------|
| Data | 04096,00~36863,15 61440,00~65535,15 | 04096~36863 61440~65535 | [L/H] | *1 *2 |

- *1 When bits are written, the Display reads the corresponding word address from the External Device, sets particular bits of that word address to ON, and then returns the resulting address to the External Device. Note that the data may not be written correctly if you write to the word address using the External Device while the Display is reading data from, and writing data to, the External Device.
- *2 The Display uses the generic Modbus address format. Please refer to the following table for supported K1G series address types and address ranges.

| K1G S | Display | |
|-----------------------|----------------|----------------|
| Address Types | Address Ranges | Address Ranges |
| Monitoring area | 0x1000~0x1FFF | 04096~08191 |
| Setting area | 0x2000~0x2FFF | 08192~12287 |
| Channel1 area | 0x3000~0x3FFF | 12288~16383 |
| Channel2 area | 0x4000~0x4FFF | 16384~20479 |
| Channel3 area | 0x5000~0x5FFF | 20480~24575 |
| Channel4 area | 0x6000~0x6FFF | 24576~28671 |
| Intensity area | 0x7000~0x7FFF | 28672~32767 |
| Operation area | 0x8000~0x8FFF | 32768~36863 |
| Special Function area | 0xF000~0xFFFF | 61440~65535 |

The External Device has 32 bit addresses. Read to or write from these 32 bit addresses in 32 bit units. For information about address length, please refer to the corresponding External Device manual.

NOTE

• You can only set the Read Area Size for the system area available to use in the External Device. Please refer to the GP-Pro EX Reference Manual for Read Area Size.

- Please refer to the GP-Pro EX Reference Manual for system data area.
- Cf. GP-Pro EX Reference Manual "LS Area (Direct Access Method Area)"Please refer to the precautions on manual notation for icons in the table.

5.10 Stepping (ORIENTAL MOTOR) AZ Series

This address can be specified as system data area.

| Device | Bit Address | Word Address | 32 bits | Notes |
|---------------|--|----------------------------|------------|-------|
| Parameter No. | 0000.00 - 008F.31 1020.00 - 1978.31 | 0000 - 008F 1020 - 1978 | - | *1 *2 |

- *1 When bits are written, the Display reads the corresponding word address from the External Device, sets particular bits of that word address to ON, and then returns the resulting address to the External Device. Note that the data may not be written correctly if you write to the word address using the External Device while the Display is reading data from, and writing data to, the External Device.
- *2 32-bit device

NOTE

E

| • You can only set the Read Area Size for the system area available to use in the External |
|--|
| Device. Please refer to the GP-Pro EX Reference Manual for Read Area Size. |

- Please refer to the GP-Pro EX Reference Manual for system data area.
- Cf. GP-Pro EX Reference Manual "LS Area (Direct Access Method Area)"
- Please refer to the precautions on manual notation for icons in the table.

6 Device Code and Address Code

Use device code and address code when you select "Device Type & Address" for the address type in data displays.

6.1 MP2000 Series / MPU-01

| Device | Device Name | Device Code (HEX) | Address Code |
|------------------|-------------|----------------------|--------------|
| System registers | SW/SB | 0080 | Word address |
| Input registers | IW/IB | 0001 | Word address |
| Output registers | OW/OB | 0081 | Word address |
| Data registers | MW/MB | 0000 | Word address |

6.2 MP3000 Series / Sub CPU

| Device | Device Name | Device Code (HEX) | Address Code |
|------------------|-------------|----------------------|--------------|
| System registers | SW/SB | 0080 | Word address |
| Input registers | IW/IB | 0001 | Word address |
| Output registers | OW/OB | 0081 | Word address |
| Data registers | MW/MB | 0000 | Word address |
| G registers | GW/GB | 0002 | Word address |

6.3 Inverter Series

| Device | Device Name | Device Code (HEX) | Address Code |
|---------------|-------------|----------------------|--------------|
| Bit registers | BR | 0080 | Address |
| Registers | - | 0000 | Address |

6.4 Servo Series

| Device | Device Name | Device Code (HEX) | Address Code |
|------------------------------|-------------|----------------------|--------------|
| Normal Parameters Area | 0 | 0000 | Word address |
| Temporary Parameters Area | 1 | 0001 | Word address |
| Monitor Area | Е | 0009 | Word address |

6.5 I/O(M-System) R7G4HML3-LC2(M-III) Series

| Device | Device Name | Device Code (HEX) | Address Code |
|------------------------|-------------|----------------------|---|
| Auto-Zero | AZ | 0001 | $\begin{array}{l} \text{Channel number} \times \\ 0x10000 + \\ \text{Word address value} \end{array}$ |
| Zero point adjust | ZPA | 0002 | $\begin{array}{l} \text{Channel number} \times \\ 0x10000 + \\ \text{Word address value} \end{array}$ |
| Span point adjustment | SPA | 0003 | $\begin{array}{l} \text{Channel number} \times \\ 0x10000 + \\ \text{Word address value} \end{array}$ |
| Average cycle | AC | 0000 | $\begin{array}{l} \text{Channel number} \times \\ 0x10000 + \\ \text{Word address value} \end{array}$ |
| Monitor Output | МО | 0004 | $\begin{array}{l} \text{Channel number} \times \\ 0x10000 + \\ \text{Word address value} \end{array}$ |
| Monitor Output Release | MOR | 0005 | Channel number × 0x10000 + Word address value |
| Offset Reset | OR | 0006 | $\begin{array}{l} \text{Channel number} \times \\ 0x10000 + \\ \text{Word address value} \end{array}$ |
| Virtual Memory Space | М | 0009 | Word address |
| CR Filter Set | CR | 0007 | Word address |
| Voltage Set | V | 0008 | Word address |

6.6 I/O(M-System) R7G4HML3-STYVS1(M-III) Series

| Device | Device Name | Device Code (HEX) | Address Code |
|----------------------|-------------|----------------------|--------------|
| Angle Offset | AAZ | 0001 | Word address |
| Angle Span Setting | ARS | 0002 | Word address |
| Virtual Memory Space | М | 0009 | Word address |
| Linearization Count | LC | 0000 | Word address |
| Linearization | L | 000A | Word address |
| Output Bias | OB | 000C | Word address |
| Output Gain | OG | 000D | Word address |

6.7 I/O(M-System) R7G4HML3-LC2A(M-III) Series

| Device | Device Name | Device Code (HEX) | Address Code |
|------------------------|-------------|----------------------|---|
| Auto-Zero | AZ | 0001 | Channel number × 0x10000 + Word address value |
| Zero point adjust | ZPA | 0002 | $\begin{array}{l} \text{Channel number} \times \\ 0x10000 + \\ \text{Word address value} \end{array}$ |
| Span point adjustment | SPA | 0003 | $\begin{array}{l} \text{Channel number} \times \\ 0x10000 + \\ \text{Word address value} \end{array}$ |
| Average cycle | AC | 0000 | $\begin{array}{l} \text{Channel number} \times \\ 0x10000 + \\ \text{Word address value} \end{array}$ |
| Monitor Output | МО | 0004 | $\begin{array}{l} \text{Channel number} \times \\ 0x10000 + \\ \text{Word address value} \end{array}$ |
| Monitor Output Release | MOR | 0005 | $\begin{array}{l} \text{Channel number} \times \\ 0x10000 + \\ \text{Word address value} \end{array}$ |
| Offset Reset | OR | 0006 | Channel number × 0x10000 + Word address value |
| Virtual Memory Space | М | 0009 | Word address |
| CR Filter Set | CR | 0007 | Word address |

6.8 I/O(Azbil) K1G Series

| Device | Device Name | Device Code (HEX) | Address Code |
|--------|-------------|----------------------|--------------|
| Data | - | 0000 | Word address |

6.9 Stepping (ORIENTAL MOTOR) AZ Series

| Device | Device Name | Device Code (HEX) | Address Code |
|---------------|-------------|----------------------|--------------|
| Parameter No. | - | 0000 | Word address |

7 Error Messages

Error messages are displayed on the screen of Display as follows: "No. : Device Name: Error Message (Error Occurrence Area)". Each description is shown below.

| Item | Description |
|-----------------------|---|
| No. | Error No. |
| Device Name | Name of External Device where error occurs. Device name is a title of External Device set with GP-Pro EX.((Initial value [PLC1]) |
| Error Message | Displays messages related to the error which occurs. |
| | Displays IP address or device address of External Device where error occurs, or error codes received from External Device. |
| Error Occurrence Area | NOTE IP address is displayed such as "IP address (Decimal): MAC address (Hex)". Device address is displayed such as "Address: Device address". Received error codes are displayed such as "Decimal [Hex]". |

Display Examples of Error Messages "RHAA035: PLC1: Error has been responded for device write command (Error Code: 2 [02H])"

| NOTE | • | Please refer to the manual of External Device for more detail of received error codes. |
|------|---|--|
| | • | Please refer to "Display-related errors" of "Maintenance/Troubleshooting Guide" for a |
| | | common error message to the driver. |

7.1 MP Series

Error Codes Unique to External Device

| Error code | Description |
|------------|--------------------|
| 0x90 | Transfer error. |
| 0x92 | Illegal parameter. |
| 0x96 | Register No. over. |
| 0x9C | File is modified. |
| 0x9D | Data access error. |

Error Messages Unique to External Device

| Message ID | Error Message | Description |
|------------|---|--------------------------|
| RHxx128 | "(Node Name):PLC is busy now(Error Code: [Hex])" | PLC is "Busy" |
| RHxx129 | "(Node Name):Option module is not mounted(Error Code: [Hex])" | Option module not mount. |
| RHxx130 | "(Node Name):Module is not ready(Error Code: [Hex])" | Module is not ready |
| RHxx131 | "(Node Name):CPU is stopped(Error Code: [Hex])" | CPU is stopped |
| RHxx132 | "(Node Name): Write protected(Error Code: [Hex])" | Write protected |

7.2 Inverter Series

Error Codes Unique to External Device

| Error code | Description |
|------------|---|
| 0x01 | Function code error |
| 0x02 | Invalid register number error |
| 0x03 | Invalid quantity error |
| 0x21 | Date setting error |
| 0x22 | Write mode error |
| 0x23 | Main circuit undervoltage (UV) error during write |
| 0x24 | Write error during processing of constants |

7.3 Servo Series

Error Codes Unique to External Device

| Error code | Description |
|------------|--|
| 0x01 | Function Code ErrorUnsupported function code or sub function code. |
| 0x02 | Faulty Register NumberAccessing register number that is not registered. |
| 0x03 | Faulty Quantity The number of read or write data for reading is not between one and the maximum quantity (as defined per model). In write mode, the number of data in the message is not the specified quantity. |
| 0x30 | Faulty Register Number (High Level)Accessing register number that is not registered. |
| 0x31 | Access Limit Error • Access to the specified register is not permitted. |
| 0x32 | Outside Setting Range Error • The write data value is outside the maximum and minimum limit. |
| 0x33 | Data Matching Error Tried to access only a portion of registers in the multiple register unit. Tried to access multiple registers that exceed the register group. |
| 0x34 | Condition Error Command message content cannot be processed due to the condition defined by the register. |
| 0x35 | Process Conflict ErrorCannot be processed due to priority issues with other channels. |
| 0x36 | Axis number error (Σ-7W/Σ-7C series only) The extended address is using an axis number that is not available. |

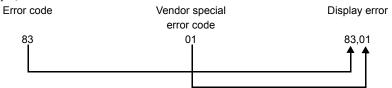
7.4 I/O(M-System)

Error Codes Unique to External Device

| Error code | Description |
|------------|---|
| 0x01 | Function Code ErrorUnsupported function code or sub function code in use. |
| 0x03 | Faulty Quantity The data count in read or write operations is outside the allowed range (1 to the maximum, as defined per model). In write mode, the data count in the message does not match the specified quantity. |
| 0x04 | Data Type ErrorNot supported by the defined mode or data type. |
| 0x09 | Process Conflict ErrorCannot process due to priority issues with other channels. |
| 0x81 | Protocol ID Setting Error When running a vendor specific command, the protocol ID did not match the External Device. |
| 0x82 | Data Length Setting Error When running a vendor specific command, the data length setting for the vendor special area does not match the External Device. |
| 0x83 | Vendor Special Area Error When running a vendor specific command, a vendor special error occurred in the vendor special area. |

• If the error code is 0x83, it is displayed together with the vendor special error code.

Example)



Vendor special error code

| Error code | Description |
|------------|---|
| 0x01 | Model code errorThe specified model code does not match the External Device. |
| 0x02 | Specified channel errorExternal Device does not support the specified channel. |
| 0x03 | Setting command errorExternal Device does not support the setting command. |
| 0x04 | Setting command data error • Error in the setting command data. |

Error Messages Unique to External Device

| Message ID | Error Message | Description |
|------------|---|--|
| RHxx134 | (Node Name): Error has been responded for device read command (Error Code: [Hex,Hex]) | The error message is displayed when the error has occurred in the read command. |
| RHxx135 | (Node Name): Error has been responded for device write command (Error Code: [Hex,Hex]) | The error message is displayed when the error has occurred in the write command. |

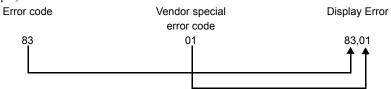
7.5 I/O(Azbil) K1G Series

Error Codes Unique to External Device

| Error code | Description |
|------------|--|
| 0x01 | Function Code ErrorUnsupported function code or sub function code in use. |
| 0x02 | Memory Address ErrorMemory address you tried to access is not in the memory address range. |
| 0x03 | Faulty QuantityThe data count in read or write operations is outside the allowed range (1 to the maximum, as defined per model). |
| 0x04 | Data Type ErrorNot supported by the defined mode or data type.Not supported by the protocol ID or device code. |
| 0x81 | Protocol ID Setting Error When running a vendor specific command, the protocol ID did not match the External Device. |
| 0x82 | Data Length Setting Error When running a vendor specific command, the data length setting for the vendor special area does not match the External Device. |
| 0x83 | Vendors Special Area Error When running a vendor specific command, a vendor special error occurred in the vendor special area. |

• If the error code is 0x83, and the vendor special error code is 0x01, it is displayed as follows.

Example)

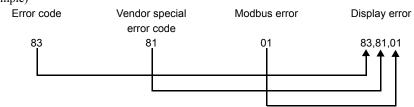


Vendor special error code

| Error code | Description | |
|------------|--|--|
| 0x01 | Azbil protocol ID setting errorThe specified Azbil protocol ID is not supported by the External Device. | |

• If the error code is 0x83, and the vendor special error code is 0x81, it is displayed together with the Modbus error.

Example)



Vendor special error code

| Error code | Description | |
|------------|---|--|
| 0x81 | MODBUS RTU abnormal response • Received a Modbus error. For more information, check the Modbus error code table. | |

Modbus error code

| Error code | Description |
|------------|---|
| 0x01 | Illegal function Unsupported function code Connected to unsupported External Device |
| 0x02 | Illegal data address • Data address error (area where access is prohibited) |
| 0x03 | Illegal data Write out-of-range value Equipment related, write-protected and read prohibited |
| 0x13 | Write mode error |

■ Error Messages Unique to External Device

| Message ID | Error Message | Description |
|------------|---|--|
| RHxx134 | (Node Name): Error has been responded for device read command (Error Code: [Hex,Hex]) | The error message is displayed when the error has occurred in the read command. |
| RHxx135 | (Node Name): Error has been responded for device write command (Error Code: [Hex,Hex]) | The error message is displayed when the error has occurred in the write command. |
| RHxx136 | (Node Name): Error has been responded for device read command (Error Code: [Hex,Hex, Hex]) | The error message is displayed when the error has occurred in the read command. |
| RHxx137 | (Node Name): Error has been responded for device write command (Error Code: [Hex,Hex, Hex]) | The error message is displayed when the error has occurred in the write command. |
| RHxx138 | (Node Name): Error has been responded for device read command (Error Code: (Decimal)[(Hex)] There are out of range devises) | The error message is displayed when the error has occurred in the read command. |

| Message ID | Error Message | Description |
|------------|--|--|
| RHxx139 | (Node Name): Error has been responded for device write command (Error Code: (Decimal)[(Hex)] There are out of range devises) | The error message is displayed when the error has occurred in the write command. |

7.6 Stepping (ORIENTAL MOTOR) AZ Series

Error Codes Unique to External Device

| Error code | Description |
|------------|--|
| 0x01 | Function Code ErrorUnsupported function code or sub function code in use. |
| 0x02 | Faulty Register NumberAccessing register number that is not registered. |
| 0x03 | Faulty Quantity The number of read or write data for reading is not between one and the maximum quantity (as defined per model). In write mode, the number of data in the message is not the specified quantity. |
| 0x04 | Data Type Error • Not supported by the defined mode or data type. |
| 0x05 | Access Limit Error • Access to the specified register is not permitted. |
| 0x06 | Outside Setting Range Error • The write data value is outside the maximum and minimum limit. |
| 0x07 | Data Matching Error Tried to access only a portion of memory in the multiple register unit. Tried to access multiple registers that exceed the register group. |
| 0x08 | Condition Error Command message content cannot be processed due to the condition defined by the register. |
| 0x09 | Process Conflict ErrorCannot be processed due to priority issues with other channels. |